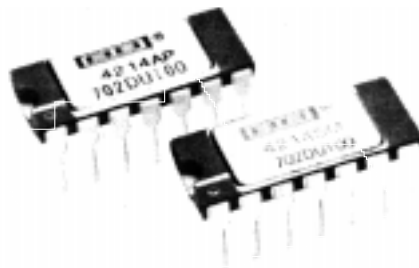




**THE DATASHEET OF
4214AP**





4214

MULTIPLIER - DIVIDER

FEATURES

- DIFFERENTIAL INPUTS
- LASER-TRIMMED
- GUARANTEED ACCURACY
0.5% and 1%
- SELF-CONTAINED
No additional parts required
- LOW NOISE
120Vrms, 10Hz - 10kHz
- DIP PACKAGE

DESCRIPTION

The 4214 family of multipliers are low-cost integrated circuit multiplier/dividers designed for general purpose usage. In addition to four-quadrant multiplication, they also perform division and square rooting of analog signals. They do not require use of additional amplifiers to perform these functions. The 4214 is laser-trimmed prior to final packaging and is guaranteed to its rated accuracy with no external components—a distinct advantage from standpoints of cost and reliability.

APPLICATIONS

- MULTIPLICATION
- DIVISION
- SQUARING
- SQUARE ROOTING
- ADAPTIVE CONTROL
- ALGEBRAIC COMPUTATION
- POWER COMPUTATION

The 4214 contains its own zener-regulated references and, as a result, is much less sensitive to supply voltage variation than were earlier IC multipliers. The multipliers' output noise is only 120Vrms in a 10Hz to 10kHz bandwidth.

The unit is packaged in a 14-pin ceramic DIP package and available in both -25°C to $+85^{\circ}\text{C}$ and -55°C to $+125^{\circ}\text{C}$ specification temperature ranges.

SPECIFICATIONS

ELECTRICAL

Typical performance at +25°C with rated power supplies unless otherwise noted.

MODEL	4214AP/RM	4214BP/SM
OUTPUT FUNCTION	$\frac{(X_1 - X_2)(Y_1 - Y_2)}{10} + Z_2$	
TOTAL ERROR⁽¹⁾ Without Trimming Error vs Temperature (-25°C to +85°C), (AP and BP) (-55°C to +125°C), (RM and SM) Error vs Supply	1% max 0.008%/°C typ., 0.02%/°C max 0.025%/°C typ., 0.05%/°C max	0.5% max 0.02%/°C max 0.05%/°C max
INDIVIDUAL ERRORS Output Offset vs Temperature vs Supply Scale Factor Error vs Temperature vs Supply Nonlinearity X (X = 20V p-p, Y = ±10VDC) Y (Y = 20V p-p, X = ±10VDC) Feedthrough at 50 Hz X = 20V p-p, Y = 0 Y = 20V p-p, X = 0 vs Temperature vs Supply	10mV typ 50mV max 0.7mV/°C typ 2mV/°C max	7mV typ 25mV max 0.3mV/°C typ 0.7mV/°C max 0.25mV/% 0.12% 0.008%/°C 0.05%/°C ±0.08% ±0.01% 30mV p-p 6mV p-p 0.1mV p-p/°C 0.15mV p-p/%
AC PERFORMANCE Small Signal ±3dB Flatness Small Signal ±1% Flatness Small Signal ±1% Vector Error (0.57° Phase Shift) Full Power Bandwidth Slew Rate Settling Time to 1% (20V step)		610 kHz 90 kHz 7.5 kHz 330 kHz 23V/μs 1.7μs
OUTPUT NOISE (X = Y = 0) 10 Hz to 10 kHz 10 Hz to 10 MHz		120μV rms 700μV rms
INPUT CHARACTERISTICS Input Voltage Range Rated Operation, min. Absolute max Input Impedance, X, Y, Z ² Input Bias Current, X, Y, Z		±10V ±V _s 10 MΩ 1.4μA
OUTPUT CHARACTERISTICS Rated Output Output Impedance		±10V at ±5mA min 1.5Ω
POWER SUPPLY REQUIREMENTS Rated Voltage Operating Range Quiescent Current		±15V ±8.5VDC to ±20VDC ±5.5mA
TEMPERATURE RANGE Rated Performance (specification) Operation Storage	AP and BP RM and SM	-25°C to +85°C -55°C to +125°C -55°C to +125°C -65°C to +150°C

- Total error is the maximum allowed value of the sum of the individual errors.
- Z₂ input impedance is 10 MΩ typ with Pin 11 open circuit. If Pin 11 is grounded or used for optional offset adjustment the Z₂ input impedance may become as low as 25kΩ.

MECHANICAL

Ceramic Dual-in-Line				
NOTE: Leads in true position within 0.010" (0.25mm) R at MMC at seating plane.				
Pin numbers shown for reference only. Numbers may not be marked on package.				
DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.70	0.710	17.02	18.03
C	0.66	0.70	1.65	4.32
D	0.15	0.21	0.38	0.53
F	0.45	0.60	1.14	1.52
G	100 BASIC		2.54 BASIC	
H	0.25	0.70	0.64	1.78
J	0.06	0.12	0.20	0.30
⌀	0.120	0.240	3.05	6.10
L	300 BASIC		7.62 BASIC	
M	— 10°		— 10°	
N	0.09	0.60	0.23	1.52

CONNECTION DIAGRAM

TYPICAL PERFORMANCE CURVES

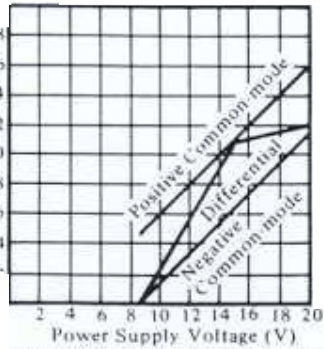
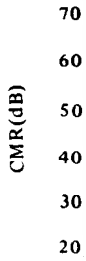


FIGURE 4. Input Range for Linear Response.

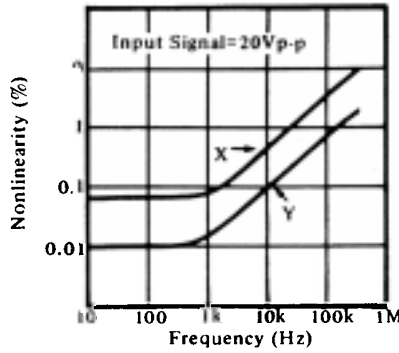


FIGURE 5. Nonlinearity vs. Frequency.

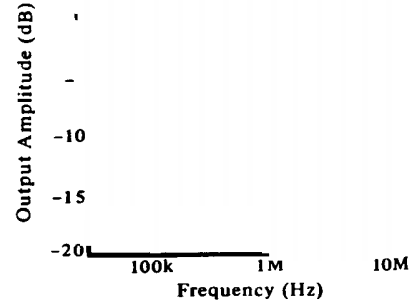


FIGURE 3. Small-signal Frequency Response.

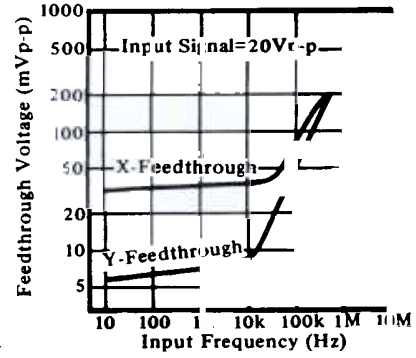


FIGURE 6. Feedthrough vs. Frequency.

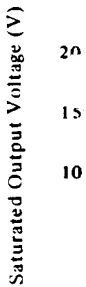


FIGURE 7. Max. Output Voltage vs. Output Current.

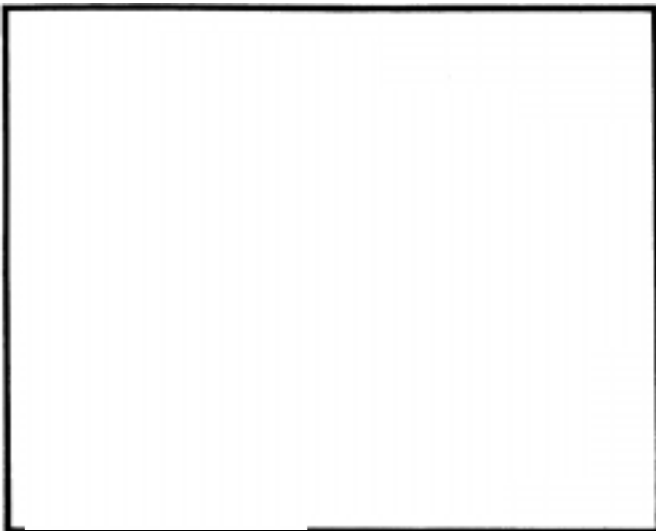
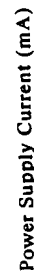


FIGURE 10. Simplified Equivalent Circuit.

OPERATING MODES MULTIPLICATION

The 4214 is a general purpose multiplier/divider with three sets of differential inputs viz. X, Y, and Z. Its open-loop transfer function is

$$e_o = A \left[\frac{(X_1 - X_2)(Y_1 - Y_2)}{10} - (Z_1 - Z_2) \right]$$

where, A is the open-loop gain of the internal output amplifier (see the simplified equivalent circuit, Figure 10). Due to very high gain ($A \rightarrow \infty$) of the output amplifier the feedback from the output to any of the inputs will establish the relationship

$$Z_1 - Z_2 = (X_1 - X_2)(Y_1 - Y_2) / 10$$

Taking output at Z_1 the multiplication mode transfer function is obtained and is expressed as

$$e_o = \frac{(X_1 - X_2)(Y_1 - Y_2)}{10} + Z_2$$

This connection of 4214 is shown on page 2.

DIVISION

The 4214 may be used as a two quadrant divider, without the need for an external op amp. Note that the maximum output error in the divide mode is given approximately by,

$$\text{Divider error} \approx \frac{10 \epsilon_m}{X_1 - X_2}, \text{ where } \epsilon_m \text{ is}$$

the total error specified for the multiply mode. The divider error, as shown above, becomes excessively large for small values of $(X_1 - X_2)$. A 10:1 denominator range is usually the practical limit. This is true for all such units, where a multiplier is used in voltage feedback mode to generate "divide" function.

If more accurate division is required over wide range of denominator voltages, the Burr-Brown model 4291 is recommended (0.25% max error over 100:1 range).

For optimum performance, the Z offset should be nulled by letting the input be zero and adjusting R_1 for zero output. This offset adjustment will improve the divider error to about $\frac{3 \epsilon_m}{(X_1 - X_2)}$ for $(X_1 - X_2)$ much less than 10V.

FIGURE 11. Divide Mode Connections—4214.

SQUARE ROOT

By applying feedback from the output to both the X and Y inputs, the square root function can be obtained. The errors in the square root mode become large for small values of Z input. The actual output is approximately

$$\text{Square root output } e_o = \sqrt{10(Z_1 - Z_2) + 10 \epsilon_m}$$

where ϵ_m is the total error for the multiply mode.

Burr-Brown's multifunction converter model 4302 is recommended for applications requiring more accuracy over wider dynamic range.

The output offset should be nulled for optimum performance by allowing the input to be its smallest expected value and adjusting R_1 for the proper output voltage.

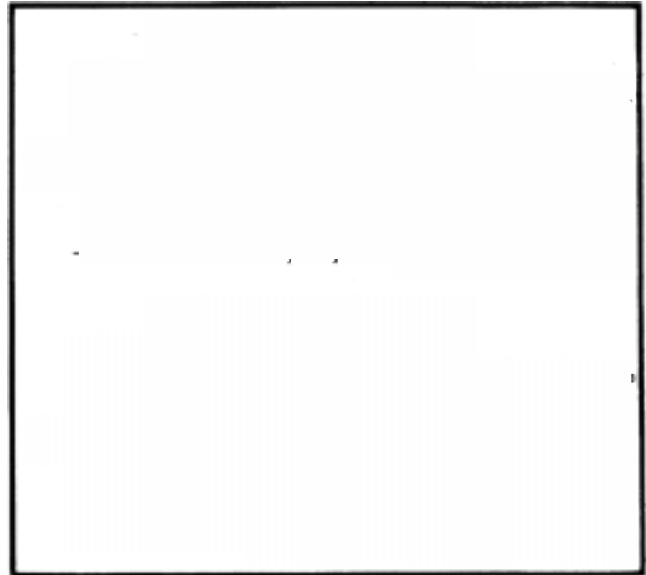


FIGURE 12. Square Root Mode Connections—4214.

SINE FUNCTION GENERATOR

Two 4214's can be connected with implicit feedback as shown in Figure 13 to implement the following sine function approximation.

$$e_o = \frac{1.5715 e_i - 0.004317 e_i^3}{1 + 0.001398 e_i^2} = 10 \text{ Sin } 9 e_i$$

The theory and procedures for developing virtually any function generator or linearization circuit can be found in the new Burr-Brown/McGraw Hill book "FUNCTION CIRCUIT - Design and Applications."

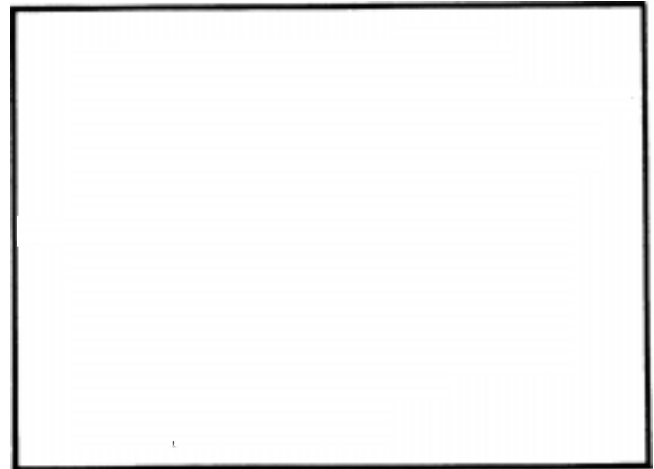


FIGURE 13. Sine Function Connections—4214.

PACKAGING INFORMATION

ORDERABLE DEVICE	STATUS(1)	PACKAGE TYPE	PACKAGE DRAWING	PINS	PACKAGE QTY
4214AP	NRND	CDIP SB	JD	14	27
4214BP	NRND	CDIP SB	JD	14	27

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

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