



## FEATURES

- Frequency Range: 30MHz to 1300MHz
- Low Power: 2.7V to 3.6V Supply; 28mA
- Low LO Carrier Leakage:  $-51.5\text{dBm}$  at 500MHz
- Side-Band Suppression:  $-52.6\text{dBc}$  at 500MHz
- Output IP3:  $20.8\text{dBm}$  at 500MHz
- Low RF Output Noise Floor:  $-156\text{dBm/Hz}$  at 6MHz Offset,  $P_{\text{RF}} = 3\text{dBm}$
- Sine Wave or Square Wave LO Drive
- SPI Control:
  - Adjustable Gain:  $-19\text{dB}$  to  $0\text{dB}$  in  $1\text{dB}$  Steps
  - Effecting Supply Current from  $8\text{mA}$  to  $35\text{mA}$
  - I/Q Offset Adjust:  $-65\text{dBm}$  LO Carrier Leakage
  - I/Q Gain/Phase Adjust:  $-60\text{dBc}$  Side-Band Suppressed
- 24-Lead QFN 4mm × 4mm Package

## APPLICATIONS

- Wireless Microphones
- Battery Powered Radios
- Ad-Hoc Wireless Infrastructure Networks
- “White-Space” Transmitters
- Software Defined Radios (SDR)
- Military Radios

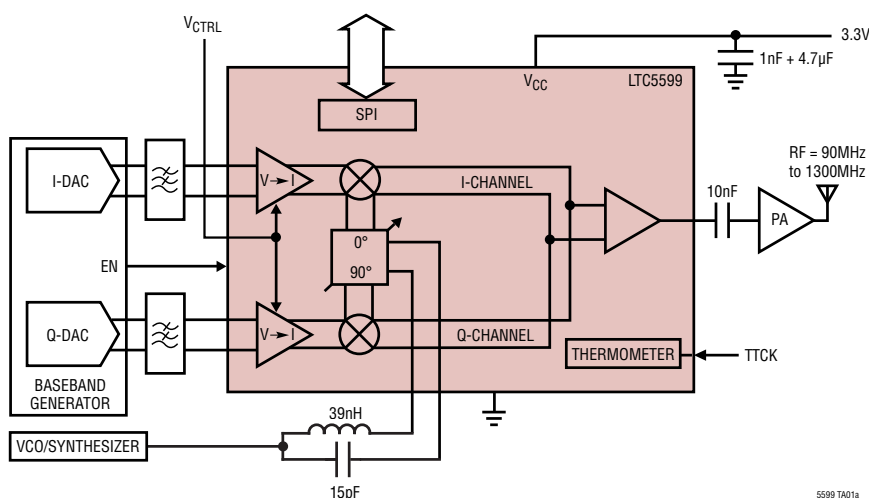
## DESCRIPTION

The **LTC<sup>®</sup>5599** is a direct conversion I/Q modulator designed for low power wireless applications that enable direct modulation of differential baseband I and Q signals on an RF carrier. Single side-band modulation or side-band suppressed upconversion can be achieved by applying  $90^\circ$  phase-shifted signals to the I and Q inputs. The I/Q baseband input ports can be either AC or DC coupled to a source with a common mode voltage level of about  $1.4\text{V}$ . The SPI interface controls the supply current, modulator gain, and allows optimization of the LO carrier feedthrough and side-band suppression, with sine wave or square wave LO drive. A fixed LC network on the LO and RF ports covers a continuous  $90\text{MHz}$  to  $1300\text{MHz}$  operation. An on-chip thermometer can be activated to compensate for gain-temperature variations. More accurate temperature measurements can be made using an on-chip diode. In addition, a continuous analog gain control ( $V_{\text{CTRL}}$ ) pin can be used for fast power control.

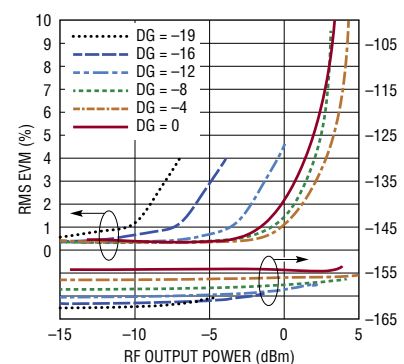
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## TYPICAL APPLICATION

90MHz to 1300MHz Direct Conversion Transmitter Application



EVM and Noise Floor vs RF Output Power and Digital Gain Setting with 1Ms/s 16-QAM Signal

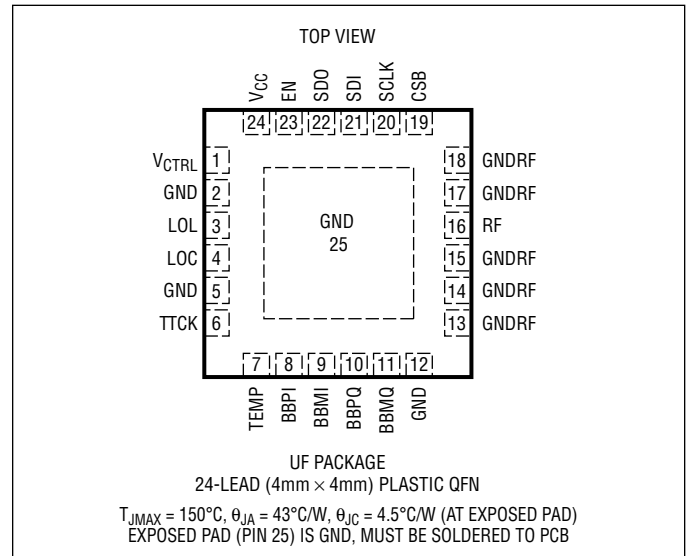


## ABSOLUTE MAXIMUM RATINGS

(Note 1)

Supply Voltage .....	3.8V
Common Mode Level of BBPI, BBMI, and BBPQ, BBMQ .....	2V
LOL, LOC DC Voltage .....	±0.1V
LOL, LOC Input Power (Note 15) .....	20dBm
Current Sink of TEMP, SDO .....	10mA
Voltage on Any Pin (Note 16) .....	-0.3V to $V_{CC} + 0.3V$
$T_{JMAX}$ .....	150°C
Case Operating Temperature Range .....	-40°C to 105°C
Storage Temperature Range .....	-65°C to 150°C

## PIN CONFIGURATION



## ORDER INFORMATION

LEAD FREE FINISH	TAPE AND REEL	PART MARKING	PACKAGE DESCRIPTION	CASE TEMPERATURE RANGE
LTC5599IUF#PBF	LTC5599IUF#TRPBF	5599	24-Lead (4mm × 4mm) Plastic QFN	-40°C to 105°C

Consult LTC Marketing for parts specified with wider operating temperature ranges.

Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandree/>

Please refer to: <http://www.linear.com/designtools/packaging/> for the most recent package drawings.

**ELECTRICAL CHARACTERISTICS** The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_C = 25^\circ\text{C}$ .  $V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $P_{LO} = 0\text{dBm}$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q 90° shifted, lower sideband selection, all registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
$f_{LO} = 150\text{MHz}$ , $f_{RF1} = 147.9\text{MHz}$ , $f_{RF2} = 148\text{MHz}$ , Register 0x00 = 0x62						
$S_{22(ON)}$	RF Port Return Loss			-26		dB
$f_{LO(MATCH)}$	LO Match Frequency Range	S11 < -10dB		116 to 272		MHz
Gain	Conversion Voltage Gain	$20 \cdot \text{Log} (V_{RF(OUT)(50\Omega)} / V_{IN(DIFF)(I \text{ or } Q)})$		-7.5		dB
$P_{OUT}$	Absolute Output Power	$1V_{P-P(DIFF)}$ CW Signal, I and Q		-3.5		dBm
OP1dB	Output 1dB Compression			5		dBm
OIP2	Output 2nd Order Intercept	(Note 5)		70.5		dBm
OIP3	Output 3rd Order Intercept	(Note 6)		21.7		dBm
NFloor	RF Output Noise Floor	No Baseband AC Input Signal (Note 3)		-155.3		dBm/Hz
SB	Side-Band Suppression	(Note 7)		-61.4		dBc
LOFT	Carrier Leakage (LO Feedthrough)	(Note 7) EN = Low (Note 7)		-52.8 -84.8		dBm dBm
2LOFT	LO Feedthrough at 2xLO			-59		dBm

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**ELECTRICAL CHARACTERISTICS** The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_C = 25^\circ\text{C}$ .  $V_{CC} = 3.3\text{V}$ ,  $EN = 3.3\text{V}$ ,  $V_{CTRL} = 3.3\text{V}$ ,  $P_{LO} = 0\text{dBm}$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz, 1V<sub>P-P(DIFF, I or Q)</sub>, I and Q 90° shifted, lower sideband selection, all registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
2LO	Signal Powers at 2xLO	Maximum of $2f_{LO} - 2f_{BB}$ ; $2f_{LO} - f_{BB}$ ; $2f_{LO} + f_{BB}$ , $2f_{LO} + 2f_{BB}$		-51		dBc
3LOFT	LO Feedthrough at 3xLO			-57		dBm
3LO	Signal Powers at 3xLO	Maximum of $3f_{LO} - f_{BB}$ ; $3f_{LO} + f_{BB}$		-10.7		dBc
BW1dB <sub>BB</sub>	-1dB Baseband Bandwidth	$R_{SOURCE} = 50\Omega$ , Differential		15		MHz
BW3dB <sub>BB</sub>	-3dB Baseband Bandwidth	$R_{SOURCE} = 50\Omega$ , Differential		28		MHz

**$f_{LO} = 500\text{MHz}$ ,  $f_{RF1} = 497.9\text{MHz}$ ,  $f_{RF2} = 498\text{MHz}$ , Register 0x00 = 0x2D**

$S_{22(ON)}$	RF Port Return Loss			-26		dB
$f_{LO(MATCH)}$	LO Match Frequency Range	$S_{11} < -10\text{dB}$		180 to 1900		MHz
Gain	Conversion Voltage Gain	$20 \cdot \text{Log}(V_{RF(OUT)(50\Omega)}/V_{IN(DIFF)(I \text{ or } Q)})$		-7.7		dB
$P_{OUT}$	Absolute Output Power	1V <sub>P-P(DIFF)</sub> CW Signal, I and Q		-3.7		dBm
OP1dB	Output 1dB Compression			5.0		dBm
OIP2	Output 2nd Order Intercept	(Note 5)		63.6		dBm
OIP3	Output 3rd Order Intercept	(Note 6)		20.8		dBm
NFloor	RF Output Noise Floor	No Baseband AC Input Signal (Note 3) $P_{OUT} = 3\text{dBm}$ (Note 3)		-156.7 -156.0		dBm/Hz dBm/Hz
SB	Side-Band Suppression	(Note 7)		-52.6		dBc
LOFT	Carrier Leakage (LO Feedthrough)	(Note 7) EN = Low (Note 7)		-51.5 -67.5		dBm dBm
2LOFT	LO Feedthrough at 2xLO			-61		dBm
2LO	Signal Powers at 2xLO	Maximum of $2f_{LO} - 2f_{BB}$ ; $2f_{LO} - f_{BB}$ ; $2f_{LO} + f_{BB}$ , $2f_{LO} + 2f_{BB}$		-51		dBc
3LOFT	LO Feedthrough at 3xLO			-62		dBm
3LO	Signal Powers at 3xLO	Maximum of $3f_{LO} - f_{BB}$ ; $3f_{LO} + f_{BB}$		-11.8		dBc
BW1dB <sub>BB</sub>	-1dB Baseband Bandwidth	$R_{SOURCE} = 50\Omega$ , Differential		29		MHz
BW3dB <sub>BB</sub>	-3dB Baseband Bandwidth	$R_{SOURCE} = 50\Omega$ , Differential		57		MHz

**$f_{LO} = 900\text{MHz}$ ,  $f_{RF1} = 897.9\text{MHz}$ ,  $f_{RF2} = 898\text{MHz}$ , Register 0x00 = 0x12**

$S_{22(ON)}$	RF Port Return Loss			-28		dB
$f_{LO(MATCH)}$	LO Match Frequency Range	$S_{11} < -10\text{dB}$		223 to 1902		MHz
Gain	Conversion Voltage Gain	$20 \cdot \text{Log}(V_{RF(OUT)(50\Omega)}/V_{IN(DIFF)(I \text{ or } Q)})$		-8.9		dB
$P_{OUT}$	Absolute Output Power	1V <sub>P-P(DIFF)</sub> CW Signal, I and Q		-4.9		dBm
OP1dB	Output 1dB Compression			4.1		dBm
OIP2	Output 2nd Order Intercept	(Note 5)		63.5		dBm
OIP3	Output 3rd Order Intercept	(Note 6)		18.4		dBm
NFloor	RF Output Noise Floor	No Baseband AC Input Signal (Note 3)		-155.6		dBm/Hz
SB	Side-Band Suppression	(Note 7)		-61.3		dBc
LOFT	Carrier Leakage (LO Feedthrough)	(Note 7) EN = Low (Note 7)		-58.6 -62.3		dBm dBm
2LOFT	LO Feedthrough at 2xLO			-59		dBm
2LO	Signal Powers at 2xLO	Maximum of $2f_{LO} - 2f_{BB}$ ; $2f_{LO} - f_{BB}$ ; $2f_{LO} + f_{BB}$ , $2f_{LO} + 2f_{BB}$		-51		dBc

**ELECTRICAL CHARACTERISTICS** The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_C = 25^\circ\text{C}$ .  $V_{CC} = 3.3\text{V}$ ,  $EN = 3.3\text{V}$ ,  $V_{CTRL} = 3.3\text{V}$ ,  $P_{LO} = 0\text{dBm}$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q 90° shifted, lower sideband selection, all registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
3LOFT	LO Feedthrough at 3xLO			-60		dBm
3LO	Signal Powers at 3xLO	Maximum of $3f_{LO} - f_{BB}$ ; $3f_{LO} + f_{BB}$		-19.2		dBc
BW1dB <sub>BB</sub>	-1dB Baseband Bandwidth	$R_{SOURCE} = 50\Omega$ , Differential		37		MHz
BW3dB <sub>BB</sub>	-3dB Baseband Bandwidth	$R_{SOURCE} = 50\Omega$ , Differential		69		MHz

**Variable Gain Control ( $V_{CTRL}$ )**

$V_{CTRLR}$	Gain Control Voltage Range	Set Bit 6 in Register 0x01		0.9 to 3.3		V
$\tau_{CTRL}$	Gain Control Response Time	Set Bit 6 in Register 0x01 (Note 8)		20		ns
$Z_{CTRL}$	Gain Control Input Impedance	Set Bit 6 in Register 0x01		10		pF
$I_{CTRL}$	DC Input Current	Set Bit 6 in Register 0x01 Clear Bit 6 in Register 0x01		2.58 0		mA mA

**Baseband Inputs (BBPI, BBMI, BBPQ, BBMQ)**

$V_{CMBB}$	DC Common Mode Voltage	Internally Generated		1.42		V
$R_{IN(DIFF)}$	Input Resistance	Differential		1.8		k $\Omega$
$R_{IN(CM)}$	Common Mode Input Resistance	Four Baseband Pins Shorted		350		$\Omega$
$I_{BB(OFF)}$	Baseband Leakage Current	Four Baseband Pins Shorted, EN = Low		1.3		nA
$V_{SWING}$	Amplitude Swing	No Hard Clipping, Single-Ended, Digital Gain (DG) = -10		1.2		$V_{P-P}$

**Power Supply ( $V_{CC}$ )**

$V_{CC}$	Supply Voltage		2.7	3.3	3.6	V
$V_{RET(MIN)}$	Minimum Data Retention Voltage	(Note 14)	1.6	1.3		V
$I_{CC(ON)}$	Supply Current	EN = High	20	28	37	mA
$I_{CC(RANGE)}$	Supply Current Range	EN = High, Register 0x01 from 0x00 to 0x13		8 to 36		mA
$I_{CC(OFF)}$	Supply Current, Sleep Mode	EN = 0V		0.7	9	$\mu\text{A}$
$t_{ON}$	Turn-On Time	EN = Low to High (Notes 8, 12)		167		ns
$t_{OFF}$	Turn-Off Time	EN = High to Low (Notes 9, 12)		53		ns
$t_{SB}$	Side-Band Suppression Settling	Register 0x00 Change, <-50dBc (Note 12)		500		ns
$t_{LO}$	LO Suppression Settling	Register 0x02 Change, <-60dBm (Note 12)		90		ns

**Serial Port (CSB, SCLK, SDI, SDO), Enable (EN) and TTCK, SCLK = 20MHz**

$V_{IH}$	Input High Voltage		●	1.1		V
$V_{IL}$	Input Low Voltage		●		0.2	V
$I_{IH}$	Input High Current			0.02		nA
$I_{IL}$	Input Low Current			-0.4		nA
$V_{OH}$	Output High Voltage	(Note 13)	●	$V_{CC\_L} - 0.2$		V
$V_{OL}$	Output Low Voltage	$I_{SINK} = 8\text{mA}$ (Note 10)	●		0.7	V
$I_{OH}$	SDO Leakage Current	for SDO = High		0.5		nA
$V_{HYS}$	Input Trip Point Hysteresis			110		mV
$t_{CKH}$	SCLK High Time		●	22.5	25	ns

**ELECTRICAL CHARACTERISTICS** The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_C = 25^\circ\text{C}$ .  $V_{CC} = 3.3\text{V}$ ,  $V_{EN} = 3.3\text{V}$ ,  $V_{CTRL} = 3.3\text{V}$ ,  $P_{LO} = 0\text{dBm}$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz, 1V<sub>P-P(DIFF, I or Q)</sub>, I and Q 90° shifted, lower sideband selection, all registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

SYMBOL	PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS	
$t_{CSS}$	CSB Setup Time		●	20		ns	
$t_{CSH}$	CSB High Time		●	30		ns	
$t_{CS}$	SDI to SCLK Setup Time		●	20		ns	
$t_{CH}$	SDI to SCLK Hold Time		●	10		ns	
$t_{DO}$	SCLK to SDO Time		●	45		ns	
$t_{C\%}$	SCLK Duty Cycle		●	45	50	55	%
$f_{CLK}$	Maximum SCLK Frequency		●	20		MHz	
$V_{TEMP}$	Temperature Diode Voltage	$I_{TEMP} = 100\mu\text{A}$			763	mV	
	Temperature Slope	$I_{TEMP} = 100\mu\text{A}$			1.6	mV/°C	

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

**Note 2:** The LTC5599 is guaranteed functional over the operating case temperature range from  $-40^\circ\text{C}$  to  $105^\circ\text{C}$ .

**Note 3:** At 6MHz offset from the LO signal frequency. 100nF between BBPI and BBMI, 100nF between BBPQ and BBMQ.

**Note 4:** The Default Register Settings are listed in Table 1.

**Note 5:** IM2 is measured at  $f_{LO} - 4.1\text{MHz}$ .

**Note 6:** IM3 is measured at  $f_{LO} - 2.2\text{MHz}$  and  $f_{LO} - 1.9\text{MHz}$ . OIP3 = lowest of  $(1.5 \cdot P(f_{LO} - 2.1\text{MHz}) - 0.5 \cdot P(f_{LO} - 2.2\text{MHz}))$  and  $(1.5 \cdot P(f_{LO} - 2\text{MHz}) - 0.5 \cdot P(f_{LO} - 1.9\text{MHz}))$ .

**Note 7:** Without side-band or LO feedthrough nulling (unadjusted).

**Note 8:** RF power is within 10% of final value.

**Note 9:** RF power is at least 30dB down from its ON state.

**Note 10:**  $V_{OL}$  voltage scales linear with current sink. For example for  $R_{PULL-UP} = 1\text{k}\Omega$ ,  $V_{CC\_L} = 3.3\text{V}$  the SDO sink current is about  $(3.3 - 0.2)/1\text{k}\Omega = 3.1\text{mA}$ . Max  $V_{OL} = 0.7 \cdot 3.1/8 = 0.271\text{V}$ , with  $R_{PULL-UP}$  the SDO

pull-up resistor and  $V_{CC\_L}$  the digital supply voltage to which  $R_{PULL-UP}$  is connected to.

**Note 11:** I and Q baseband Input signal = 2MHz CW, 0.8V<sub>P-P, DIFF</sub> each, I and Q 0° shifted.

**Note 12:**  $f_{LO} = 500\text{MHz}$ ,  $P_{LO} = 0\text{dBm}$ ,  $C_4 = 1.5\text{nF}$

**Note 13:** Maximum  $V_{OH}$  is derated for capacitive load using the following formula:  $V_{CC\_L} \cdot \exp(-0.5 \cdot T_{CLK}/(R_{PULL-UP} \cdot C_{LOAD}))$ , with  $T_{CLK}$  the time of one SCLK cycle,  $R_{PULL-UP}$  the SDO pull-up resistor,  $V_{CC\_L}$  the digital supply voltage to which  $R_{PULL-UP}$  is connected to, and  $C_{LOAD}$  the capacitive load at the SDO pin. For example for  $T_{CLK} = 100\text{ns}$  (10MHz SCLK),  $R_{PULL-UP} = 1\text{k}\Omega$ ,  $C_{LOAD} = 10\text{pF}$  and  $V_{CC\_L} = 3.3\text{V}$  the derating is  $3.3 \cdot \exp(-5) = 22.2\text{mV}$ , thus maximum  $V_{OH} = 3.3\text{V} - 0.1 - 0.0222 = 3.177\text{V}$ .

**Note 14:** Minimum  $V_{CC}$  in order to retain register data content.

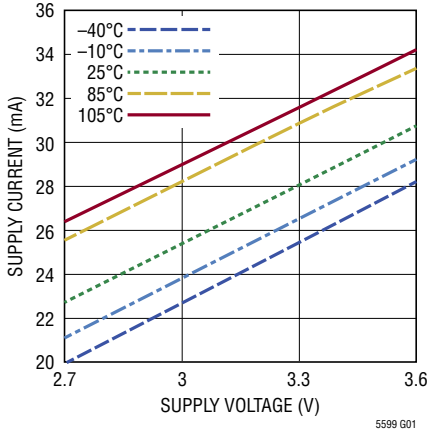
**Note 15:** Guaranteed by design and characterization. This parameter is not tested.

**Note 16:** RF pin guaranteed by design while using a 10nF coupling capacitor. The RF pin is not tested.

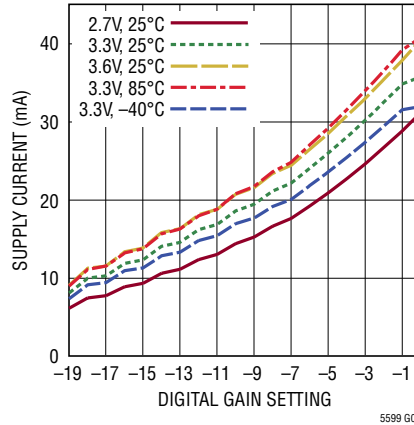
## TYPICAL PERFORMANCE CHARACTERISTICS

$V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P}(DIFF, I \text{ or } Q)$ , I and Q  $90^\circ$  shifted, lower sideband selection,  $TEMPUPDT = 0$ , register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

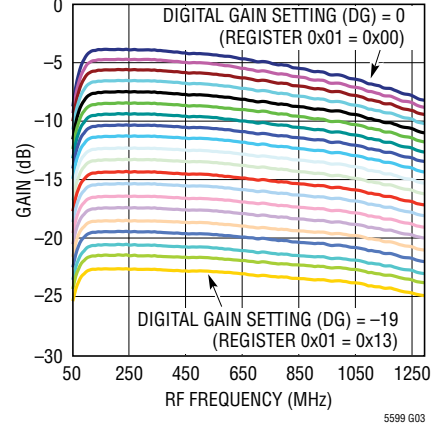
**Supply Current vs Supply Voltage**



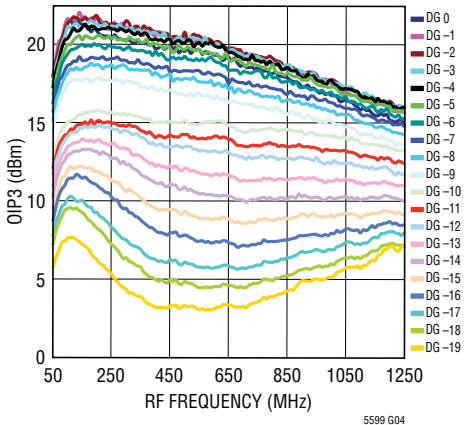
**Supply Current vs Digital Gain Setting**



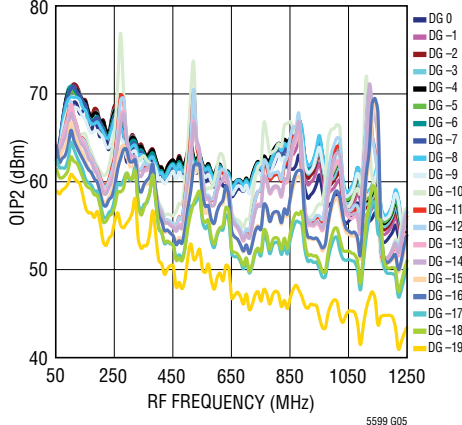
**Gain vs RF Frequency and Digital Gain Setting**



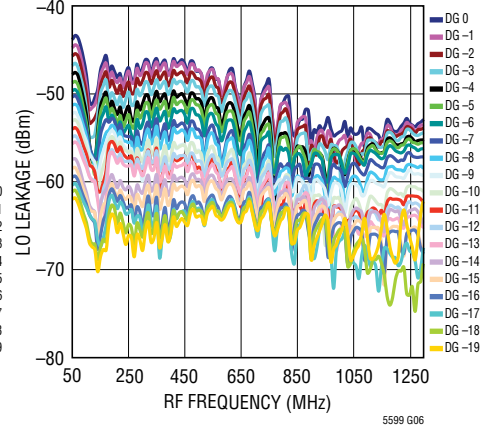
**Output IP3 vs RF Frequency and Digital Gain Setting**



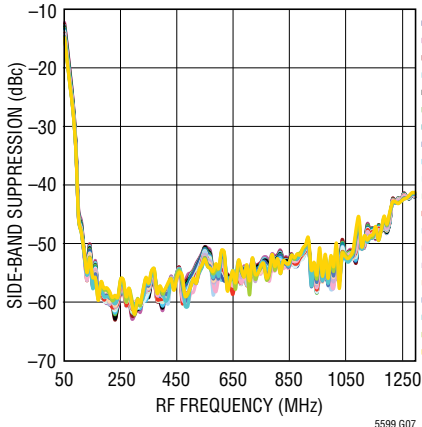
**Output IP2 vs RF Frequency and Digital Gain Setting**



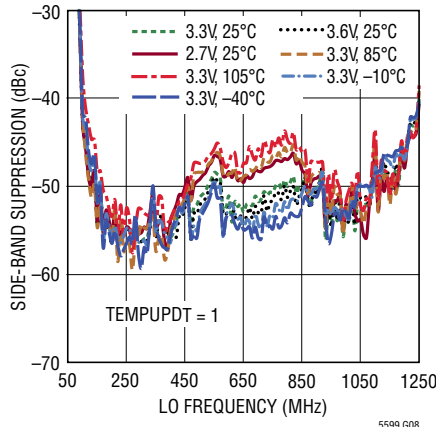
**LO Leakage vs RF Frequency and Digital Gain Setting**



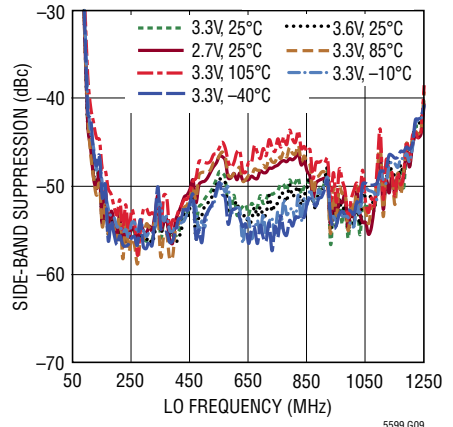
**Side-Band Suppression vs RF Frequency and Digital Gain Setting**



**Side-Band Suppression vs LO Frequency for Gain TempComp Off**

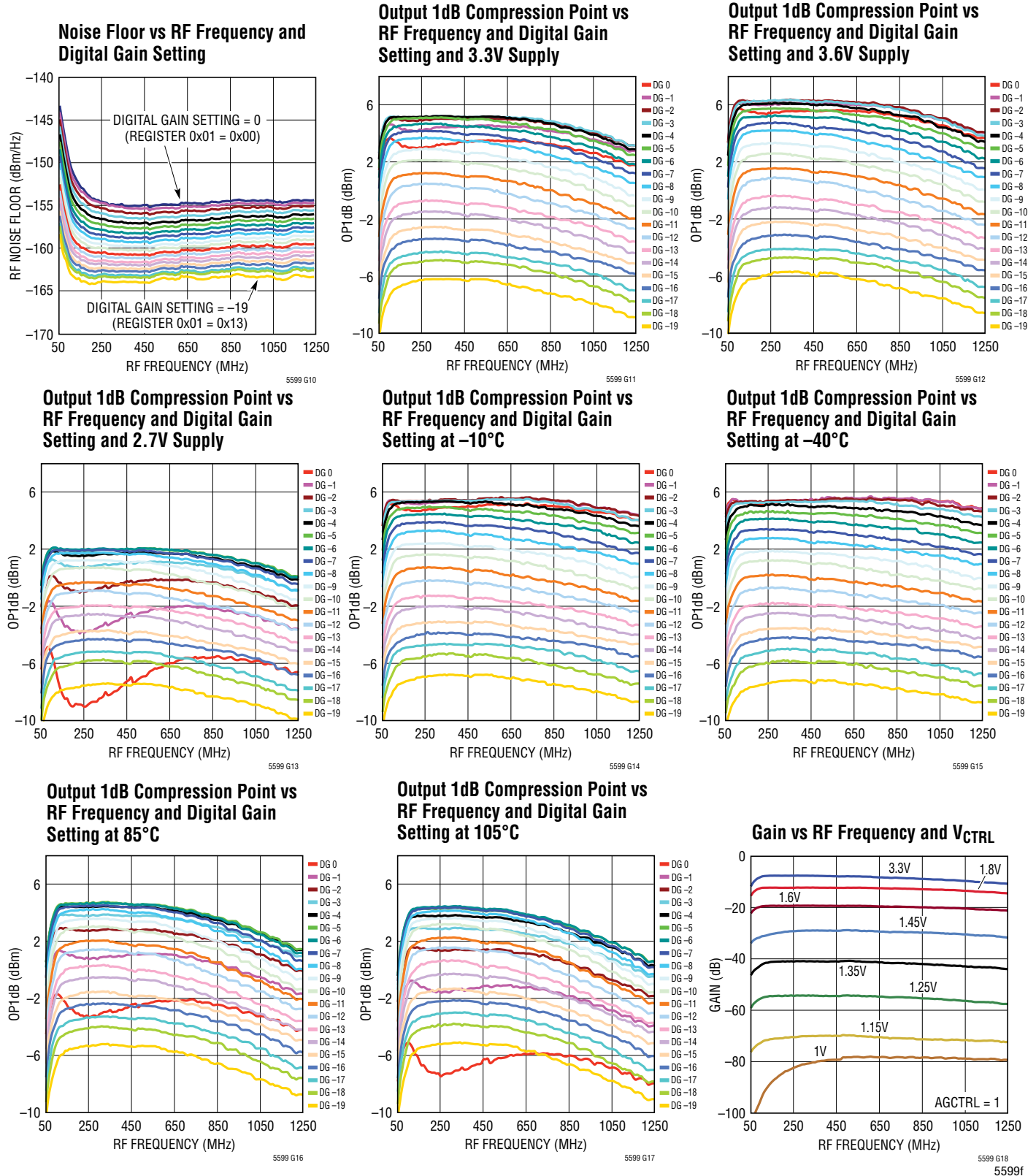


**Side-Band Suppression vs LO Frequency for Gain TempComp On**



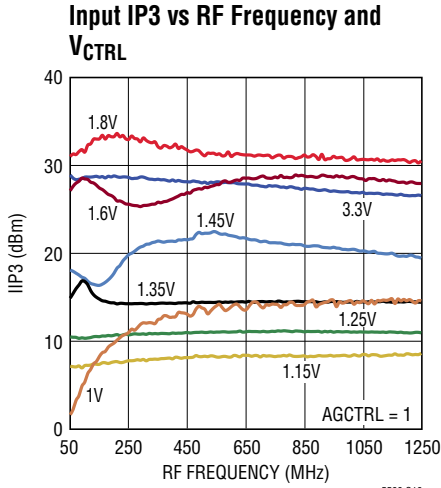
# TYPICAL PERFORMANCE CHARACTERISTICS

$V_{CC} = 3.3V$ ,  $V_{EN} = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

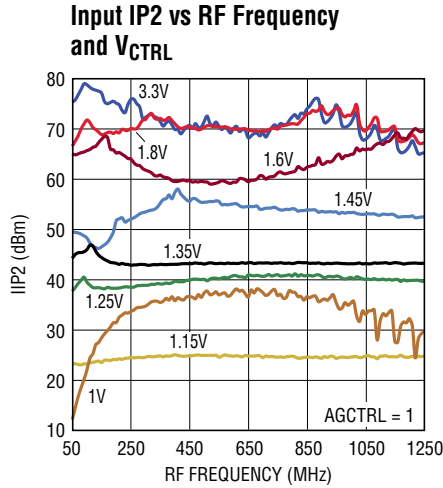


**TYPICAL PERFORMANCE CHARACTERISTICS**

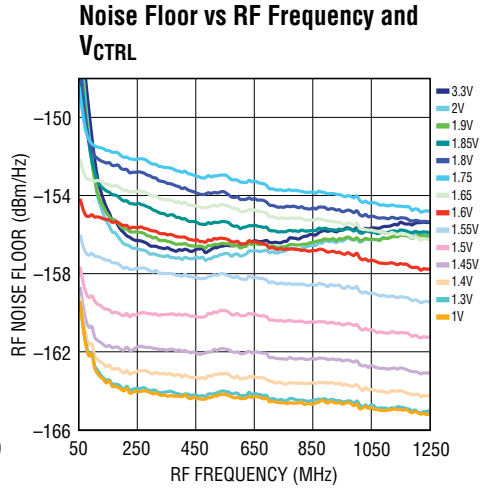
$V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.



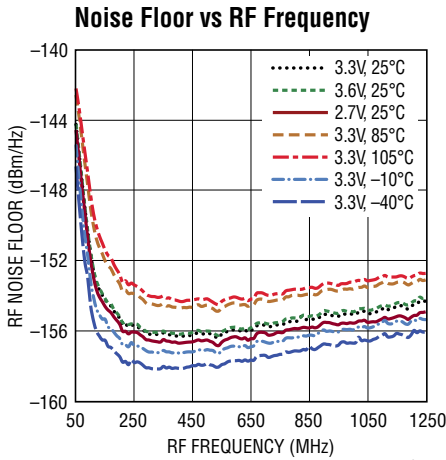
5599 G19



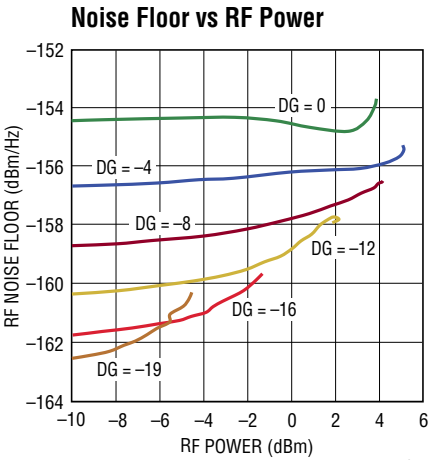
5599 G20



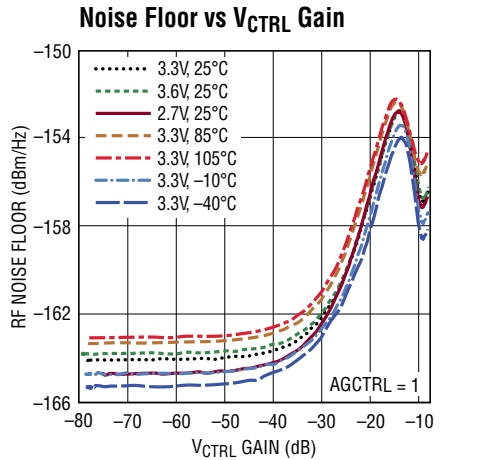
5599 G21



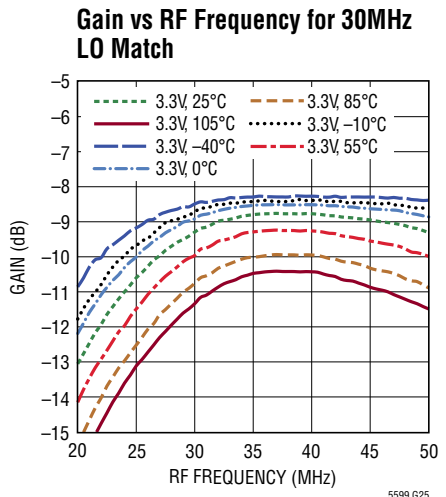
5599 G22



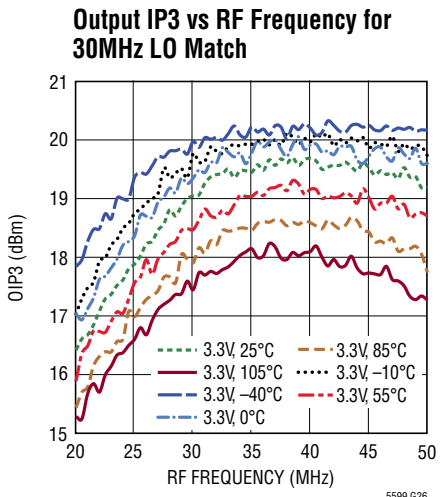
5599 G23



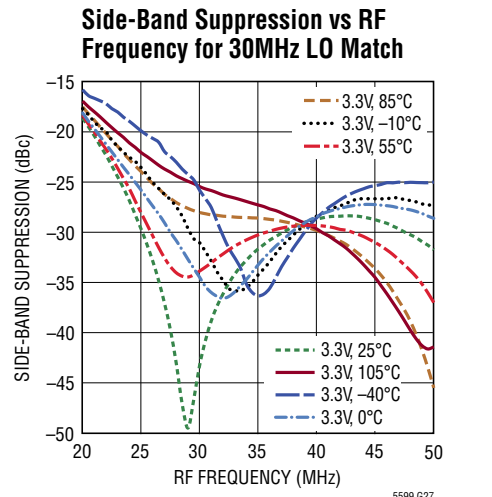
5599 G24



5599 G25



5599 G26

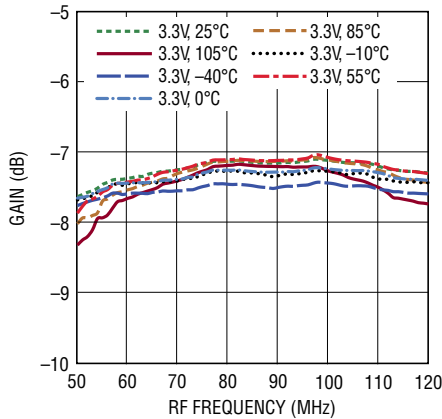


5599 G27

# TYPICAL PERFORMANCE CHARACTERISTICS

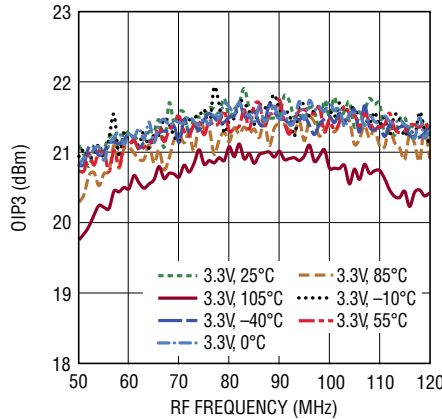
$V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

**Gain vs RF Frequency for 70MHz LO Match**



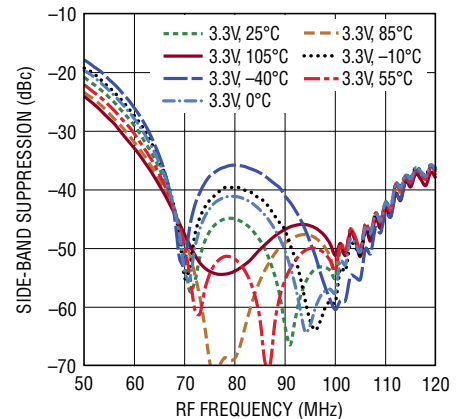
5599 G28

**Output IP3 vs RF Frequency for 70MHz LO Match**



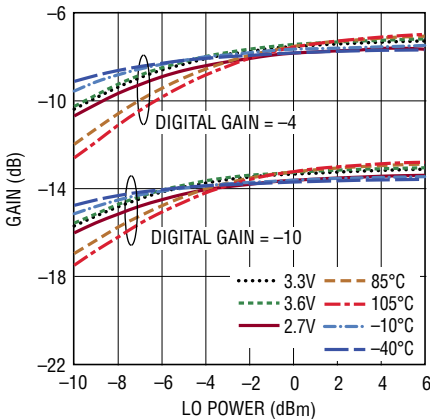
5599 G29

**Side-Band Suppression vs RF Frequency for 70MHz LO Match**



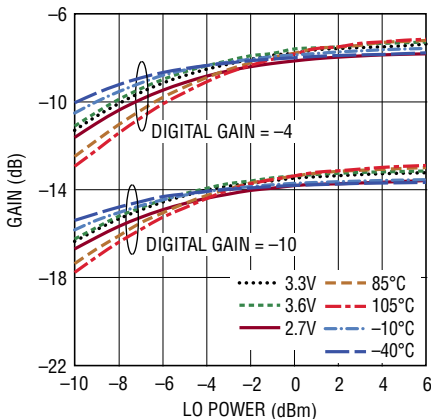
5599 G30

**Gain vs LO Power at  $f_{LO} = 150MHz$**



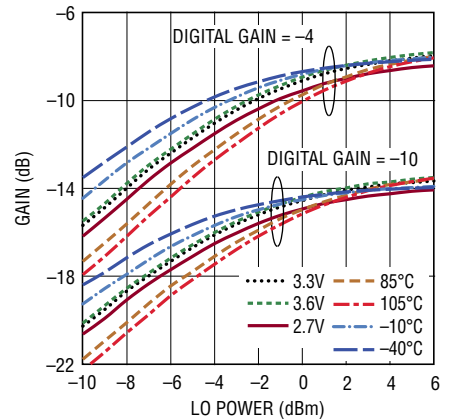
5599 G31

**Gain vs LO Power at  $f_{LO} = 500MHz$**



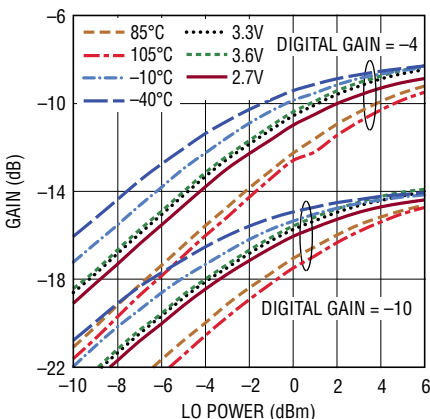
5599 G32

**Gain vs LO Power at  $f_{LO} = 900MHz$**



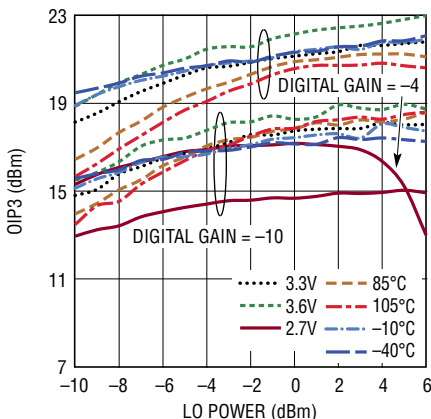
5599 G33

**Gain vs LO Power at  $f_{LO} = 1260MHz$**



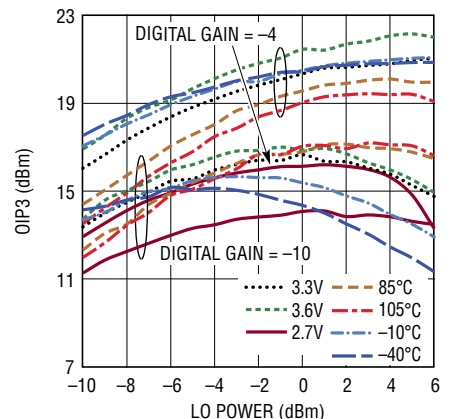
5599 G34

**Output IP3 vs LO Power at  $f_{LO} = 150MHz$**



5599 G35

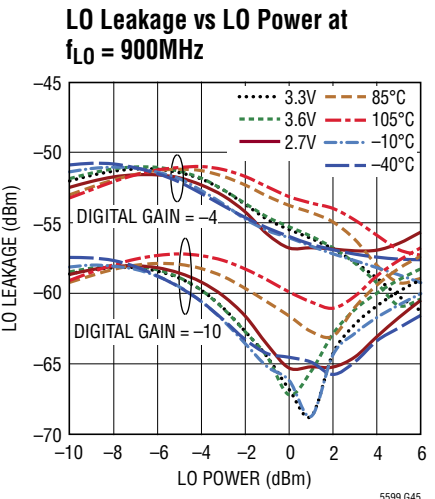
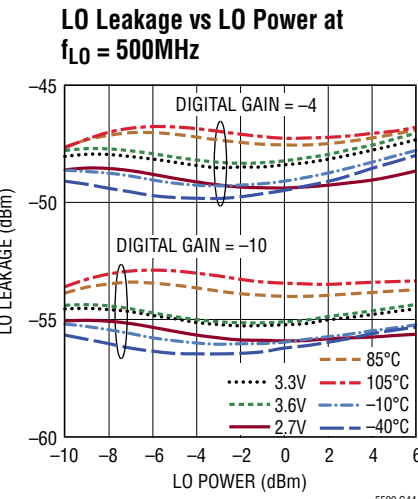
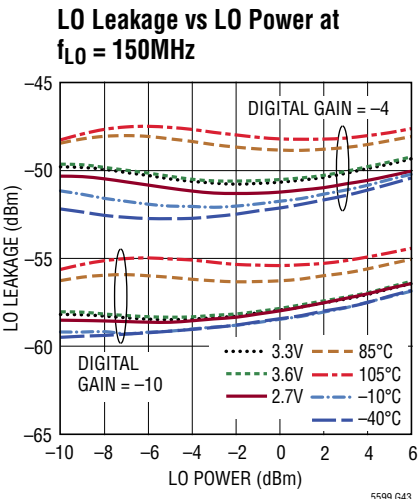
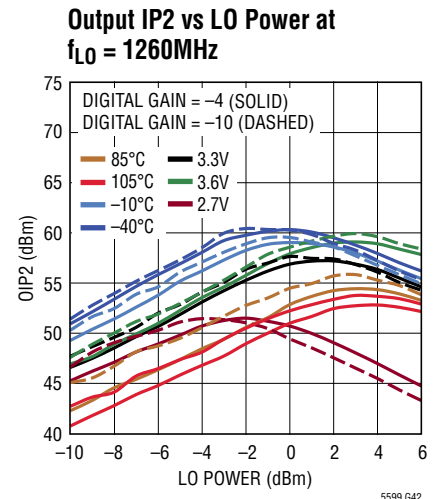
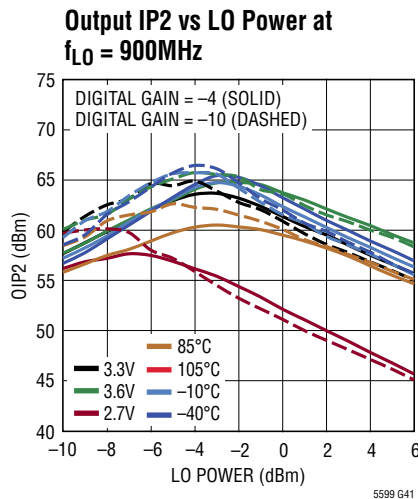
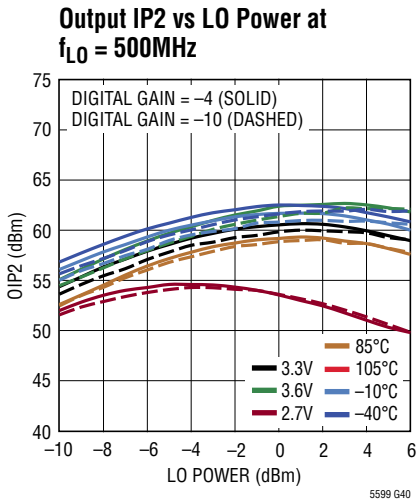
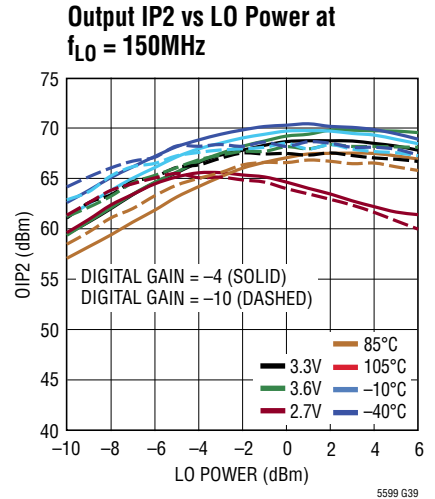
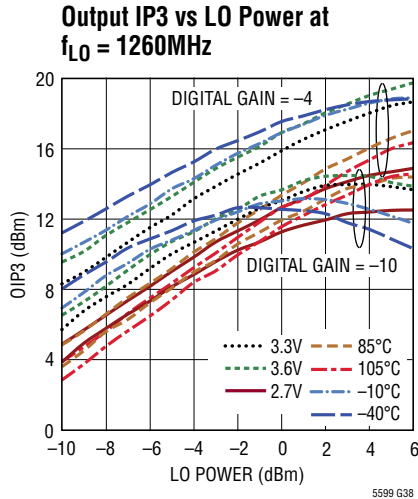
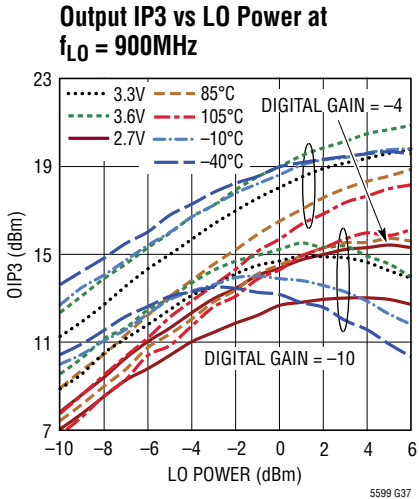
**Output IP3 vs LO Power at  $f_{LO} = 500MHz$**



5599 G36

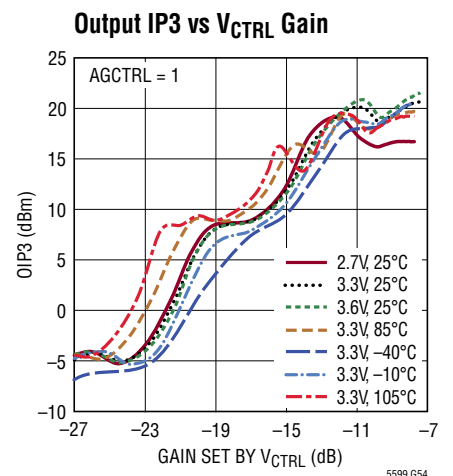
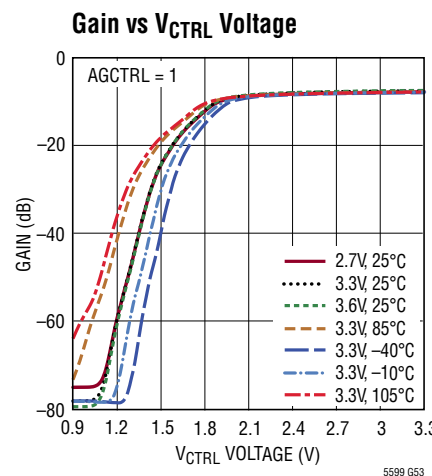
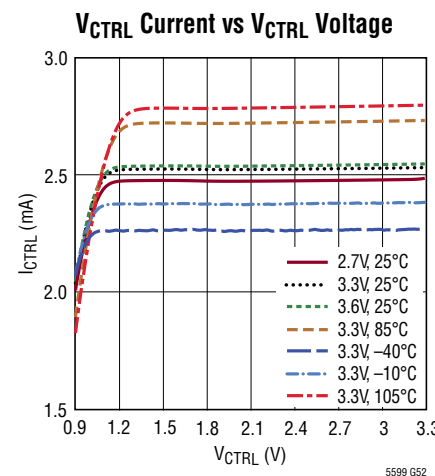
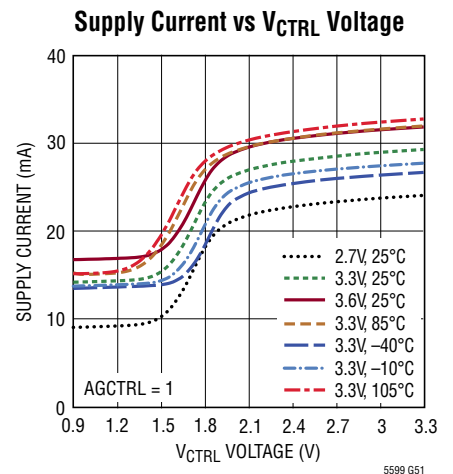
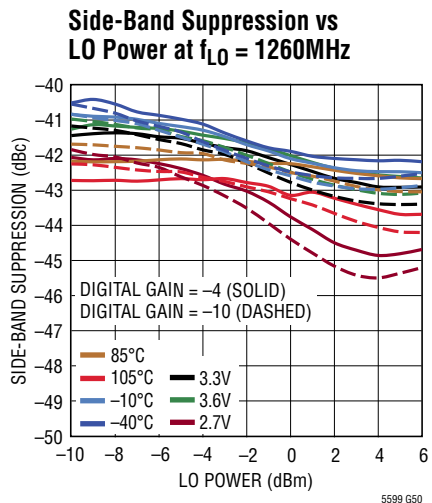
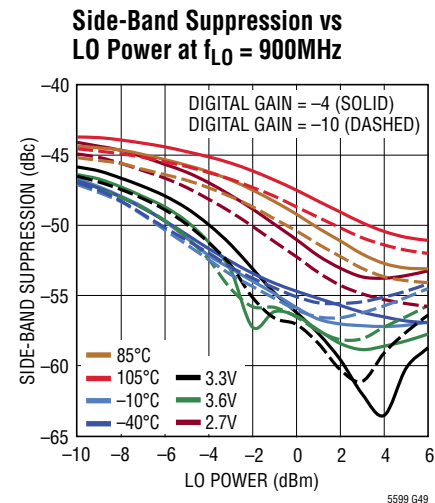
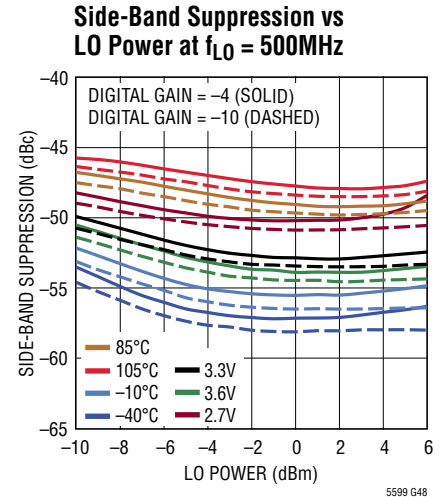
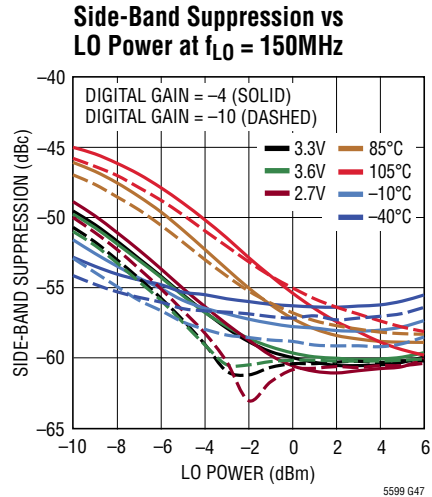
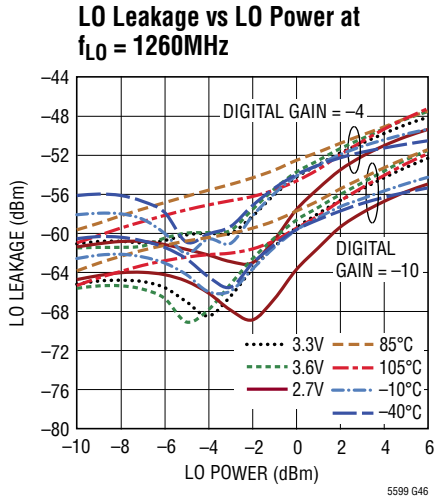
**TYPICAL PERFORMANCE CHARACTERISTICS**

$V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P}(DIFF, I \text{ or } Q)$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.



# TYPICAL PERFORMANCE CHARACTERISTICS

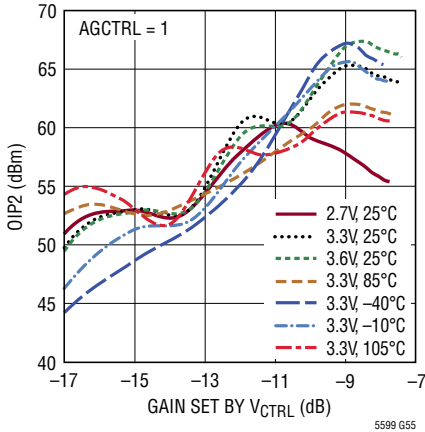
$V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz, 1V<sub>P-P</sub>(DIFF, I or Q), I and Q 90° shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.



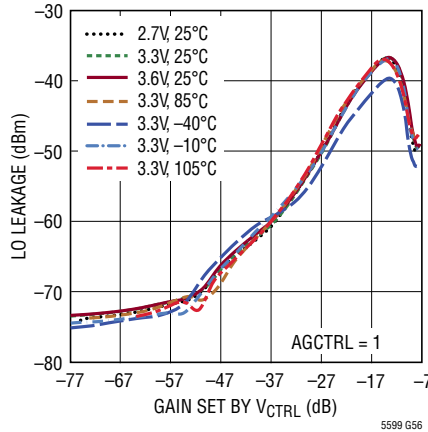
**TYPICAL PERFORMANCE CHARACTERISTICS**

$V_{CC} = 3.3V$ ,  $V_{EN} = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P}(DIFF, I \text{ or } Q)$ , I and Q  $90^\circ$  shifted, lower sideband selection,  $TEMPUPDT = 0$ , register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

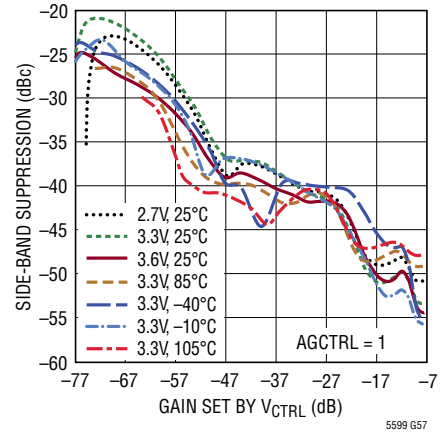
**Output IP2 vs  $V_{CTRL}$  Gain**



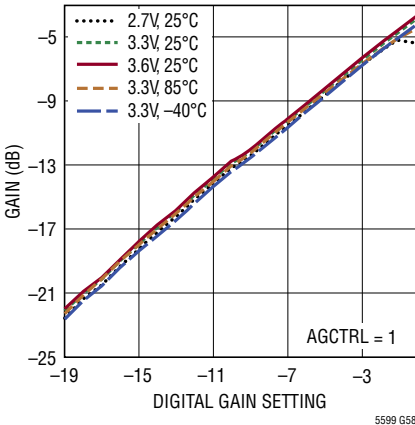
**LO Leakage vs  $V_{CTRL}$  Gain**



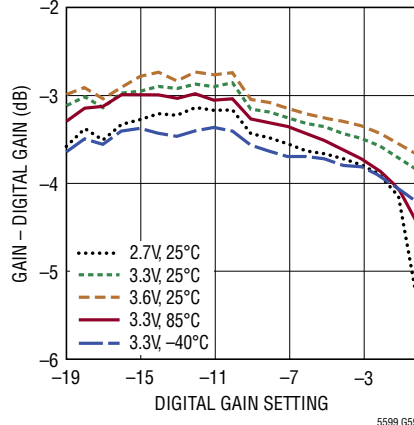
**Side-Band Suppression vs  $V_{CTRL}$  Gain**



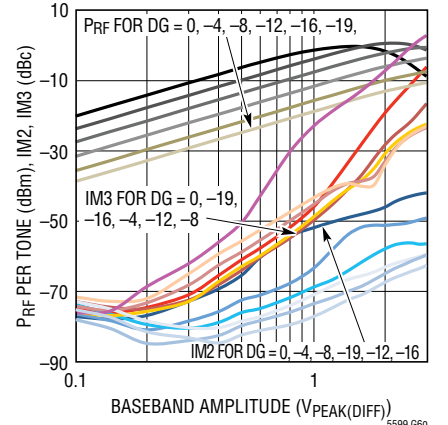
**Gain vs Digital Gain Setting**



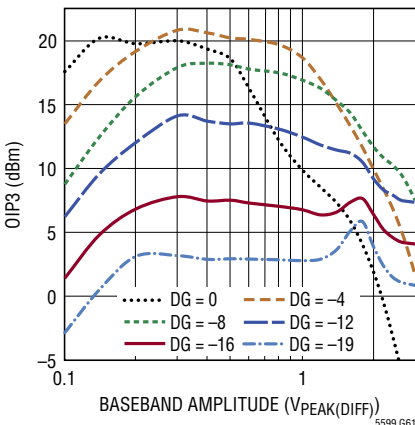
**Gain Minus Digital Gain vs Digital Gain Setting**



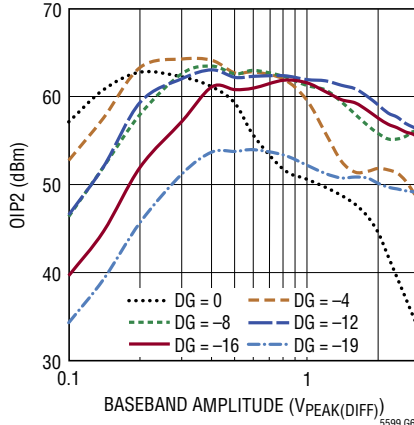
**$P_{RF}$ , IM2, IM3 vs Baseband Amplitude**



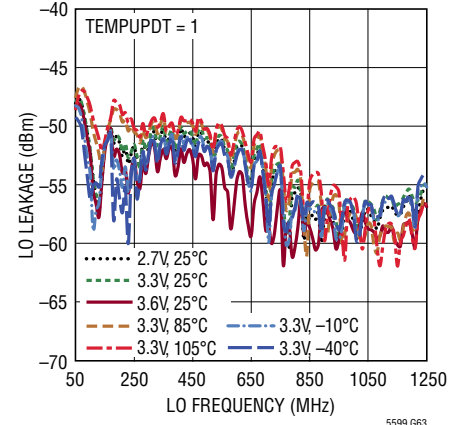
**Output IP3 vs Baseband Amplitude**



**Output IP2 vs Baseband Amplitude**

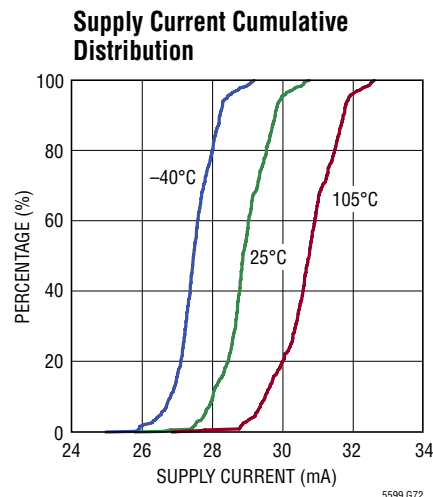
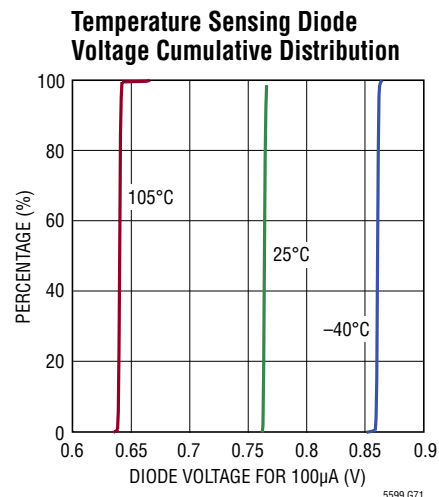
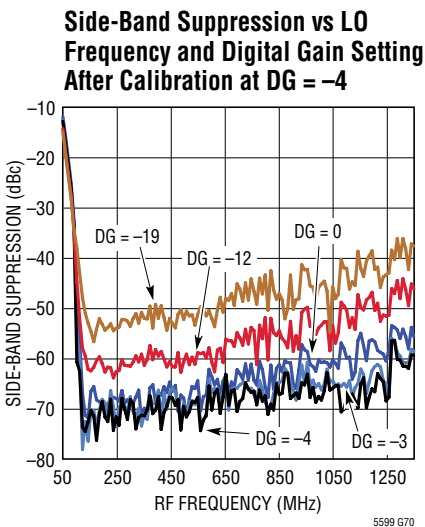
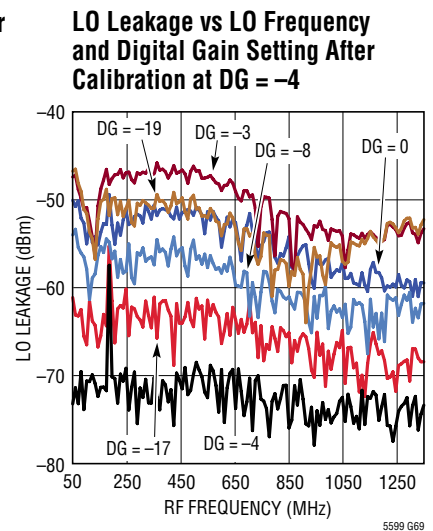
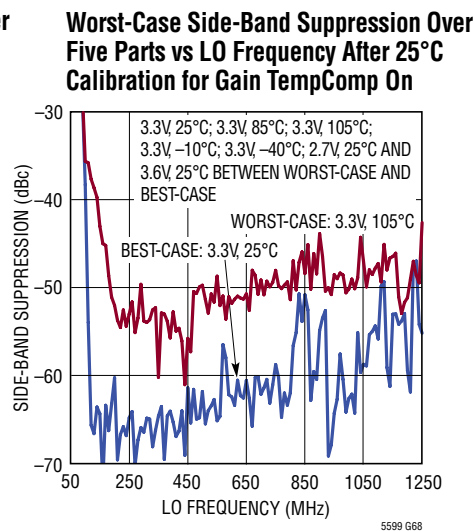
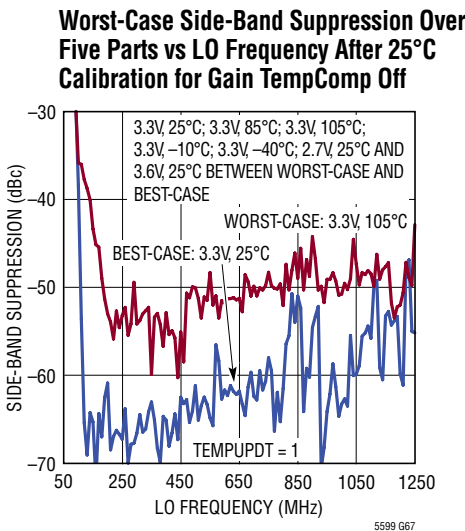
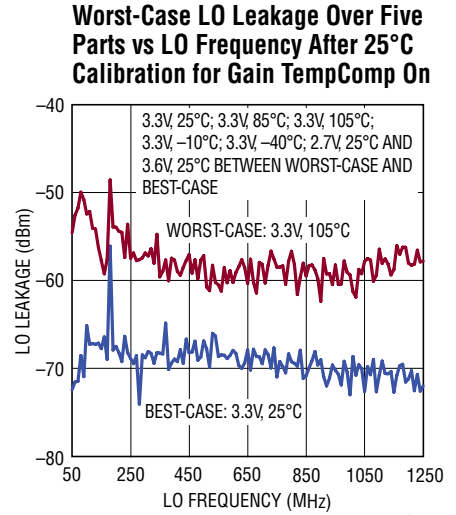
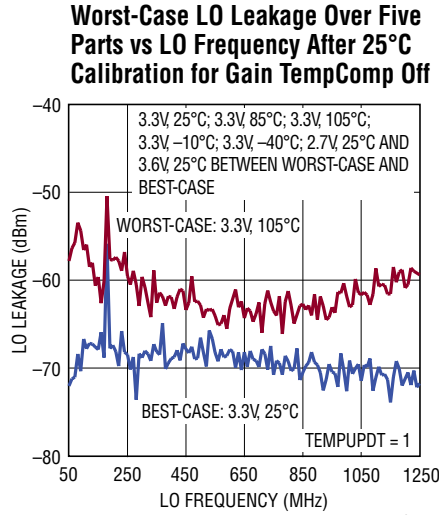
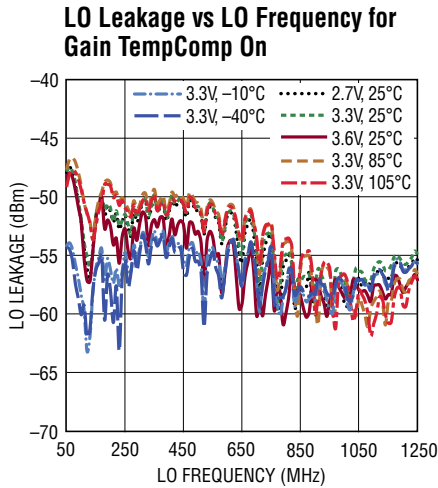


**LO Leakage vs LO Frequency for Gain TempComp Off**



# TYPICAL PERFORMANCE CHARACTERISTICS

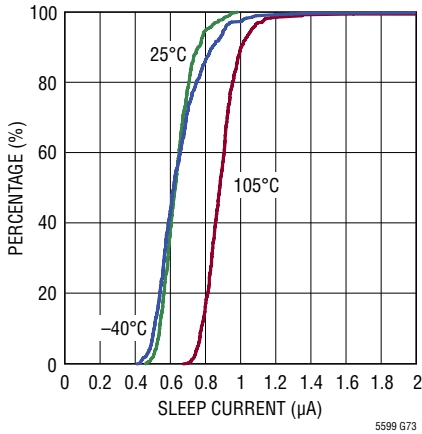
$V_{CC} = 3.3V$ ,  $V_{EN} = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P}(DIFF, I \text{ or } Q)$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.



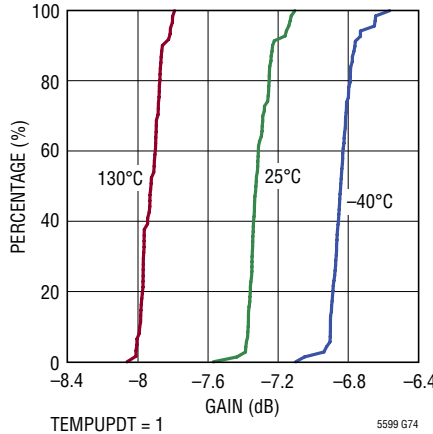
**TYPICAL PERFORMANCE CHARACTERISTICS**

$V_{CC} = 3.3V$ ,  $EN = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz, 1V<sub>P-P</sub>(DIFF, I or Q), I and Q 90° shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

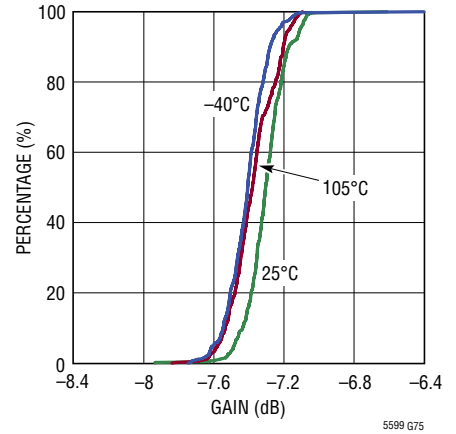
**Sleep Current Cumulative Distribution**



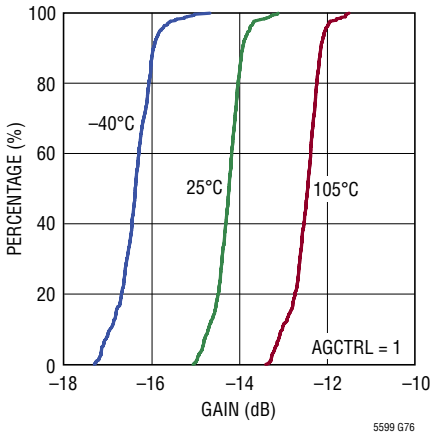
**Gain Cumulative Distribution for Gain TempComp Off**



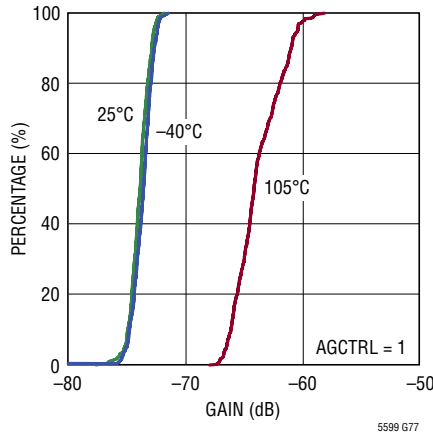
**Gain Cumulative Distribution for Gain TempComp On**



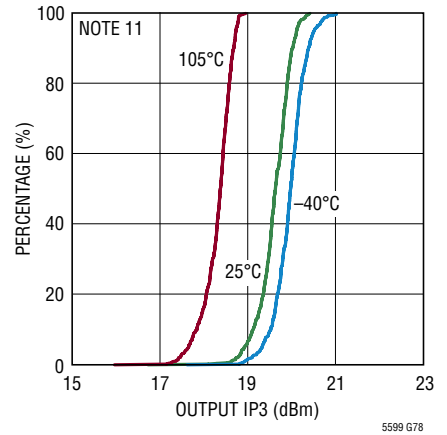
**Gain Cumulative Distribution for V<sub>CTRL</sub> = 1.75V**



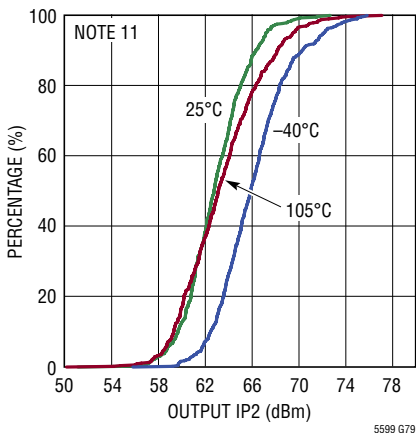
**Gain Cumulative Distribution for V<sub>CTRL</sub> = 1V**



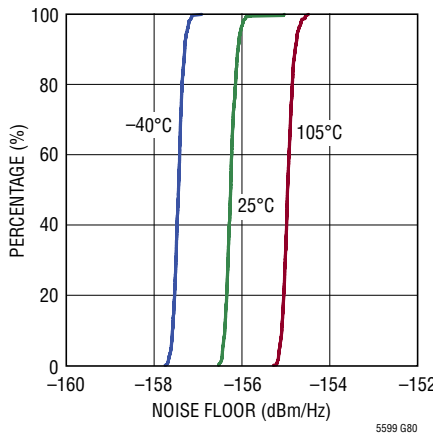
**Output IP3 Cumulative Distribution**



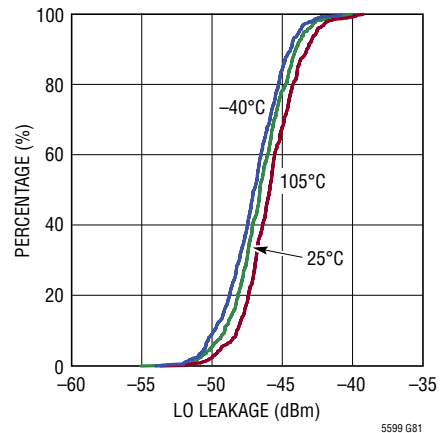
**Output IP2 Cumulative Distribution**



**Noise Floor Cumulative Distribution**

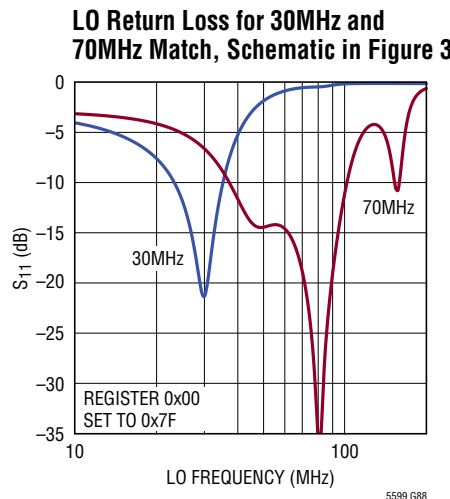
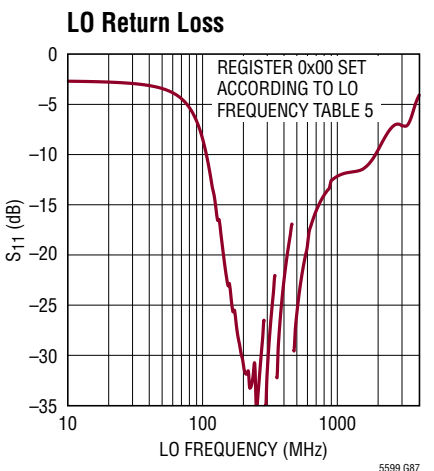
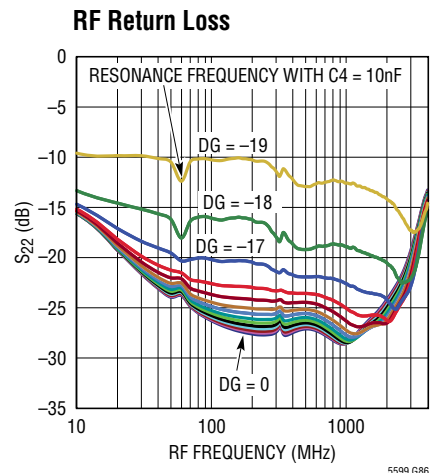
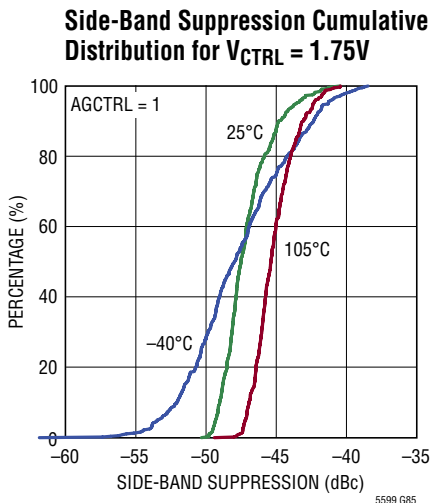
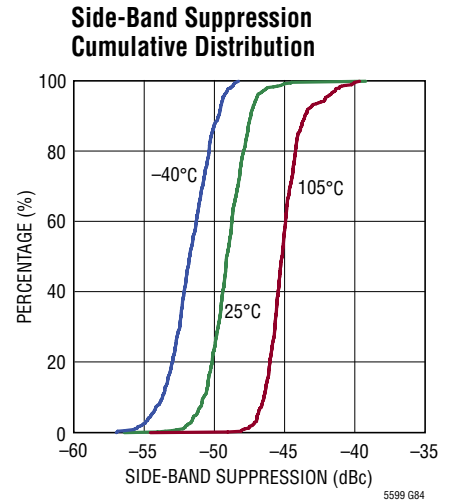
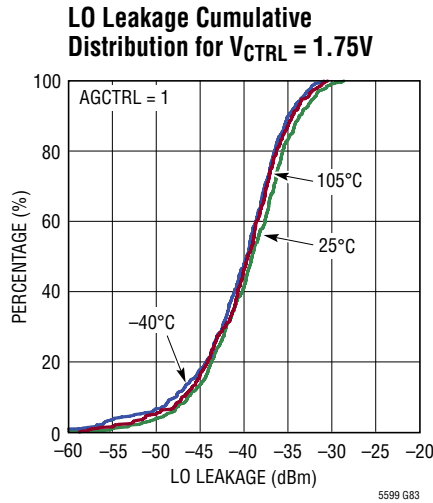
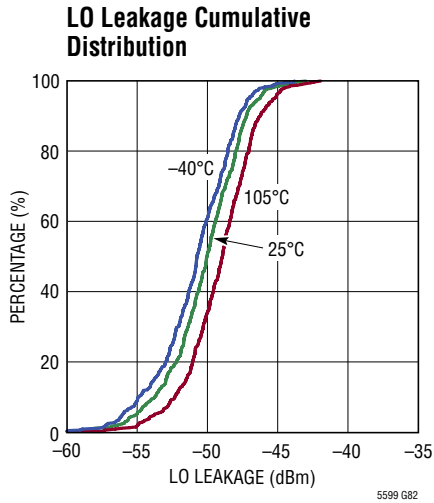


**LO Leakage Cumulative Distribution for Floating Baseband Pins**



**TYPICAL PERFORMANCE CHARACTERISTICS**

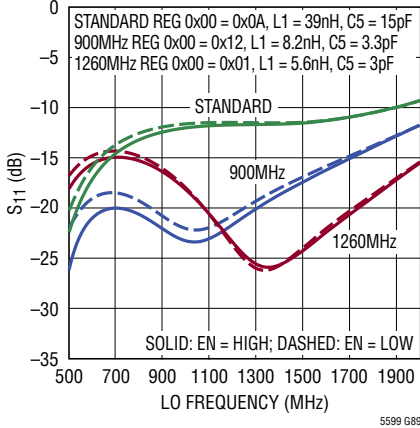
$V_{CC} = 3.3V$ ,  $V_{EN} = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.



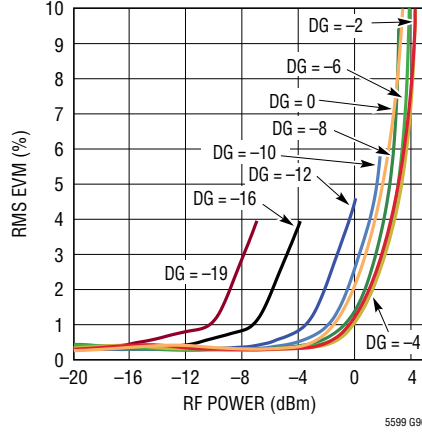
## TYPICAL PERFORMANCE CHARACTERISTICS

$V_{CC} = 3.3V$ ,  $V_{EN} = 3.3V$ ,  $V_{CTRL} = 3.3V$ ,  $T_C = 25^\circ C$ ,  $P_{LO} = 0dBm$ ,  $f_{LO} = 500MHz$ , BBPI, BBMI, BBPQ, BBMQ common mode DC voltage  $V_{CMBB} = 1.4V_{DC}$ , I and Q baseband input signal = 2MHz, 2.1MHz,  $1V_{P-P(DIFF, I \text{ or } Q)}$ , I and Q  $90^\circ$  shifted, lower sideband selection, TEMPUPDT = 0, register 0x00 value according to Table 5, all other registers set to default values, unless otherwise noted. Test circuit is shown in Figure 13.

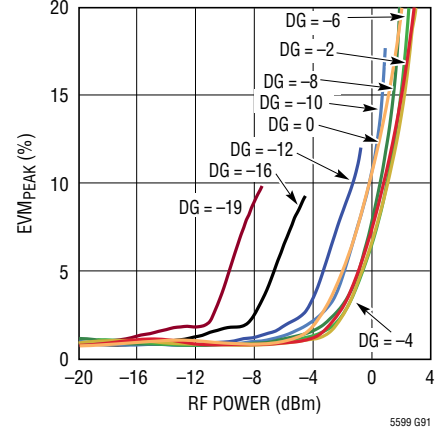
**LO Return Loss for Standard, 900MHz and 1260MHz Match**



**RMS EVM vs RF Output Power with 1Ms/s 16-QAM Signal**



**Peak EVM vs RF Output Power with 1Ms/s 16-QAM Signal**



## PIN FUNCTIONS

**V<sub>CTRL</sub> (Pin 1):** Variable Gain Control Input. This analog control pin sets the gain. Write a “1” to bit 6 in register 0x01 (AGCTRL = 1) to activate this pin, resulting in about 2.58mA current draw from a positive supply. Typical V<sub>CTRL</sub> voltage range is 0.9V to 3.3V. Gain transfer function is not linear-in-dB. Tie to V<sub>CC</sub> when not used.

**GND (Pins 2, 5, 12, Exposed Pad 25):** Ground. All these pins are connected together internally. For best RF performance all ground pins should be connected to RF ground.

**LOL, LOC (Pins 3, 4):** LO Inputs. This is not a differential input. Both pins are 50Ω inputs. An LC diplexer is recommended to be used at these pins (see Figure 13). AC-coupling capacitors are required at these pins if the applied DC level is higher than ±100mV.

**TTCK (Pin 6):** Temperature Update. When the TTCK temperature update mode is selected in register 0x01 (bit 7 = High, TEMPUPDT = 1), the temperature readout and digital gain compensation vs temperature can be updated through a logic low to logic high transition at this pin. Do not float.

**TEMP (Pin 7):** Temperature Sensing Diode. This pin is connected to the anode of a diode that may be used to measure the die temperature, by forcing a current and measuring the voltage. This diode is not part of the on-chip thermometer.

**BBPI, BBMI (Pins 8, 9):** Baseband Inputs of the I-Channel. The input impedance of each input is about 1kΩ. It should be externally biased to a 1.4V common mode level, or AC-coupled. Do not apply common mode voltage beyond 2V<sub>DC</sub>.

**BBPQ, BBMQ (Pins 10, 11):** Baseband Inputs of the Q-Channel. The input impedance of each input is about 1kΩ. It should be externally biased to a 1.4V common mode level, or AC-coupled. Do not apply common mode voltage beyond 2V<sub>DC</sub>. Float if Q-channel is disabled.

**GNDRF (Pins 13, 14, 15, 17, 18):** RF Ground. These pins are connected together internally. For best RF performance all ground pins should be connected to RF ground.

**RF (Pin 16):** RF Output. The output impedance at RF frequencies is 50Ω. Its DC output voltage is about 1.7V if enabled. An AC-coupling capacitor should be used at this pin with a recommended value of 10nF.

**CSB (Pin 19):** Serial Port Chip Select. This CMOS input initiates a serial port transaction when driven low, ending the transaction when driven back high. Do not float.

**SCLK (Pin 20):** Serial Port Clock. This CMOS input clocks serial port input data on its rising edge. Do not float.

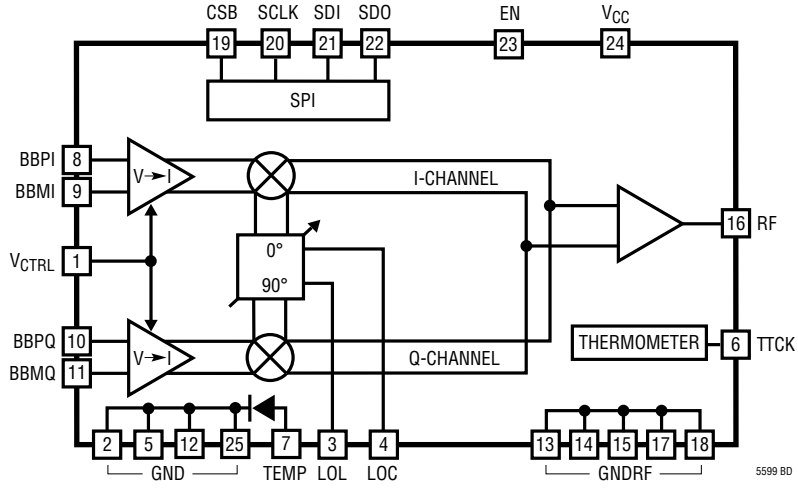
**SDI (Pin 21):** Serial Port Data Input. The serial port uses this CMOS input for data. Do not float.

**SDO (Pin 22):** Serial Port Data Output. This NMOS output presents data from the serial port during a read transaction. Connect this pin to the digital supply voltage through a pull-up resistor of sufficiently large value, to ensure that the current does not exceed 10mA when pulled low.

**EN (Pin 23):** Enable Pin. The chip is completely turned on when a logic high voltage is applied to this pin, and completely turned off for a logic low voltage. Do not float.

**V<sub>CC</sub> (Pin 24):** Power Supply. It is recommended to use 1nF and 4.7μF capacitors for decoupling to ground on this pin.

**BLOCK DIAGRAM**



## APPLICATIONS INFORMATION

The LTC5599 consists of I and Q input differential voltage-to-current converters, I and Q upconverting mixers, an RF output buffer and an LO quadrature phase generator. An SPI bus addresses nine control registers, enabling optimization of side-band suppression, LO leakage, and adjustment of the modulator gain. See Table 1 for a summary of the writable registers and their default values. A full map of all the registers in the LTC5599 is listed in Table 10 and Table 11 in the Appendix.

**Table 1. SPI Writable Registers and Default Register Values.**

ADDRESS	DEFAULT VALUE	SETTING	REGISTER FUNCTION
0x00	0x2E	490MHz	LO Frequency Tuning
0x01	0x84	DG = -4	Gain
0x02	0x80	0mV	Offset I-Channel
0x03	0x80	0mV	Offset Q-Channel
0x04	0x80	0dB	I/Q Gain Ratio
0x05	0x10	0°	I/Q Phase Balance
0x06	0x50	OFF	LO Port Matching Override
0x07	0x06	OFF	Temperature Correction Override
0x08	0x00	NORMAL	Operating Mode

Without using the SPI the registers will use the default values which may not result in the optimum side-band suppression (SB). For example: for LO frequency from about 400MHz to about 580MHz, the SB is about -45dBc; from 380MHz to 400MHz and 580MHz to 630MHz it falls to about -40dBc; from 350MHz to 380MHz and 630MHz to 690MHz the SB falls to about -35dBc.

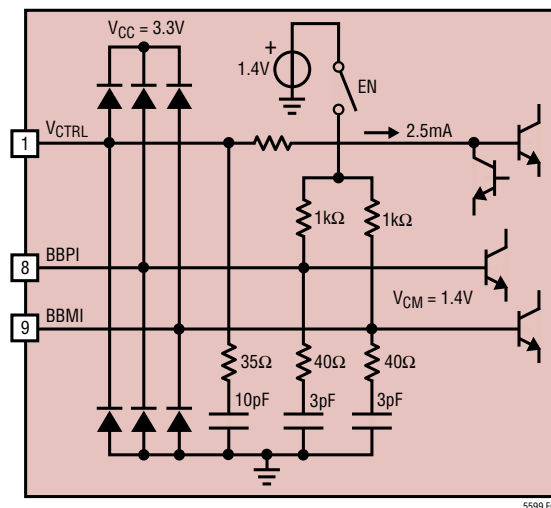
Aside of powering up the LTC5599, the register values can be reset to the default values by setting SRESET = 1 (bit 3, register 0x08). After about 50ns SRESET is automatically set back to 0.

External I and Q baseband signals are applied to the differential baseband input pins: BBPI, BBMI and BBPQ, BBMQ. These voltage signals are converted to currents and translated to RF frequency by means of double-balanced upconverting mixers. The mixer outputs are combined at the inputs of the RF output buffer, which also transforms the output impedance to 50Ω. The center frequency of the

resulting RF signal is equal to the LO signal frequency. The LO inputs drive a phase shifter which splits the LO signal into in-phase and quadrature signals which drive the upconverting mixers. In most applications, the LOL input is driven by the LO source via a 39nH inductor, while the LOC input is driven by the LO source via a 15pF capacitor. This inductor and capacitor form a diplexer circuit tuned to 200MHz. The RF output is single-ended and internally 50Ω matched across a wide RF frequency range from 0.6MHz to 6GHz with better than 10dB return loss using C4 = 10nF. See Figure 13.

### Baseband Interface

The baseband inputs (BBPI, BBMI, BBPQ, BBMQ) present a differential input impedance of about 1.8kΩ, as depicted in Figure 1. The baseband bandwidth depends on the source impedance and the frequency setting (register 0x00). It is recommended to compensate the baseband input impedance in the baseband lowpass filter design in order to achieve best gain flatness vs baseband frequency. The S-parameters for (each of) the baseband inputs are given in Table 2 for various LO frequency and gain settings.



**Figure 1. Simplified Circuit Schematic of the Base Band Input Interface (Only One Channel Is Shown).**

## APPLICATIONS INFORMATION

Table 2. Differential Baseband (BB) Input Impedance vs Frequency for EN = High and  $V_{CMBB} = 1.4V$

BB FREQUENCY (MHz)	INPUT IMPEDANCE ( $\Omega$ )		REFL COEFFICIENT	
	REAL*	IMAG* (CAP)	MAG	ANGLE
<b>LO FREQUENCY = 92MHz (REGISTER 0x00 = 0x79), DIGITAL GAIN = -4dB</b>				
1	1.90k	-7.17k (22.2pF)	0.900	-1.6
4	1.76k	-1.82k (21.9pF)	0.893	-6.3
10	1.25k	-751 (21.2pF)	0.854	-15
20	678	-429 (18.6pF)	0.755	-27
40	342	-308 (12.9pF)	0.585	-39
<b>LO FREQUENCY = 150MHz (REGISTER 0x00 = 0x62), DIGITAL GAIN = -4dB</b>				
1	1.90k	-9.11k (17.5pF)	0.900	-1.3
4	1.82k	-2.30k (17.3pF)	0.896	-5.0
10	1.45k	-935 (17.0pF)	0.872	-12
20	887	-507 (15.7pF)	0.804	-23
40	441	-325 (12.2pF)	0.658	-36
100	226	-252 (6.3pF)	0.457	-51
<b>LO FREQUENCY = 500MHz (REGISTER 0x00 = 0x2D), DIGITAL GAIN = -4dB</b>				
1	1.91k	-14.7k (10.6pF)	0.900	-0.8
4	1.89k	-3.74k (10.7pF)	0.899	-3.0
10	1.72k	-1.50k (10.7pF)	0.891	-7.7
20	1.35k	-769 (10.4pF)	0.864	-15
40	786	-426 (9.4pF)	0.785	-27
100	323	-251 (6.4pF)	0.583	-47
200	212	-190 (4.2pF)	0.478	-65
<b>LO FREQUENCY = 500MHz (REGISTER 0x00 = 0x2D), DIGITAL GAIN = 0dB</b>				
1	1.56k	-15.0k (10.6pF)	0.879	-0.8
4	1.56k	-3.84k (10.4pF)	0.880	-3.0
10	1.48k	-1.52k (10.4pF)	0.874	-7.5
20	1.21k	-784 (10.2pF)	0.849	-15
40	753	-432 (9.2pF)	0.776	-27
100	323	-251 (6.3pF)	0.582	-47
200	213	-190 (4.2pF)	0.478	-65
<b>LO FREQUENCY = 900MHz (REGISTER 0x00 = 0x12), DIGITAL GAIN = -4dB</b>				
1	1.91k	-17.0k (9.4pF)	0.901	-0.7
2	1.90k	-4.3k (9.3pF)	0.900	-2.7
10	1.77k	-1.72k (9.3pF)	0.893	-6.7
20	1.46k	-878 (9.1pF)	0.873	-13
40	915	-475 (8.4pF)	0.811	-24
100	371	-261 (6.1pF)	0.622	-45
200	233	-193 (4.1pF)	0.506	-62

Table 2. Differential Baseband (BB) Input Impedance vs Frequency for EN = High and  $V_{CMBB} = 1.4V$  (continued)

BB FREQUENCY (MHz)	INPUT IMPEDANCE ( $\Omega$ )		REFL COEFFICIENT	
	REAL*	IMAG* (CAP)	MAG	ANGLE
<b>EN = Low (Chip Disabled, REGISTER 0x00 = 0x2E)</b>				
1	2.04k	-18.2k (8.8pF)	0.906	-0.6
2	2.02k	-4.59k (8.7pF)	0.906	-2.5
10	1.91k	-1.84k (8.7pF)	0.901	-6.3
20	1.59k	-935 (8.5pF)	0.893	-12
40	1.01k	-502 (7.9pF)	0.826	-23
100	402	-269 (5.9pF)	0.644	-43
200	246	-197 (4.0pF)	0.522	-60

\*Parallel Equivalent

The circuit is optimized for a common mode voltage of 1.4V which can be internally or externally applied. In case of AC-coupling to the baseband pins (1.4V internally generated bias) make sure that the high pass filter corner is not affecting the low frequency components of the baseband signal. Even a small error for low baseband frequencies can result in degraded EVM.

The baseband input offset voltage depends on the source resistance. In case of AC-coupling the 1 sigma offset is about 1.1mV, resulting in about -46.6dBm LO leakage. For shorted baseband pins ( $0\Omega$  source resistance), the LO leakage improves to about -50.1dBm. In case of AC-coupling the LO leakage can be reduced by connecting a resistor in parallel with the baseband inputs, thus lowering baseband input impedance and offset. Further, the low combined baseband input leakage current of 1.3nA in shutdown mode retains the voltage over the coupling capacitors, which helps to settle faster when the part is enabled again. It is recommended to drive the baseband inputs differentially to improve the linearity. When a DAC is used as the signal source, a reconstruction filter should be placed between the DAC output and the LTC5599 baseband inputs to avoid aliasing.

### Internal Gain Trim DACs

Four internal gain trim DACs (one for each baseband pin) are configured as 11-bit each. The usable DAC input value range is integer continuous from 64 to 2047 and 0 for shutdown. The DACs are not intended for baseband signal

## APPLICATIONS INFORMATION

generation but for gain and offset setting only, because there are no reconstruction filters between the DACs and the mixer core, and there is only indirect access between the DAC values and the register settings. The following functions are implemented in this way:

- Coarse digital gain control with 1dB steps
- Fine digital gain control with 0.1dB steps
- Gain-temperature correction
- DC offset adjustment in the I-channel
- DC offset adjustment in the Q-channel
- I/Q gain balance control
- Disable Q-channel
- Continuous variable gain control

### Coarse Digital Gain Control (DG) with 1dB Steps (Register 0x01)

Twenty digital gain positions 1dB apart are implemented by hardwiring a corresponding DAC code for all four DACs. The coarse digital gain is set by writing to the five least-significant bits in register 0x01, see Table 10 and 11. The gain is the highest for code 00000 (code 0 = 0dB, DG = 0) and the lowest for code 10011 (code 19 = -19dB, DG = -19). Note that the gain 0dB set by the digital gain control is not the same as the voltage gain of the part. The remaining 12 codes (decimal 20 to 31) are reserved.

The digital gain in dB equals minus the decimal value written into the 5 least-significant bits of the gain register. The formula relating the modulator gain  $G$  (in V/V) relative to the maximum conversion gain therefore equals:

$$G(V/V) = 10^{(DG/20)}$$

### Fine Digital Gain Control (FDG) with 0.1dB Steps and Gain-Temperature Correction (Register 0x07)

Sixteen digital gain positions about 0.1dB apart can be set directly using the four least-significant bits in register 0x07 combined with bit 2 = 1 in register 0x08 (TEMPCORR = 1). For coarse digital gain settings code 9 and higher some or more subsequent codes of the fine digital gain positions may be the same due to the limited resolution of the 11-bit DACs. The main purpose of these 0.1dB gain steps is

to implement an automatic gain/temperature correction which can be activated by setting TEMPCORR = 1. In that case, the input of the fine digital gain control will be the on-chip thermometer. The on-chip thermometer generates a 4-bit digital code with code 0 corresponding to -30°C and code 15 corresponding to 120°C and 10°C spacing between the codes. The on-chip thermometer output code can be updated continuous (by clearing TEMPUPDT, bit 7 in register 0x01, see Table 10) or can be updated by bringing the external pin TTCK from low to high (and setting TEMPUPDT = 1). In case of continuous update the code will be an asynchronous update whenever the temperature crosses a certain threshold. In some cases it is desired to prevent a gain update to happen in the middle of a data frame. In that case, the gain/temperature update can be synchronized using the TTCK pin for example at the beginning or end of a data frame. The on-chip temperature can be read back by reading register 0x1F (TEMP[3:0]). The decimal value of TEMP[3:0] is given by:

$$\text{TEMP}[3:0] = \text{round}(T/10) + 3$$

with  $T$  the actual on-chip temperature in °C. It's accuracy is about  $\pm 10^\circ\text{C}$ . TEMP[3:0] defaults to 7 after an EN low to high transition with TEMPUPDT = 1. Switching from TEMPUPDT = 0 to TEMPUPDT = 1, TEMP[3:0] indicates the temperature during the last time TTCK went from low to high. Note that the actual on-chip temperature cannot be read if TEMPCORR = 1 or when TEMPUPDT = 1 without toggling TTCK.

### Analog Gain Control

The LTC5599 supports analog control of the conversion gain through a voltage applied to  $V_{\text{CTRL}}$  (pin 1). The gain can be controlled downward from the digital gain setting (DG) programmed in register 0x01. In order to minimize distortion in the RF output signal the AGCTRL bit (bit 6 in register 0x01) should be set to 1. If analog gain control is not used,  $V_{\text{CTRL}}$  should be connected to  $V_{\text{CC}}$  and AGCTRL set to 0; this saves about 2.58mA of supply current. The typical usable gain control range is from 0.9V to 3.3V. Setting  $V_{\text{CTRL}}$  to a voltage lower than  $V_{\text{CC}}$  with AGCTRL = 0 significantly impairs the linearity of the RF output signal and lowers the  $V_{\text{CTRL}}$  response time. A simplified schematic is shown in Figure 1.

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### I/Q DC Offset Adjustment (Registers 0x02 and 0x03) and LO Leakage

Offsets in the I- and Q-channel translates into LO leakage at the RF port. This offset can either be caused by the I/Q modulator or, in case the baseband connections are DC-coupled, applied externally. Registers 0x02 and 0x03 (I-offset and Q-offset) can be set to cancel this offset and hence lower the LO leakage. To adjust the offset in the I-channel, the BBPI DAC is set to a (slightly) different value than the BBMI DAC, introducing an offset. These 8-bit registers defaults are 128 and represents 0 offset. The register value can be set from 1 to 255. The value 0 represents an unsupported code and should not be used. Since the input referred offset depends on the gain the input offset value ( $V_{OS}$ ) can be calculated as:

$$V_{OS} = 1260 / ((3632 \cdot G) / (N_{OS} - 128) - (N_{OS} - 128) / (3632 \cdot G))$$

and  $V_{OS} = 0$  for  $N_{OS} = 128$ .  $G$  represents the gain from Table 3.

**Table 3. Coarse Digital Gain (DG) Register Settings.**

DG (dB)	G(V/V)	DEC	BINARY	HEX
0	1.000	0	00000	0x00
-1	0.891	1	00001	0x01
-2	0.794	2	00010	0x02
-3	0.708	3	00011	0x03
-4	0.631	4	00100	0x04
-5	0.562	5	00101	0x05
-6	0.501	6	00110	0x06
-7	0.447	7	00111	0x07
-8	0.398	8	01000	0x08
-9	0.355	9	01001	0x09
-10	0.316	10	01010	0x0A
-11	0.282	11	01011	0x0B
-12	0.251	12	01100	0x0C
-13	0.224	13	01101	0x0D
-14	0.200	14	01110	0x0E
-15	0.178	15	01111	0x0F
-16	0.158	16	10000	0x10
-17	0.141	17	10001	0x11
-18	0.126	18	10010	0x12
-19	0.112	19	10011	0x13

A positive offset means that the voltage of the positive input terminal (BBPI or BBPQ) is increased relative to the negative input terminal (BBMI or BBMQ).

### I/Q Gain Ratio (Register 0x04) and Side-Band Suppression

The 8-bit I/Q gain ratio register 0x04 controls the ratio of the I-channel mixer conversion gain  $G_I$  and the Q-channel mixer conversion gain  $G_Q$ . Together with the quadrature phase imbalance register 0x05, register 0x04 allows further optimization of the modulator side-band suppression.

The expression relating the gain ratio  $G_I/G_Q$  to the contents of the 8-bit register 0x04, represented by decimal  $N_{IQ}$  and the nominal conversion gain  $G$  equals:

$$20 \log (G_I/G_Q) = 20 \log ((3632 \cdot G - (N_{IQ} - 128)) / (3632 \cdot G + (N_{IQ} - 128))) \text{ (dB)}$$

The step size of the gain ratio trim in dB vs  $N_{IQ}$  is approximately constant for the same digital gain setting. For digital gain setting = -4, for example, the step size is about 7.6m dB. Table 4 lists the gain step size for each digital gain setting that follows from the formula above.

**Table 4. I/Q Gain Ratio Step Size vs Digital Gain Setting**

DG (dB)	G (V/V)	$\Delta G_I/G_Q$ (m dB)
0	1.000	4.8
-1	0.891	5.4
-2	0.794	6.0
-3	0.708	6.8
-4	0.631	7.6
-5	0.562	8.5
-6	0.501	9.6
-7	0.447	10.7
-8	0.398	12.0
-9	0.355	13.5
-10	0.316	15.1
-11	0.282	17.1
-12	0.251	19.2
-13	0.224	21.5
-14	0.200	24.2
-15	0.178	27.3

## APPLICATIONS INFORMATION

**Table 4. I/Q Gain Ratio Step Size vs Digital Gain Setting (continued)**

DG (dB)	G (V/V)	$\Delta G_I/G_Q$ (mdB)
-16	0.158	30.7
-17	0.141	34.6
-18	0.126	39.0
-19	0.112	44.1

The conversion gain of the I-channel and Q-channel are equal for  $N_{IQ} = 128$ . The I-channel gain is larger than the Q-channel gain for  $N_{IQ} > 128$ .

### Disable Q-Channel

If bit 5 in register 0x01 (QDISABLE) is set, the Q-channel is switched off, turning the I/Q modulator into an upconversion mixer. It is recommended to float the BBPQ and BBMQ pins in this mode. The default mode is Q-channel is on (QDISABLE = 0).

### LO Section (Register 0x00)

The internal LO chain consists of a poly-phase filter which generates the I and Q signals for the image-reject double-balanced mixer. The center frequency of the poly-phase filter is set by the lower seven bits of register 0x00. The recommended settings vs LO frequency are given in Table 5 (see the QuikEval™ GUI).

**Table 5. Register 0x00 Setting vs LO Frequency**

REGISTER VALUE			LO FREQUENCY RANGE (MHz)	
DECIMAL	BINARY	HEX	LOWER BOUND	UPPER BOUND
0	0000000	00	N/A	N/A
1	0000001	01	1249.1	1300.0
2	0000010	02	1248.6	1249.0
3	0000011	03	1238.1	1248.5
4	0000100	04	1214.1	1238.0
5	0000101	05	1191.2	1214.0
6	0000110	06	1165.6	1191.1
7	0000111	07	1141.0	1165.5
8	0001000	08	1120.6	1140.9
9	0001001	09	1100.5	1120.5
10	0001010	0A	1069.5	1100.4
11	0001011	0B	1039.6	1069.4
12	0001100	0C	1023.1	1039.5
13	0001101	0D	1007.1	1023.0
14	0001110	0E	988.3	1007.0

**Table 5. Register 0x00 Setting vs LO Frequency (continued)**

REGISTER VALUE			LO FREQUENCY RANGE (MHz)	
DECIMAL	BINARY	HEX	LOWER BOUND	UPPER BOUND
15	0001111	0F	961.8	988.2
16	0010000	10	941.3	961.7
17	0010001	11	921.5	941.2
18	0010010	12	895.2	921.4
19	0010011	13	877.6	895.1
20	0010100	14	863.6	877.5
21	0010101	15	843.2	863.5
22	0010110	16	826.9	843.1
23	0010111	17	807.0	826.8
24	0011000	18	792.3	806.9
25	0011001	19	772.2	792.2
26	0011010	1A	752.7	772.1
27	0011011	1B	734.0	752.6
28	0011100	1C	724.2	739.9
29	0011101	1D	704.6	724.1
30	0011110	1E	688.7	704.5
31	0011111	1F	673.2	688.6
32	0100000	20	655.2	673.1
33	0100001	21	638.1	655.1
34	0100010	22	624.6	638.0
35	0100011	23	611.9	624.5
36	0100100	24	598.4	611.8
37	0100101	25	585.1	598.3
38	0100110	26	573.9	585.0
39	0100111	27	563.1	573.8
40	0101000	28	548.1	563.0
41	0101001	29	538.1	548.0
42	0101010	2A	529.1	538.0
43	0101011	2B	518.5	529.0
44	0101100	2C	507.0	518.4
45	0101101	2D	497.7	506.9
46	0101110	2E	488.0	497.6
47	0101111	2F	471.5	487.9
48	0110000	30	457.7	471.4
49	0110001	31	448.7	457.6
50	0110010	32	437.4	448.6
51	0110011	33	426.6	437.3
52	0110100	34	417.5	426.5
53	0110101	35	407.5	417.4
54	0110110	36	398.0	407.4

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Table 5. Register 0x00 Setting vs LO Frequency (continued)

REGISTER VALUE			LO FREQUENCY RANGE (MHz)	
DECIMAL	BINARY	HEX	LOWER BOUND	UPPER BOUND
55	0110111	37	390.1	397.9
56	0111000	38	382.8	390.0
57	0111001	39	376.6	382.7
58	0111010	3A	369.8	376.5
59	0111011	3B	353.1	369.7
60	0111100	3C	339.0	353.0
61	0111101	3D	332.6	338.9
62	0111110	3E	327.2	332.5
63	0111111	3F	320.6	327.1
64	1000000	40	313.7	320.5
65	1000001	41	309.1	313.6
66	1000010	42	304.5	309.0
67	1000011	43	288.1	304.4
68	1000100	44	278.3	288.0
69	1000101	45	274.2	278.2
70	1000110	46	270.3	274.1
71	1000111	47	266.0	270.2
72	1001000	48	261.9	265.9
73	1001001	49	258.2	261.8
74	1001010	4A	254.1	258.1
75	1001011	4B	243.6	254.0
76	1001100	4C	233.8	243.5
77	1001101	4D	230.8	233.7
78	1001110	4E	228.0	230.7
79	1001111	4F	220.2	227.9
80	1010000	50	212.6	220.1
81	1010001	51	210.0	212.5
82	1010010	52	207.6	209.9
83	1010011	53	202.1	207.5
84	1010100	54	196.2	202.0
85	1010101	55	193.7	196.1
86	1010110	56	191.2	193.6
87	1010111	57	186.6	191.1
88	1011000	58	182.0	186.5
89	1011001	59	179.4	181.9
90	1011010	5A	176.0	179.3
91	1011011	5B	170.1	175.9
92	1011100	5C	165.0	170.0
93	1011101	5D	162.5	164.9
94	1011110	5E	160.0	162.4
95	1011111	5F	156.7	159.9

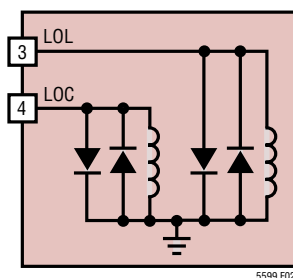
Table 5. Register 0x00 Setting vs LO Frequency (continued)

REGISTER VALUE			LO FREQUENCY RANGE (MHz)	
DECIMAL	BINARY	HEX	LOWER BOUND	UPPER BOUND
96	1100000	60	153.6	156.6
97	1100001	61	151.1	153.5
98	1100010	62	148.6	151.0
99	1100011	63	142.5	148.5
100	1100100	64	139.6	142.4
101	1100101	65	136.5	139.5
102	1100110	66	134.3	136.4
103	1100111	67	131.2	134.2
104	1101000	68	128.1	131.1
105	1101001	69	126.0	128.0
106	1101010	6A	123.8	125.9
107	1101011	6B	121.3	123.7
108	1101100	6C	118.3	121.2
109	1101101	6D	115.7	118.2
110	1101110	6E	113.5	115.6
111	1101111	6F	111.3	113.4
112	1110000	70	109.5	111.2
113	1110001	71	107.6	109.4
114	1110010	72	105.6	107.5
115	1110011	73	103.0	105.5
116	1110100	74	100.3	102.9
117	1110101	75	98.5	100.2
118	1110110	76	96.6	98.4
119	1110111	77	94.7	96.5
120	1111000	78	93.0	94.6
121	1111001	79	30.0	92.9
122	1111010	7A	N/A	N/A
123	1111011	7B	N/A	N/A
124	1111100	7C	N/A	N/A
125	1111101	7D	N/A	N/A
126	1111110	7E	N/A	N/A
127	1111111	7F	N/A	N/A

A simplified circuit schematic of the LOL and LOC interfaces is depicted in Figure 2. The LOL and LOC inputs are not differential LO inputs. They are 50Ω inputs and are intended to be driven with an inductor going to the LOL input and a capacitor to the LOC input. Do not switch the capacitor and inductor, as this will result in very poor performance. For a wideband LO range an inductor value of 39nH and a capacitor value of 15pF (standard LO match)

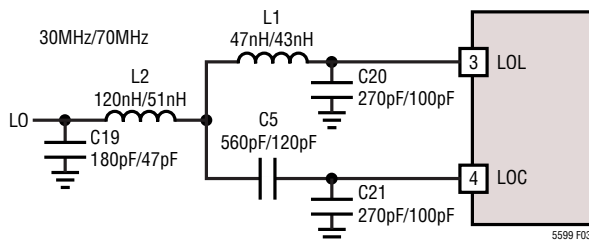
## APPLICATIONS INFORMATION

is recommended at these pins, forming a diplexer circuit with center frequency of 200MHz. This diplexer helps to improve the uncalibrated side-band suppression significantly around 200MHz. Even for LO frequencies far from 200MHz the diplexer performs better than a single-ended LO drive or a differential drive. Due to factory calibration of the poly-phase filter the typical side-band suppression is about 50dBc for frequencies from 100MHz to 700MHz and 45dBc from 700MHz to 1300MHz. For narrow-band applications far from 200MHz it may help to tune the diplexer to a different frequency which can improve the uncalibrated side-band suppression and the gain vs LO drive level. The Typical Performance Characteristics section shows the return loss for a 900MHz match ( $L1 = 8.2\text{nH}$ ,  $C5 = 3.3\text{pF}$ ) and a 1260MHz match ( $L1 = 5.6\text{nH}$ ,  $C5 = 3\text{pF}$ ). To get a performance with the standard 200MHz match equivalent to the 900MHz and 1260MHz match, the LO power should be increased by 1.5dB and 2dB respectively. Register 0x00 values of Table 5 may have to be adjusted as well, in case the standard match is not used.



**Figure 2. Simplified Circuit Schematic for the LOL and LOC Inputs**

Below 100MHz the matching network of Figure 3 can be used. The side-band suppression in that case is largely defined by the diplexer  $L1$ ,  $C5$  and the (temperature dependent) LOL and LOC input impedance. See measured performance in the Typical Performance Characteristics section.



**Figure 3. Impedance Matching Network for LOL and LOC Interfaces Matched at 30MHz/70MHz**

Table 6 lists LOL and LOC port input impedance vs frequency at  $EN = \text{High}$  and  $P_{LO} = 0\text{dBm}$ . The other LO port (LOC or LOL) is terminated in a  $50\Omega$ .

**Table 6. LOL, LOC Port Input Impedance vs Frequency for  $EN = \text{High}$  and  $P_{LO} = 0\text{dBm}$  (Other LO Port Terminated with  $50\Omega$  to Ground)**

FREQ (MHz)	REG 0x00	LOL/LOC PORT IMPEDANCE ( $\Omega$ )		REFL COEFFICIENT	
		REAL*	IMAG* (IND)	MAG	ANGLE
20	79	7.9	24.3 (194nH)	0.750	175
30	79	9.1	19.0 (101nH)	0.743	172
40	79	10.8	17.4 (69nH)	0.732	169
50	79	13.0	17.6 (56nH)	0.716	165
60	79	15.7	18.9 (50nH)	0.693	162
70	79	18.6	21.4 (49nH)	0.661	158
80	79	21.6	25.0 (50nH)	0.618	154
90	79	24.4	30.3 (54nH)	0.564	151
100	75	27.0	38.3 (61nH)	0.497	148
110	70	29.0	51.4 (74nH)	0.419	146
120	6C	30.3	76.1 (101nH)	0.338	149
130	68	32.3	109.3 (134nH)	0.276	150
140	64	34.3	121.6 (138nH)	0.247	148
150	62	36.2	119.4 (127nH)	0.234	142
160	5E	37.4	149.1 (148nH)	0.201	143
170	5C	37.1	357.5 (335nH)	0.160	162
180	59	39.6	188.6 (167nH)	0.164	141
190	57	41.4	192.0 (161nH)	0.150	135
200	54	40.7	418.6 (333nH)	0.116	156

\*Parallel Equivalent

The circuit schematic of the demo board is shown in Figure 13.

### I/Q Phase Balance Adjustment Register 0x05 and Side-Band Suppression

Ideally the I-channel LO phase is exactly  $90^\circ$  ahead of the Q-channel LO phase, so called quadrature. In practice however, the I/Q phase difference differs from exact quadrature by a small error due to component parameter variations and harmonic content in the LO signal (see below).

The I/Q phase imbalance register (0x05) allows adjustment of the I/Q phase shift to compensate for such errors. Together with gain ratio register 0x04, it can thus be used to optimize the side-band suppression of the modulator.

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Register 0x05 contains two parts (see Table 11); the five least significant bits IQPHF realize a fine phase adjustment, while the three most significant bits IQPHE are used for coarse adjustments. The fine phase adjustment realized by IQPHF can be approximated as:

$$\phi_{IQ} = -((N_{ph} - 16)/15) \cdot \ln(f_{LO}/50) \text{ (degrees)}$$

for  $30\text{MHz} < f_{LO} < 1300\text{MHz}$

where  $N_{ph}$  is the decimal value of IQPHF and  $f_{LO}$  is the frequency of the LO signal in MHz. A positive value for  $\phi_{IQ}$  means that the I-channel LO phase is more than  $90^\circ$  ahead of the Q-channel LO phase. Notice from the expression that the phase adjustment range and resolution are coupled, and dependent on the LO frequency. At low LO frequencies the the smallest adjustment range and highest resolution is achieved, while high LO frequencies exhibit the largest range and lowest resolution.

The extension bits IQPHE provide a larger phase adjustment range, particularly useful at lower LO frequencies, and overcome another trade-off; between phase adjustment range and the maximum center frequency of the poly-phase filter. The latter trade-off is due to the fact that the capacitances in the I-channel,  $C_{ppI}$ , and Q-channel,  $C_{ppQ}$ , of the poly-phase filter control both these parameters. Their difference sets the phase shift, while their sum determines the center frequency of the filter.

The extension bits IQPHE introduce a large phase offset in addition to the fine adjustment realized by the IQPHF bits. The sign of this large offset can be positive or negative, controlled by IQPHSIGN (bit 7 in register 0x00). Including these bits, the total phase shift from quadrature can be expressed as:

$$\phi_{IQ} = -(M_{PH}/15) \cdot \ln(f_{LO}/50) \text{ (degrees) with}$$

$$M_{PH} = N_{COARSE} + N_{PH} - 16 \text{ and}$$

$$N_{COARSE} = 32 \cdot (-1)^{IQPHSIGN} + 1 \cdot N_{EXT}$$

where  $N_{ext}$  equals the decimal value of the IQPHE bits. The valid range of values for  $(N_{ph} - 16)$  is thus expanded from  $\{-16, -15, \dots, +15\}$  to  $\{-240, -239, \dots, +239\}$ . Table 9 in the Appendix lists all the possible combinations. The coding ranges for IQPHSIGN = 0 and IQPHSIGN = 1 overlap between  $M_{ph} = -16$  and  $M_{ph} = +15$ , such that IQPHSIGN only needs to be changed for larger phase shifts.

As a side effect, the extension bits slightly detune the center frequency of the poly-phase filter, after crossing the boundary to a new  $N_{COARSE}$  value. This can be observed as a large step in the actual phase shift. A solution for this is to decrease the value in the frequency register 0x00 (increase the poly-phase filter center frequency) at the  $N_{COARSE}$  value boundaries. The result is a smooth phase adjustment. In the demo board QuikEval GUI, this LO frequency register adjustment is automatically taken care of.

Whenever the poly-phase filter center frequency is adjusted to improve the smoothness of the phase adjustment, it is recommended to manually program the LO port impedance match using the CLOO bits in register 0x06. By default, changing the filter center frequency also automatically adjusts the matching of the LO port (when CLOEN, bit 4 in register 0x06 is set). However, since the LO carrier frequency does not change, automatic adjustment of the LO match is undesirable in this case; it may add another large step to the phase adjustment. Instead, the LO match should remain unchanged while the filter center frequency is adjusted. This can be achieved as follows. First, the current LO matching configuration is read from the CLO bits in register 0x1D, and written to the CLOO override bits in register 0x06. Subsequently, the CLOEN bit (bit 4, register 0x06) is cleared to disable automatic LO match adjustment. As a result the center frequency can be adjusted in register 0x00 without changing the LO match.

At 100MHz the maximum phase shift is about  $\pm 9.8^\circ$ , while at 1GHz it is about  $\pm 3^\circ$ . The extension bits are not useful above 988.2MHz since the poly-phase center frequency register 0x00 value cannot be adjusted low enough to ensure a smooth transition to a new  $N_{COARSE}$  value.

### Square Wave LO Drive

Harmonic content of the LO signal adversely affects quadrature phase error and gain accuracy, whenever a poly-phase filter is used for quadrature generation. The LTC5599 can correct for phase and gain errors due to harmonics in the LO carrier (e.g. in a square wave) by setting appropriate values in the I/Q gain and I/Q phase registers. Such adjustments are typically needed when the 3rd-order harmonic of the LO signal exceeds the desirable side-band suppression minus 13dB. Although the poly-phase filter is less sensitive to the second harmonic content of the LO

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carrier, it's influence can still be significant. For  $-15\text{dBc}$  second harmonic content, the side-band suppression can degrade to  $-45\text{dBc}$ ; for  $-20\text{dBc}$  it is  $-54\text{dBc}$ , assuming no I/Q gain and phase adjustments are made.

### RF Output

After upconversion, the RF outputs of the I and Q mixers are combined. An on-chip buffer performs internal differential to single-ended conversion, while transforming the output signal to  $50\Omega$  as shown in Figure 4.

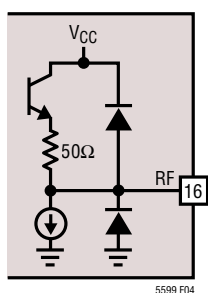


Figure 4. Simplified Circuit Schematic for the RF Output Port

Table 7 shows the RF port output impedance vs frequency and digital gain setting for EN = High.

Table 7. RF Output Impedance vs Frequency and Digital Gain Setting (DG) for EN = High

FREQUENCY (MHz)	DG (dB)	OUTPUT IMPEDANCE ( $\Omega$ )		REFL COEFFICIENT	
		REAL*	IMAG* (CAP)	MAG	ANGLE
30	0	59	-413 (12.8pF)	0.104	-43
30	-12	61	-465 (11.4pF)	0.114	-35
30	-16	64	-529 (10.0pF)	0.133	-27
30	-18	69	-623 (8.5pF)	0.166	-19
30	-19	83	-902 (5.9pF)	0.249	-10
50	0	56	-671 (4.7pF)	0.068	-38
50	-12	58	-762 (4.2pF)	0.082	-27
50	-16	61	-859 (3.7pF)	0.107	-19
50	-18	67	-972 (3.3pF)	0.146	-13
50	-19	81	-1.21k (2.6pF)	0.239	-8
100	0	55	-1.08k (1.5pF)	0.050	-30
100	-12	57	-1.32k (1.2pF)	0.066	-19
100	-16	60	-1.55k (1.0pF)	0.096	-12
100	-18	66	-1.75k (0.91pF)	0.142	-8
100	-19	82	-1.98k (0.80pF)	0.246	-5
600	0	54	-1.35k (0.20pF)	0.040	-30
600	-12	56	-1.75k (0.15pF)	0.057	-16

Table 7. RF Output Impedance vs Frequency and Digital Gain Setting (DG) for EN = High (continued)

FREQUENCY (MHz)	DG (dB)	OUTPUT IMPEDANCE ( $\Omega$ )		REFL COEFFICIENT	
		REAL*	IMAG* (CAP)	MAG	ANGLE
600	-16	58	-1.77k (0.15pF)	0.078	-12
600	-18	62	-1.44k (0.18pF)	0.109	-11
600	-19	77	-680 (0.39pF)	0.217	-14
1300	0	48	-802 (0.15pF)	0.035	-119
1300	-12	51	-807 (0.15pF)	0.034	-68
1300	-16	55	-709 (0.17pF)	0.059	-41
1300	-18	59	-526 (0.23pF)	0.098	-35
1300	-19	73	-280 (0.44pF)	0.215	-36

\*Parallel Equivalent

The RF port output impedance for EN = Low is given in Table 8.

Table 8. RF Output Impedance vs Frequency for EN = Low

FREQUENCY (MHz)	OUTPUT IMPEDANCE ( $\Omega$ )		REFL COEFFICIENT	
	REAL*	IMAG* (CAP)	MAG	ANGLE
30	16.1k	-7.76k (0.68pF)	0.994	-0.7
40	16.2k	-5.24k (0.76pF)	0.994	-1.1
50	15.7k	-3.96k (0.80pF)	0.994	-1.4
60	16.5k	-3.18k (0.83pF)	0.994	-1.8
70	16.8k	-2.66k (0.86pF)	0.994	-2.2
80	16.4k	-2.29k (0.87pF)	0.994	-2.5
90	17.1k	-2.01k (0.88pF)	0.994	-2.9
100	17.9k	-1.79k (0.89pF)	0.994	-3.2
200	14.7k	-856 (0.93pF)	0.993	-6.7
250	11.1k	-679 (0.94pF)	0.991	-8.4
300	8.55k	-563 (0.94pF)	0.988	-10
350	7.97k	-481 (0.94pF)	0.988	-12
400	6.42k	-420 (0.95pF)	0.985	-14
450	5.27k	-373 (0.95pF)	0.982	-15
500	4.26k	-336 (0.95pF)	0.977	-17
600	3.05k	-281 (0.94pF)	0.969	-20
700	2.32k	-241 (0.94pF)	0.959	-23
800	1.85k	-211 (0.94pF)	0.950	-27
900	1.54k	-188 (0.94pF)	0.941	-30
1000	1.30k	-169 (0.94pF)	0.932	-33
1100	1.12k	-154 (0.94pF)	0.923	-36
1200	991	-141 (0.94pF)	0.914	-39
1300	881	-129 (0.95pF)	0.906	-42

\*Parallel Equivalent

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For  $V_{CC} = 3.3V$  and  $EN = High$  the RF pin voltage is about 1.68V. For  $V_{CC} = 3.3V$  and  $EN = Low$  the RF pin voltage is about 3.1V.

### Enable Interface

Figure 5 shows a simplified schematic of the EN pin interface. The voltage necessary to turn on the LTC5599 is 1.1V. To disable (shut down) the chip, the enable voltage must be below 0.2V.

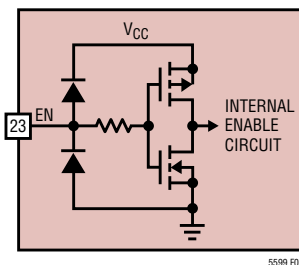


Figure 5. Simplified Circuit Schematic of the EN interface

### SERIAL PORT

The SPI-compatible serial port provides control and monitoring functionality.

### Communication Sequence

The serial bus is comprised of CSB, SCLK, SDI and SDO. Data transfers to the part are accomplished by the

serial bus master device first taking CSB low to enable the LTC5599's port. Input data applied on SDI is clocked on the rising edge of SCLK, with all transfers MSB first. The communication burst is terminated by the serial bus master returning CSB high. See Figure 6 for details.

Data is read from the part during a communication burst using SDO. Readback may be multidrop (more than one LTC5599 connected in parallel on the serial bus), as SDO is high impedance (Hi-Z) when  $CSB = 1$ , or when data is not being read from the part. *If the LTC5599 is not used in a multidrop configuration, or if the serial port master is not capable of setting the SDO line level between read sequences, it is recommended to attach a resistor between SDO and  $V_{CC\_L}$  to ensure the line returns to  $V_{CC\_L}$  during Hi-Z states. The resistor value should be large enough to ensure that the SDO output current does not exceed 10mA. See Figure 7 for details.*

### Single Byte Transfers

The serial port is arranged as a simple memory map, with status and control available in 9 read/write and 23 read-only byte-wide registers. All data bursts are comprised of at least two bytes. The 7 most significant bits of the first byte are the register address, with an LSB of 1 indicating a read from the part, and LSB of 0 indicating a write to the part. The subsequent byte, or bytes, is data from/to the

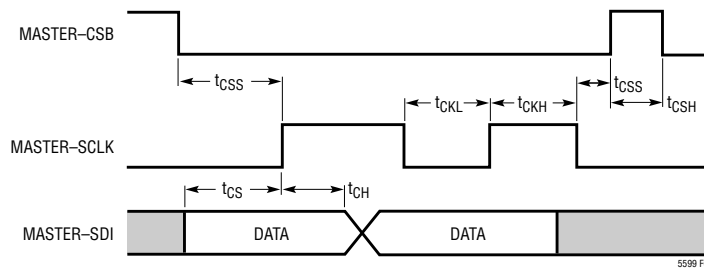


Figure 6. Serial Port Write Timing Diagram

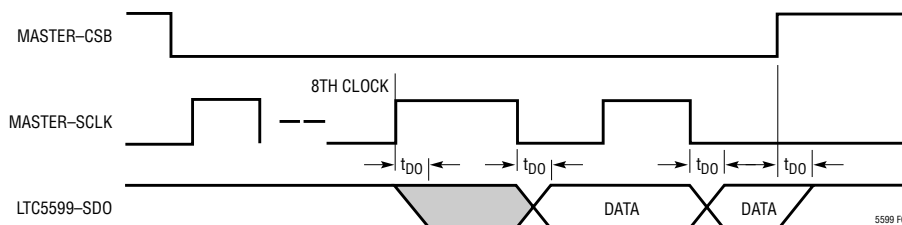


Figure 7. Serial Port Read Timing Diagram

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specified register address. See Figure 8 for an example of a detailed write sequence, and Figure 9 for a read sequence.

Figure 10 shows an example of two write communication bursts. The first byte of the first burst sent from the serial bus master on SDI contains the destination register address (Addr0) and an LSB of 0 indicating a write. The next byte is the data intended for the register at address Addr0. CSB is then taken high to terminate the transfer. The first

byte of the second burst contains the destination register address (Addr1) and an LSB indicating a write. The next byte on SDI is the data intended for the register at address Addr1. CSB is then taken high to terminate the transfer.

Note that the written data is transferred to the internal register at the falling edge of the 16<sup>th</sup> clock cycle (parallel load).

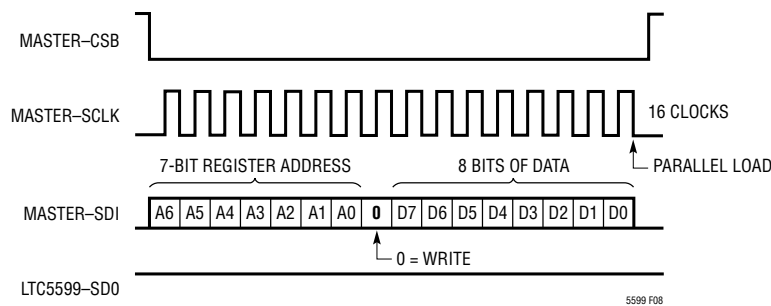


Figure 8. Serial Port Write Sequence

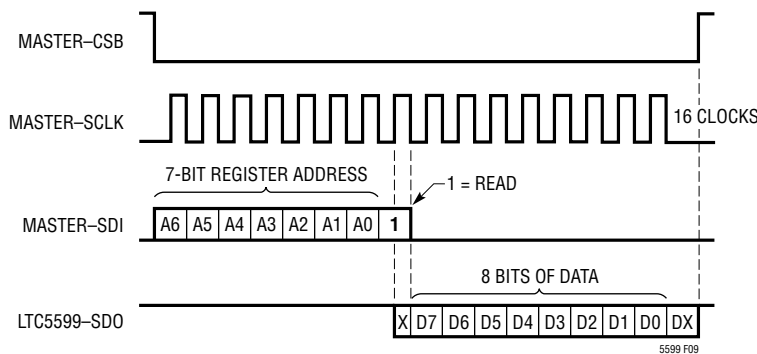


Figure 9. Serial Port Read Sequence

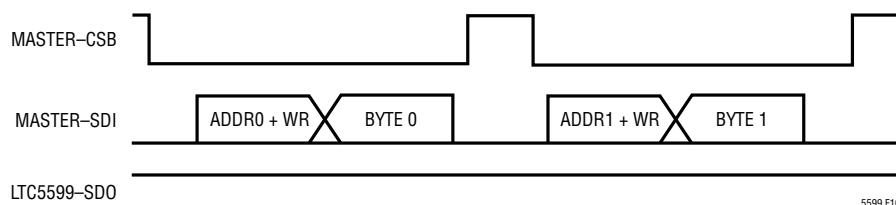


Figure 10. Serial Port Single Byte Writes

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### Multiple Byte Transfers

More efficient data transfer of multiple bytes is accomplished by using the LTC5599's register address auto-increment feature as shown in Figure 11. The serial port master sends the destination register address in the first byte and its data in the second byte as before, but continues sending bytes destined for subsequent registers. Byte 1's address is  $\text{Addr0}+1$ , Byte 2's address is  $\text{Addr0}+2$ , and so on. If the register address pointer attempts to increment past 31 (0x1F), it is automatically reset to 0.

An example of an auto-increment read from the part is shown in Figure 12. The first byte of the burst sent from the serial bus master on SDI contains the destination register address ( $\text{Addr0}$ ) and an LSB of 1 indicating a read. Once the LTC5599 detects a read burst, it takes SDO out of the Hi-Z condition and sends data bytes sequentially, beginning with data from register  $\text{Addr0}$ . The part ignores all other data on SDI until the end of the burst.

### Multidrop Configuration

Several LTC5599s may share the serial bus. In this multidrop configuration, SCLK, SDI, and SDO are common between all parts. The serial bus master must use a separate CSB for each LTC5599 and ensure that only one device has CSB asserted at any time. It is recommended to attach a high value resistor to SDO to ensure the line returns to a known level ( $V_{CC\_L}$ ) during Hi-Z states.

### Serial Port Registers

The memory map of the LTC5599 may be found in the Appendix in Table 10, with detailed bit descriptions found in Table 11. The register address shown in hexadecimal format under the ADDR column is used to specify each register. Each register is denoted as either read-only (R) or read-write (R/W). The register's default value on device power-up or after a reset (bit 3, register 0x08, SRESET) is shown at the right.

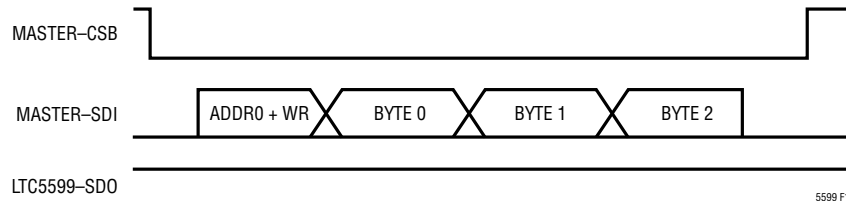


Figure 11. Serial Port Auto-Increment Write

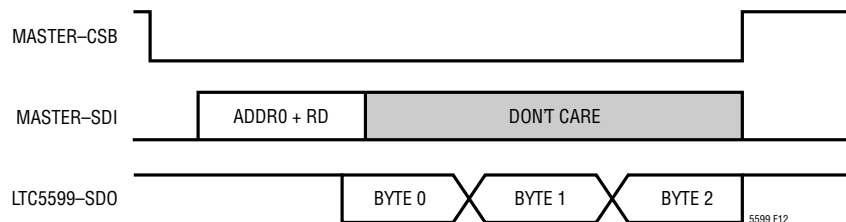


Figure 12. Serial Port Auto-Increment Read

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### SPI Signal Levels

The SPI bus supports signal levels from a digital  $V_{CC\_L}$  from 1.2V to 3.6V. The  $CSB = 1.2V$  condition creates an additional static input sleep current of  $0.2\mu A$ . For  $CSB = 1.8V$  the extra sleep current can be neglected.

### Evaluation Board

Figure 13 shows the evaluation board schematic. A good ground connection is required for the exposed pad. If this

is not done properly, the RF performance will degrade. Figures 14 and 15 show the component side and bottom side of the evaluation board.

Ferrite bead FB1 limits the supply voltage ramping speed in case  $V_{CC}$  is abruptly connected to a voltage source. In the application, limit the  $V_{CC}$  ramp speed to a maximum of  $1V/\mu s$ .

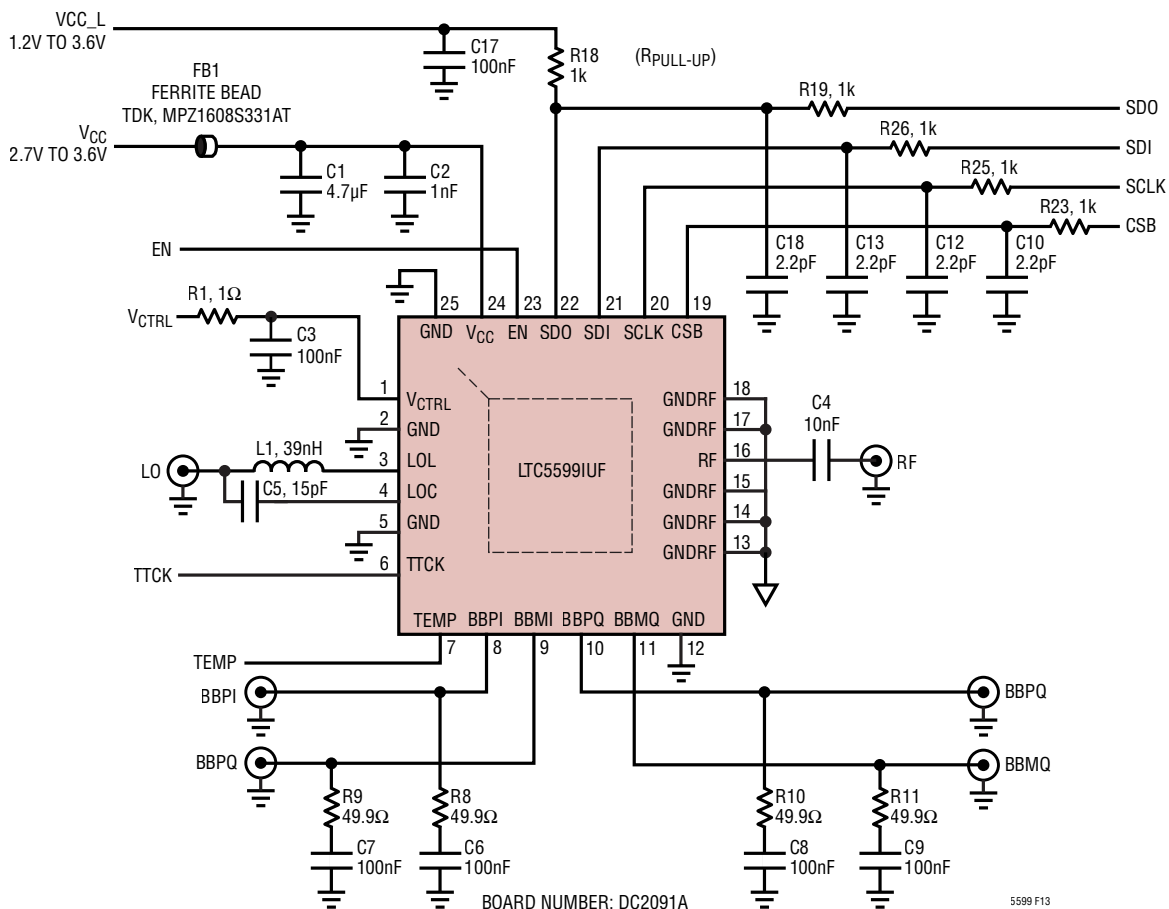


Figure 13. Evaluation Circuit Schematic



## APPENDIX

### Phase Shift Register (0x05) Map

This appendix summarizes the detailed value assignments for the phase shift register, including the extension bits and sign bit (bit 7 in register 0x00).

**Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00)**

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
-240	-224	0	011100000
-239	-224	1	011100001
-238	-224	2	011100010
-237	-224	3	011100011
-236	-224	4	011100100
-235	-224	5	011100101
-234	-224	6	011100110
-233	-224	7	011100111
-232	-224	8	011101000
-231	-224	9	011101001
-230	-224	10	011101010
-229	-224	11	011101011
-228	-224	12	011101100
-227	-224	13	011101101
-226	-224	14	011101110
-225	-224	15	011101111
-224	-224	16	011110000
-223	-224	17	011110001
-222	-224	18	011110010
-221	-224	19	011110011
-220	-224	20	011110100
-219	-224	21	011110101
-218	-224	22	011110110
-217	-224	23	011110111
-216	-224	24	011111000
-215	-224	25	011111001
-214	-224	26	011111010
-213	-224	27	011111011
-212	-224	28	011111100
-211	-224	29	011111101
-210	-224	30	011111110
-209	-224	31	011111111
-208	-192	0	011000000
-207	-192	1	011000001
-206	-192	2	011000010
-205	-192	3	011000011

**Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)**

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
-204	-192	4	011000100
-203	-192	5	011000101
-202	-192	6	011000110
-201	-192	7	011000111
-200	-192	8	011001000
-199	-192	9	011001001
-198	-192	10	011001010
-197	-192	11	011001011
-196	-192	12	011001100
-195	-192	13	011001101
-194	-192	14	011001110
-193	-192	15	011001111
-192	-192	16	011010000
-191	-192	17	011010001
-190	-192	18	011010010
-189	-192	19	011010011
-188	-192	20	011010100
-187	-192	21	011010101
-186	-192	22	011010110
-185	-192	23	011010111
-184	-192	24	011011000
-183	-192	25	011011001
-182	-192	26	011011010
-181	-192	27	011011011
-180	-192	28	011011100
-179	-192	29	011011101
-178	-192	30	011011110
-177	-192	31	011011111
-176	-160	0	010100000
-175	-160	1	010100001
-174	-160	2	010100010
-173	-160	3	010100011
-172	-160	4	010100100
-171	-160	5	010100101
-170	-160	6	010100110
-169	-160	7	010100111
-168	-160	8	010101000
-167	-160	9	010101001
-166	-160	10	010101010
-165	-160	11	010101011
-164	-160	12	010101100

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Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
-163	-160	13	010101101
-162	-160	14	010101110
-161	-160	15	010101111
-160	-160	16	010110000
-159	-160	17	010110001
-158	-160	18	010110010
-157	-160	19	010110011
-156	-160	20	010110100
-155	-160	21	010110101
-154	-160	22	010110110
-153	-160	23	010110111
-152	-160	24	010111000
-151	-160	25	010111001
-150	-160	26	010111010
-149	-160	27	010111011
-148	-160	28	010111100
-147	-160	29	010111101
-146	-160	30	010111110
-145	-160	31	010111111
-144	-128	0	010000000
-143	-128	1	010000001
-142	-128	2	010000010
-141	-128	3	010000011
-140	-128	4	010000100
-139	-128	5	010000101
-138	-128	6	010000110
-137	-128	7	010000111
-136	-128	8	010001000
-135	-128	9	010001001
-134	-128	10	010001010
-133	-128	11	010001011
-132	-128	12	010001100
-131	-128	13	010001101
-130	-128	14	010001110
-129	-128	15	010001111
-128	-128	16	010010000
-127	-128	17	010010001
-126	-128	18	010010010
-125	-128	19	010010011
-124	-128	20	010010100
-123	-128	21	010010101

Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
-122	-128	22	010010110
-121	-128	23	010010111
-120	-128	24	010011000
-119	-128	25	010011001
-118	-128	26	010011010
-117	-128	27	010011011
-116	-128	28	010011100
-115	-128	29	010011101
-114	-128	30	010011110
-113	-128	31	010011111
-112	-96	0	001100000
-111	-96	1	001100001
-110	-96	2	001100010
-109	-96	3	001100011
-108	-96	4	001100100
-107	-96	5	001100101
-106	-96	6	001100110
-105	-96	7	001100111
-104	-96	8	001101000
-103	-96	9	001101001
-102	-96	10	001101010
-101	-96	11	001101011
-100	-96	12	001101100
-99	-96	13	001101101
-98	-96	14	001101110
-97	-96	15	001101111
-96	-96	16	001110000
-95	-96	17	001110001
-94	-96	18	001110010
-93	-96	19	001110011
-92	-96	20	001110100
-91	-96	21	001110101
-90	-96	22	001110110
-89	-96	23	001110111
-88	-96	24	001111000
-87	-96	25	001111001
-86	-96	26	001111010
-85	-96	27	001111011
-84	-96	28	001111100
-83	-96	29	001111101
-82	-96	30	001111110

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Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
-81	-96	31	001111111
-80	-64	0	001000000
-79	-64	1	001000001
-78	-64	2	001000010
-77	-64	3	001000011
-76	-64	4	001000100
-75	-64	5	001000101
-74	-64	6	001000110
-73	-64	7	001000111
-72	-64	8	001001000
-71	-64	9	001001001
-70	-64	10	001001010
-69	-64	11	001001011
-68	-64	12	001001100
-67	-64	13	001001101
-66	-64	14	001001110
-65	-64	15	001001111
-64	-64	16	001010000
-63	-64	17	001010001
-62	-64	18	001010010
-61	-64	19	001010011
-60	-64	20	001010100
-59	-64	21	001010101
-58	-64	22	001010110
-57	-64	23	001010111
-56	-64	24	001011000
-55	-64	25	001011001
-54	-64	26	001011010
-53	-64	27	001011011
-52	-64	28	001011100
-51	-64	29	001011101
-50	-64	30	001011110
-49	-64	31	001011111
-48	-32	0	000100000
-47	-32	1	000100001
-46	-32	2	000100010
-45	-32	3	000100011
-44	-32	4	000100100
-43	-32	5	000100101
-42	-32	6	000100110
-41	-32	7	000100111

Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
-40	-32	8	000101000
-39	-32	9	000101001
-38	-32	10	000101010
-37	-32	11	000101011
-36	-32	12	000101100
-35	-32	13	000101101
-34	-32	14	000101110
-33	-32	15	000101111
-32	-32	16	000110000
-31	-32	17	000110001
-30	-32	18	000110010
-29	-32	19	000110011
-28	-32	20	000110100
-27	-32	21	000110101
-26	-32	22	000110110
-25	-32	23	000110111
-24	-32	24	000111000
-23	-32	25	000111001
-22	-32	26	000111010
-21	-32	27	000111011
-20	-32	28	000111100
-19	-32	29	000111101
-18	-32	30	000111110
-17	-32	31	000111111
-16	0	0	x00000000
-15	0	1	x00000001
-14	0	2	x00000010
-13	0	3	x00000011
-12	0	4	x00000100
-11	0	5	x00000101
-10	0	6	x00000110
-9	0	7	x00000111
-8	0	8	x00001000
-7	0	9	x00001001
-6	0	10	x00001010
-5	0	11	x00001011
-4	0	12	x00001100
-3	0	13	x00001101
-2	0	14	x00001110
-1	0	15	x00001111
0	0	16	x00010000

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Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
1	0	17	x00010001
2	0	18	x00010010
3	0	19	x00010011
4	0	20	x00010100
5	0	21	x00010101
6	0	22	x00010110
7	0	23	x00010111
8	0	24	x00011000
9	0	25	x00011001
10	0	26	x00011010
11	0	27	x00011011
12	0	28	x00011100
13	0	29	x00011101
14	0	30	x00011110
15	0	31	x00011111
16	32	0	10010000
17	32	1	10010001
18	32	2	100100010
19	32	3	100100011
20	32	4	100100100
21	32	5	100100101
22	32	6	100100110
23	32	7	100100111
24	32	8	100101000
25	32	9	100101001
26	32	10	100101010
27	32	11	100101011
28	32	12	100101100
29	32	13	100101101
30	32	14	100101110
31	32	15	100101111
32	32	16	100110000
33	32	17	100110001
34	32	18	100110010
35	32	19	100110011
36	32	20	100110100
37	32	21	100110101
38	32	22	100110110
39	32	23	100110111
40	32	24	100111000
41	32	25	100111001

Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
42	32	26	100111010
43	32	27	100111011
44	32	28	100111100
45	32	29	100111101
46	32	30	100111110
47	32	31	100111111
48	64	0	101000000
49	64	1	101000001
50	64	2	101000010
51	64	3	101000011
52	64	4	101000100
53	64	5	101000101
54	64	6	101000110
55	64	7	101000111
56	64	8	101001000
57	64	9	101001001
58	64	10	101001010
59	64	11	101001011
60	64	12	101001100
61	64	13	101001101
62	64	14	101001110
63	64	15	101001111
64	64	16	101010000
65	64	17	101010001
66	64	18	101010010
67	64	19	101010011
68	64	20	101010100
69	64	21	101010101
70	64	22	101010110
71	64	23	101010111
72	64	24	101011000
73	64	25	101011001
74	64	26	101011010
75	64	27	101011011
76	64	28	101011100
77	64	29	101011101
78	64	30	101011110
79	64	31	101011111
80	96	0	101100000
81	96	1	101100001
82	96	2	101100010

## APPENDIX

Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
83	96	3	101100011
84	96	4	101100100
85	96	5	101100101
86	96	6	101100110
87	96	7	101100111
88	96	8	101101000
89	96	9	101101001
90	96	10	101101010
91	96	11	101101011
92	96	12	101101100
93	96	13	101101101
94	96	14	101101110
95	96	15	101101111
96	96	16	101110000
97	96	17	101110001
98	96	18	101110010
99	96	19	101110011
100	96	20	101110100
101	96	21	101110101
102	96	22	101110110
103	96	23	101110111
104	96	24	101111000
105	96	25	101111001
106	96	26	101111010
107	96	27	101111011
108	96	28	101111100
109	96	29	101111101
110	96	30	101111110
111	96	31	101111111
112	128	0	110000000
113	128	1	110000001
114	128	2	110000010
115	128	3	110000011
116	128	4	110000100
117	128	5	110000101
118	128	6	110000110
119	128	7	110000111
120	128	8	110001000
121	128	9	110001001
122	128	10	110001010
123	128	11	110001011

Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
124	128	12	110001100
125	128	13	110001101
126	128	14	110001110
127	128	15	110001111
128	128	16	110010000
129	128	17	110010001
130	128	18	110010010
131	128	19	110010011
132	128	20	110010100
133	128	21	110010101
134	128	22	110010110
135	128	23	110010111
136	128	24	110011000
137	128	25	110011001
138	128	26	110011010
139	128	27	110011011
140	128	28	110011100
141	128	29	110011101
142	128	30	110011110
143	128	31	110011111
144	160	0	110100000
145	160	1	110100001
146	160	2	110100010
147	160	3	110100011
148	160	4	110100100
149	160	5	110100101
150	160	6	110100110
151	160	7	110100111
152	160	8	110101000
153	160	9	110101001
154	160	10	110101010
155	160	11	110101011
156	160	12	110101100
157	160	13	110101101
158	160	14	110101110
159	160	15	110101111
160	160	16	110110000
161	160	17	110110001
162	160	18	110110010
163	160	19	110110011
164	160	20	110110100

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Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
165	160	21	110110101
166	160	22	110110110
167	160	23	110110111
168	160	24	110111000
169	160	25	110111001
170	160	26	110111010
171	160	27	110111011
172	160	28	110111100
173	160	29	110111101
174	160	30	110111110
175	160	31	110111111
176	192	0	111000000
177	192	1	111000001
178	192	2	111000010
179	192	3	111000011
180	192	4	111000100
181	192	5	111000101
182	192	6	111000110
183	192	7	111000111
184	192	8	111001000
185	192	9	111001001
186	192	10	111001010
187	192	11	111001011
188	192	12	111001100
189	192	13	111001101
190	192	14	111001110
191	192	15	111001111
192	192	16	111010000
193	192	17	111010001
194	192	18	111010010
195	192	19	111010011
196	192	20	111000100
197	192	21	111010101
198	192	22	111010110
199	192	23	111010111
200	192	24	111011000
201	192	25	111011001
202	192	26	111011010
203	192	27	111011011
204	192	28	111011100

Table 9. Register 0x05 Phase Shift Register Settings, Including the Extension Bits and Sign Bit (Bit 7 in Register 0x00) (continued)

M <sub>PH</sub>	N <sub>COARSE</sub>	N <sub>PH</sub>	B <sub>PH</sub>
205	192	29	111011101
206	192	30	111011110
207	192	31	111011111
208	224	0	111100000
209	224	1	111100001
210	224	2	111100010
211	224	3	111100011
212	224	4	111100100
213	224	5	111100101
214	224	6	111100110
215	224	7	111100111
216	224	8	111101000
217	224	9	111101001
218	224	10	111101010
219	224	11	111101011
220	224	12	111101100
221	224	13	111101101
222	224	14	111101110
223	224	15	111101111
224	224	16	111110000
225	224	17	111110001
226	224	18	111110010
227	224	19	111110011
228	224	20	111110100
229	224	21	111110101
230	224	22	111110110
231	224	23	111110111
232	224	24	111111000
233	224	25	111111001
234	224	26	111111010
235	224	27	111111011
236	224	28	111111100
237	224	29	111111101
238	224	30	111111110
239	224	31	111111111

## APPENDIX

Table 10. Serial Port Register Contents

ADDR	MSB	[6]	[5]	[4]	[3]	[2]	[1]	LSB	R/W	DEFAULT
0x00	IQPHSIGN	FREQ[6]	FREQ[5]	FREQ[4]	FREQ[3]	FREQ[2]	FREQ[1]	FREQ[0]	R/W	0x2E
0x01	TEMPUPDT	AGCTRL	QDISABLE	GAIN[4]	GAIN[3]	GAIN[2]	GAIN[1]	GAIN[0]	R/W	0x84
0x02	OFFSETI[7]	OFFSETI[6]	OFFSETI[5]	OFFSETI[4]	OFFSETI[3]	OFFSETI[2]	OFFSETI[1]	OFFSETI[0]	R/W	0x80
0x03	OFFSETQ[7]	OFFSETQ[6]	OFFSETQ[5]	OFFSETQ[4]	OFFSETQ[3]	OFFSETQ[2]	OFFSETQ[1]	OFFSETQ[0]	R/W	0x80
0x04	IQGR[7]	IQGR[6]	IQGR[5]	IQGR[4]	IQGR[3]	IQGR[2]	IQGR[1]	IQGR[0]	R/W	0x80
0x05	IQPHE[2]	IQPHE[1]	IQPHE[0]	IQPHF[4]	IQPHF[3]	IQPHF[2]	IQPHF[1]	IQPHF[0]	R/W	0x10
0x06	*	*	*	CLOEN	CLOO[3]	CLOO[2]	CLOO[1]	CLOO[0]	R/W	0x50
0x07	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	GAINF[3]	GAINF[2]	GAINF[1]	GAINF[0]	R/W	0x06
0x08	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	SRESET	TEMPCORR	THERMINP	*	R/W	0x00
0x09	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	R	0x00
0x0A	CHIPID[7]	CHIPID[6]	CHIPID[5]	CHIPID[4]	CHIPID[3]	CHIPID[2]	CHIPID[1]	CHIPID[0]	R	0x01
0x0B	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	FUSE[3]	FUSE[2]	FUSE[1]	FUSE[0]	R	0x0X
0x0C	0 <sup>†</sup>	0 <sup>†</sup>	CPPP0[5]	CPPP0[4]	CPPP0[3]	CPPP0[2]	CPPP0[1]	CPPP0[0]	R	0xXX
0x0D	0 <sup>†</sup>	CPPP1[6]	CPPP1[5]	CPPP1[4]	CPPP1[3]	CPPP1[2]	CPPP1[1]	CPPP1[0]	R	0x0X
0x0E	0 <sup>†</sup>	0 <sup>†</sup>	CPPM0[5]	CPPM0[4]	CPPM0[3]	CPPM0[2]	CPPM0[1]	CPPM0[0]	R	0xXX
0x0F	0 <sup>†</sup>	CPPM1[6]	CPPM1[5]	CPPM1[4]	CPPM1[3]	CPPM1[2]	CPPM1[1]	CPPM1[0]	R	0x0X
0x10	0 <sup>†</sup>	GPI0[6]	GPI0[5]	GPI0[4]	GPI0[3]	GPI0[2]	GPI0[1]	GPI0[0]	R	0x08
0x11	GPI1[7]	GPI1[6]	GPI1[5]	GPI1[4]	GPI1[3]	GPI1[2]	GPI1[1]	GPI1[0]	R	0xFF
0x12	0 <sup>†</sup>	GPI2[6]	GPI2[5]	GPI2[4]	GPI2[3]	GPI2[2]	GPI2[1]	GPI2[0]	R	0x01
0x13	0 <sup>†</sup>	GMI0[6]	GMI0[5]	GMI0[4]	GMI0[3]	GMI0[2]	GMI0[1]	GMI0[0]	R	0x08
0x14	GMI1[7]	GMI1[6]	GMI1[5]	GMI1[4]	GMI1[3]	GMI1[2]	GMI1[1]	GMI1[0]	R	0xFF
0x15	0 <sup>†</sup>	GMI2[6]	GMI2[5]	GMI2[4]	GMI2[3]	GMI2[2]	GMI2[1]	GMI2[0]	R	0x01
0x16	0 <sup>†</sup>	GPQ0[6]	GPQ0[5]	GPQ0[4]	GPQ0[3]	GPQ0[2]	GPQ0[1]	GPQ0[0]	R	0x08
0x17	GPQ1[7]	GPQ1[6]	GPQ1[5]	GPQ1[4]	GPQ1[3]	GPQ1[2]	GPQ1[1]	GPQ1[0]	R	0xFF
0x18	0 <sup>†</sup>	GPQ2[6]	GPQ2[5]	GPQ2[4]	GPQ2[3]	GPQ2[2]	GPQ2[1]	GPQ2[0]	R	0x01
0x19	0 <sup>†</sup>	GMQ0[6]	GMQ0[5]	GMQ0[4]	GMQ0[3]	GMQ0[2]	GMQ0[1]	GMQ0[0]	R	0x08
0x1A	GMQ1[7]	GMQ1[6]	GMQ1[5]	GMQ1[4]	GMQ1[3]	GMQ1[2]	GMQ1[1]	GMQ1[0]	R	0xFF
0x1B	0 <sup>†</sup>	GMQ2[6]	GMQ2[5]	GMQ2[4]	GMQ2[3]	GMQ2[2]	GMQ2[1]	GMQ2[0]	R	0x01
0x1C	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	R	0x00
0x1D	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	CLO[3]	CLO[2]	CLO[1]	CLO[0]	R	0x00
0x1E	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	GOR	IDT[3]	IDT[2]	IDT[1]	IDT[0]	R	0x04
0x1F	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	0 <sup>†</sup>	TEMP[3]	TEMP[2]	TEMP[1]	TEMP[0]	R	0x0Y

\*unused †read-only; values written are disregarded, X = production dependent, Y = resets to 7 after EN from Low to High with TEMPUPDT = 1, for EN = Low all read-only (R) registers default to 0x00.

## APPENDIX

Table 11. Serial Port Register Bit Field Summary

BITS	FUNCTION	DESCRIPTION	VALID VALUES	DEFAULT
AGCTRL	Analog Gain Control Enable	Enables analog control through V <sub>CTRL</sub> (Pin 1) when AGCTRL = 1.	0, 1	1
CHIPID[7:0]	Chip ID		1	1
CLO[3:0]	LO Port Match Cap Array	LO port match, automatically adjusted through programming FREQ[6:0]	0x00 to 0x0F	0x00
CLOO[3:0]	LO Port Cap Array Override	Programs LO port match capacitor array when CLOEN = 0	0x00 to 0x0F	0x00
CLOEN	Automatic LO Match Enable	Automatic LO port impedance matching enabled when CLOEN = 1. Override bits CLOO[3:0] control LO port match when CLOEN = 0.	0, 1	1
CPPM0[5:0]	C <sub>ppQ</sub> Fine Control	$C_{ppQ} = CPPM0[5:0] + \text{number of 1's in } CPPM1[6:0] \times 64$	0x00 to 0x5F	0xXX
CPPM1[6:0]	C <sub>ppQ</sub> Coarse Control		0x00 to 0x7F	0x0X
CPPP0[5:0]	C <sub>ppI</sub> Fine Control	$C_{ppI} = CPPP0[5:0] + \text{number of 1's in } CPPP1[6:0] \times 64$	0x00 to 0x5F	0xXX
CPPP1[6:0]	C <sub>ppI</sub> Coarse Control		0x00 to 0x7F	0x0X
FREQ[6:0]	Poly-Phase Filter Frequency	Programs the center frequency of the poly-phase filter, according to Table 5.	0x00 to 0x79	0x2E
FUSE[3:0]	Fuse Read Out		0x00 to 0x0F	0x0X
GAIN[4:0]	Coarse Digital Gain Control	Programs the conversion gain in 1dB steps, according to Table 3.	0x00 to 0x13	0x04
GAINF[3:0]	Fine Digital Gain Control	Conversion gain control in approximately 0.1dB steps, when TEMPCORR = 1.	0x00 to 0x0F	0x00
GMI0[6:0]	Fine GMI DAC Read-Out	BBMI input stage gain Gml.	0x00 to 0x7F	0x08
GMI1[7:0]	Coarse GMI DAC Read-Out1	$Gml = GMI0[6:0] + (\text{number of 1's in } GMI1[7:0] \text{ and } GMI2[6:0]) \times 128$	0x00 to 0x07	0xFF
GMI2[6:0]	Coarse GMI DAC Read-Out2		0x00 to 0x07	0x01
GMQ0[6:0]	Fine GMQ DAC Read-Out	BBMQ input stage gain GmQ.	0x00 to 0x7F	0x08
GMQ1[7:0]	Coarse GMQ DAC Read-Out1	$GmQ = GMQ0[6:0] + (\text{number of 1's in } GMQ1[7:0] \text{ and } GMQ2[6:0]) \times 128$	0x00 to 0x07	0xFF
GMQ2[6:0]	Coarse GMQ DAC Read-Out2		0x00 to 0x07	0x01
GOR	Gain Out of Range	For DG < -19 GOR = 1; Else GOR = 0	0, 1	0
GPI0[6:0]	Fine GPI DAC Read-Out	BBPI input stage gain Gpl.	0x00 to 0x7F	0x08
GPI1[7:0]	Coarse GPI DAC Read-Out1	$Gpl = GPI0[6:0] + (\text{number of 1's in } GPI1[7:0] \text{ and } GPI2[6:0]) \times 128$	0x00 to 0x07	0xFF
GPI2[6:0]	Coarse GPI DAC Read-Out2		0x00 to 0x07	0x01
GPQ0[6:0]	Fine GPQ DAC Read-Out	BBPQ input stage gain GpQ.	0x00 to 0x7F	0x08
GPQ1[7:0]	Coarse GPQ DAC Read-Out1	$GpQ = GPQ0[6:0] + (\text{number of 1's in } GPQ1[7:0] \text{ and } GPQ2[6:0]) \times 128$	0x00 to 0x07	0xFF
GPQ2[6:0]	Coarse GPQ DAC Read-Out2		0x00 to 0x07	0x01
IDT[3:0]	RF Buffer Bias		0x00 to 0x0D	0x04
IQGR[7:0]	I/Q Gain Ratio Control	Adjust the gain difference in approximate constant steps in dB. See Table 4.	0x00 to 0xFF	0x80
IQPHE[2:0]	I/Q Phase Extension Bits	Extend the IQ phase adjustment range. See Table 9.	0x00 to 0x07	0x00
IQPHF[4:0]	Fine I/Q Phase Balance Control	Fine adjustment of IQ LO phase difference. See Table 9. Zero phase shift for 0x10.	0x00 to 0x1F	0x10
IQPHSIGN	Sign IQ Phase Extension Bits	Encodes the sign of the IQ phase extension bits IQPHE[2:0]. Positive for IQPHSIGN = 1.	0, 1	0
OFFSETI[7:0]	I-Channel Offset Control	Adjusts DC offset in the I-channel. Zero offset for 0x80. See page 19.	0x01 to 0xFF	0x80
OFFSETQ[7:0]	Q-Channel Offset Control	Adjusts DC offset in the Q-channel. Zero offset for 0x80. See page 19.	0x01 to 0xFF	0x80
QDISABLE	Disable Q-Channel	QDISABLE = 1 shuts down the Q-channel, turning the LTC5599 into an upconversion mixer.	0, 1	0
SRESET	Soft Reset	Writing 1 to this bit resets all registers to their default values.	0, 1	0
TEMP[3:0]	Thermometer Output	Digital representation of die temperature. Step size about 10°C.	0x00 to 0x07	0x07
TEMPCORR	Temperature Correction Disable	TEMPCORR = 1 disables temperature correction of the gain, and enables manual fine-adjustment using bits GAINF[3:0].	0, 1	0
TEMPUPDT	Temperature Correction Update	TEMPUPDT = 1 synchronizes temperature correction of the gain to a LOW - HIGH transition on the TTCK pin. Asynchronous correction for TEMPUPDT = 0.	0, 1	1
THERMINP	Thermometer Input Select	For test purposes only. Should be set to 0.	0	0

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## TYPICAL APPLICATION

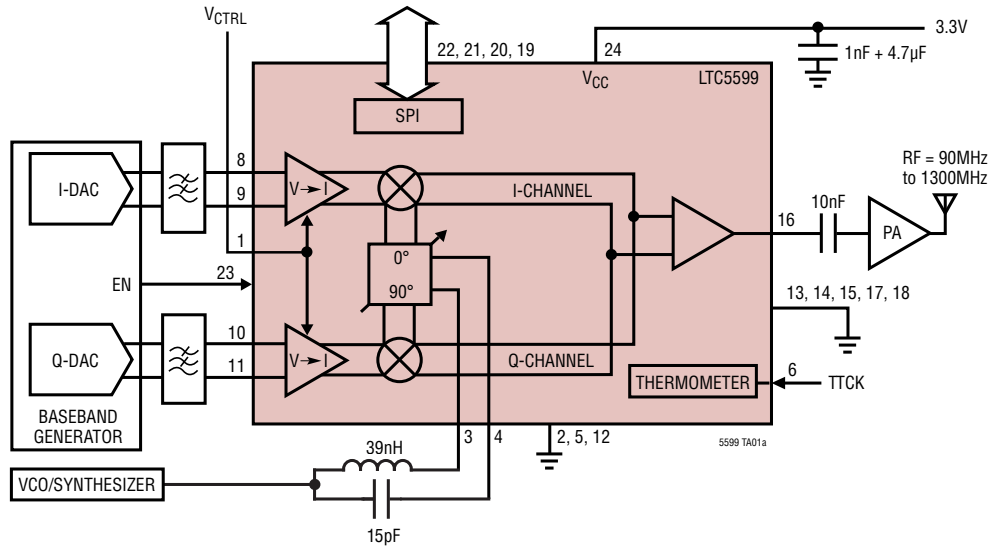


Figure 16. 90MHz to 1300MHz Direct Conversion Transmitter Application

## RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
<b>Infrastructure</b>		
<a href="#">LT5518</a>	1.5GHz to 2.4GHz High Linearity Direct Quadrature Modulator	22.8dBm OIP3 at 2GHz, -158.2dBm/Hz Noise Floor, 3kΩ 2.1V <sub>DC</sub> Baseband Interface, 5V/128mA Supply
<a href="#">LT5528</a>	1.5GHz to 2.4GHz High Linearity Direct Quadrature Modulator	21.8dBm OIP3 at 2GHz, -159.3dBm/Hz Noise Floor, 50Ω 0.5V <sub>DC</sub> Baseband Interface, 5V/128mA Supply
<a href="#">LT5558</a>	600MHz to 1100MHz High Linearity Direct Quadrature Modulator	22.4dBm OIP3 at 900MHz, -158dBm/Hz Noise Floor, 3kΩ 2.1V <sub>DC</sub> Baseband Interface, 5V/108mA Supply
<a href="#">LT5568</a>	700MHz to 1050MHz High Linearity Direct Quadrature Modulator	22.9dBm OIP3 at 850MHz, -160.3dBm/Hz Noise Floor, 50Ω 0.5V <sub>DC</sub> Baseband Interface, 5V/117mA Supply
<a href="#">LT5571</a>	620MHz to 1100MHz High Linearity Direct Quadrature Modulator	21.7dBm OIP3 at 900MHz, -159dBm/Hz Noise Floor, Hi-Z 0.5V <sub>DC</sub> Baseband Interface, 5V/97mA Supply
<a href="#">LT5572</a>	1.5GHz to 2.5GHz High Linearity Direct Quadrature Modulator	21.6dBm OIP3 at 2GHz, -158.6dBm/Hz Noise Floor, Hi-Z 0.5V <sub>DC</sub> Baseband Interface, 5V/120mA Supply
<a href="#">LTC5598</a>	5MHz to 1600MHz High Linearity Direct Quadrature Modulator	27.7dBm OIP3 at 140MHz, -160dBm/Hz Noise Floor with P <sub>OUT</sub> = 5dBm
<a href="#">LT5560</a>	0.01MHz to 4GHz Low Power Active Mixer	IIP3 = 9dBm, 2.6dB Conversion Gain, 9.3dB NF, 3.0V/10mA Supply Current
<a href="#">LT5506/5546</a>	40MHz to 500MHz Quadrature Demodulator with VGA	56dB Gain, -49 to 0dBm IIP3, 6.8dB NF, 1.8V to 5.25V/26.5mA Supply Current
<a href="#">LTC5510</a>	1MHz to 6GHz, 3.3V Wideband High Linearity Active Mixer	1.5dB Gain, 27dBm IIP3, 11.6dB NF, 3.3V/105mA Supply Current
<b>RF Power Detector</b>		
<a href="#">LT5581</a>	6GHz Low Power RMS Detector	40dB Dynamic Range, ±1dB Accuracy Over Temperature, 1.5mA Supply Current
<a href="#">LTC5582</a>	40MHz to 10GHz RMS Power Detector	57dB Dynamic Range, ±1dB Accuracy Over Temperature, Single-Ended RF Input (No Transformer)
<a href="#">LT5534</a>	50MHz to 3GHz RF Power Detector with 60dB Dynamic Range	60dB Dynamic Range, Linear-in-dB Response, 2.7V to 5.25V/7mA
<a href="#">LT5537</a>	LF to 1GHz Wide Dynamic Range RF/IF Log Detector	83dB Dynamic Range, Linear-in-dB Response, 2.7V to 5.25V/13.5mA

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