

Serial EEPROM Series Standard EEPROM WLCSP EEPROM BU9889GUL-W (8Kbit)



● General Description

BU9889GUL-W is a serial EEPROM of I²C BUS interface method.

● Features

- Completely conforming to the world standard I²C BUS.
All controls available by 2 ports of serial clock (SCL) and serial data (SDA)
- 1k words × 8 bits architecture 8kbit serial EEPROM.
- Other devices than EEPROM can be connected to the same port, saving microcontroller port.
- 1.7V to 5.5V single power source action most suitable for battery use.
- FAST MODE 400kHz at 1.7V to 5.5V
- Page write mode useful for initial value write at factory shipment.
- Auto erase and auto end function at data rewrite.
- Low current consumption
 - At write operation (5V) : 0.5mA (Typ.)
 - At read operation (5V) : 0.2mA (Typ.)
 - At standby operation (5V) : 0.1μA (Typ.)
- Write mistake prevention function
 - Write (write protect) function added
 - Write mistake prevention function at low voltage
- Data rewrite up to 100,000 times
- Data kept for 40 years
- Noise filter built in SCL / SDA terminal
- Shipment data all address FFh

● Package W(Typ.) x D(Typ.) x H(Max.)

VCSP50L1 1.60mm x 1.00mm x 0.55mm

● Absolute Maximum Ratings (Ta=25°C)

Parameter	symbol	Limits	Unit	Remarks
Impressed voltage	V _{CC}	-0.3 to +6.5	V	
Permissible dissipation	P _d	220	mW	When using at Ta=25°C or higher, 2.2mW to be reduced per 1°C
Storage temperature range	T _{stg}	-65 to +125	°C	
Action temperature range	T _{opr}	-40 to +85	°C	
Terminal voltage	-	-0.3 to V _{CC} +1.0	V	

● Memory cell characteristics (Ta=25°C, V_{CC}=1.7V to 5.5V)

Parameter	Limits			Unit
	Min.	Typ.	Max.	
Number of data rewrite times *1	100,000	-	-	Times
Data hold years *1	40	-	-	Years

Shipment data all address FFh
*1 Not 100% TESTED

● Recommended Operating Ratings

Parameter	Symbol	Limits	Unit
Power source voltage	V _{CC}	1.7 to 5.5	V
Input voltage	V _{IN}	0 to V _{CC}	

●Electrical Characteristics (Unless otherwise specified Ta=-40°C to +85°C, Vcc=1.7V to 5.5V)

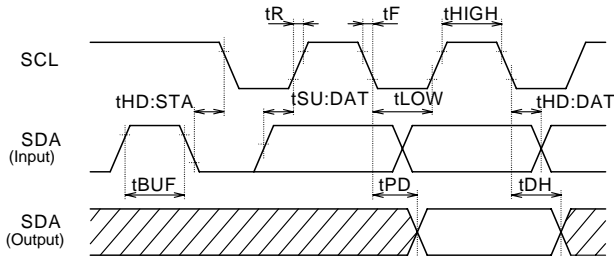
Parameter	Symbol	Limits			Unit	Condition
		Min	Typ.	Max.		
"H" Input Voltage1	V _{IH1}	0.7V _{CC}	-	V _{CC} +1.0	V	
"L" Input Voltage1	V _{IL1}	-0.3	-	0.3V _{CC}	V	
"L" Output Voltage1	V _{OL1}	-	-	0.4	V	I _{OL} =3.0mA, 2.5V ≤ V _{CC} ≤ 5.5V (SDA)
"L" Output Voltage2	V _{OL2}	-	-	0.2	V	I _{OL} =0.7mA, 1.7V ≤ V _{CC} ≤ 2.5V (SDA)
Input Leakage Current	I _{LI}	-1	-	1	μA	V _{IN} =0 to V _{CC}
Output Leakage Current	I _{LO}	-1	-	1	μA	V _{OUT} =0 to V _{CC} (SDA)
Current consumption at action	I _{CC1}	-	-	2.0	mA	V _{CC} =5.5V, f _{SCL} =400kHz, t _{WR} =5ms Byte Write, Page Write
	I _{CC2}	-	-	0.5	mA	V _{CC} =5.5V, f _{SCL} =400kHz Random read, Current read, Sequential read
Standby Current	I _{SB}	-	-	2.0	μA	V _{CC} =5.5V, SDA · SCL=V _{CC} A2=GND, WP=GND

●Action timing characteristics (Unless otherwise specified Ta=-40°C to +85°C, Vcc=1.7V to 5.5V)

Parameter	Symbol	Limits			Unit
		Min.	Typ.	Max.	
SCL Frequency	f _{SCL}	-	-	400	kHz
Data clock "High" time	t _{HIGH}	0.6	-	-	μs
Data clock "Low" time	t _{LOW}	1.2	-	-	μs
SDA, SCL rise time *1	t _R	-	-	0.3	μs
SDA, SCL fall time *1	t _F	-	-	0.3	μs
Start condition hold time	t _{HD:STA}	0.6	-	-	μs
Start condition setup time	t _{SU:STA}	0.6	-	-	μs
Input data hold time	t _{HD:DAT}	0	-	-	ns
Input data setup time	t _{SU:DAT}	100	-	-	ns
Output data delay time	t _{PD}	0.1	-	0.9	μs
Output data hold time	t _{DH}	0.1	-	-	μs
Stop condition data setup time	t _{SU:STO}	0.6	-	-	μs
Bus release time before transfer start	t _{BUF}	1.2	-	-	μs
Internal write cycle time	t _{WR}	-	-	5	ms
Noise removal valid period (SDA,SCL terminal)	t _I	-	-	0.1	μs
WP hold time	t _{HD:WP}	0	-	-	ns
WP setup time	t _{SU:WP}	0.1	-	-	μs
WP valid time	t _{HIGH:WP}	1.0	-	-	μs

*1 : Not 100% TESTED

● Sync Data Input / Output Timing



○ Input read at the rise edge of SCL
 ○ Data output in sync with the fall of SCL

Figure 1-(a) Sync data input / output timing

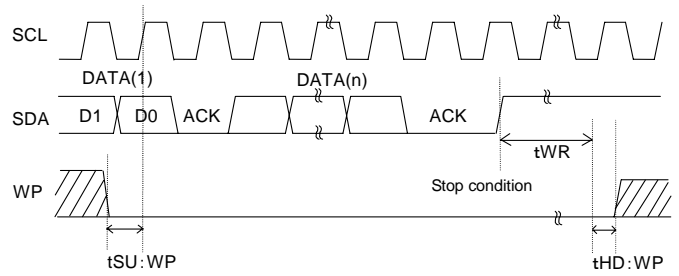


Figure 1-(d) WP timing at write execution

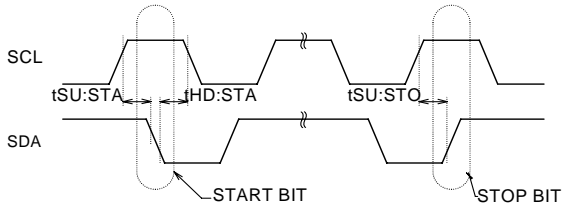
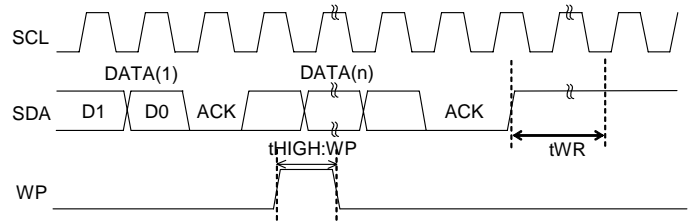


Figure 1-(b) Start - stop bit timing



○ At write execution, in the area from the D0 taken clock rise of the first DATA(1), to t_{WR} , set WP = 'LOW'.
 ○ By setting WP "HIGH" in the area, write can be cancelled. When it is set WP = "HIGH" during t_{WR} , write is forcibly ended, and data of address under access is not guaranteed, therefore write it once again.

Figure 1-(e) WP timing at write cancel

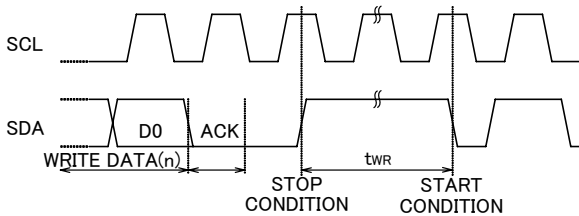
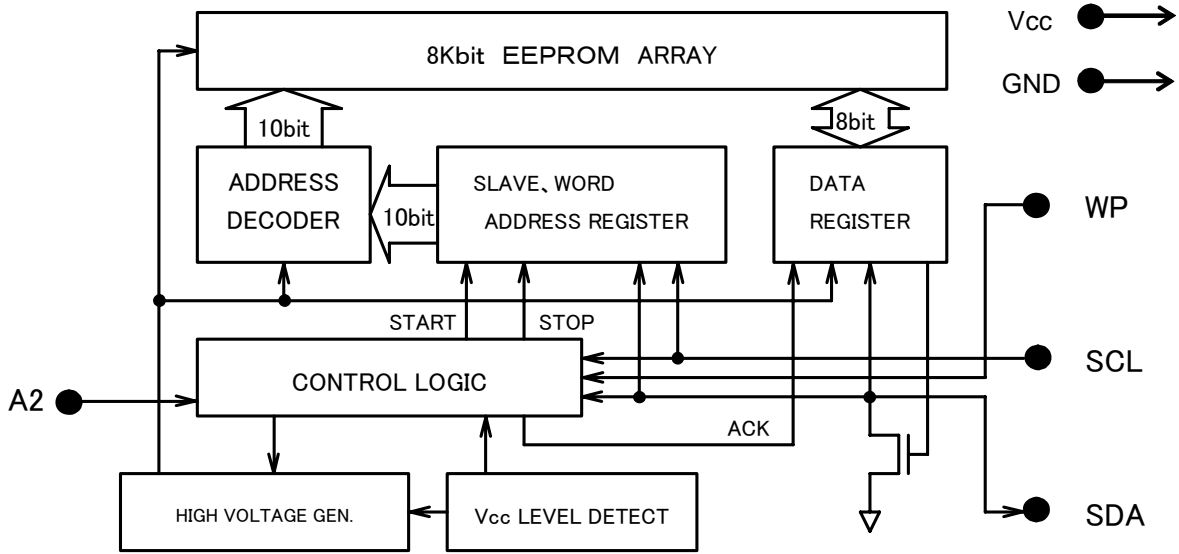
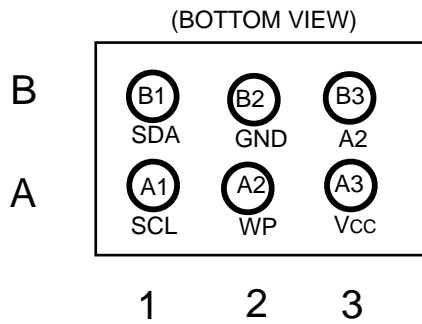


Figure 1-(c) Write cycle timing

●Block Diagram



●Pin Configuration



●Pin Descriptions

Terminal name	Input/ Output	Function
A2	Input	Slave address setting
GND	-	Reference voltage of all input / output, 0V.
SDA	Input / Output	Slave and word address, Serial data input serial data output
SCL	Input	Serial clock input
WP	Input	Write protect terminal
Vcc	-	Connect the power source.

● Typical Performance Curves

(The following values are Typ. ones.)

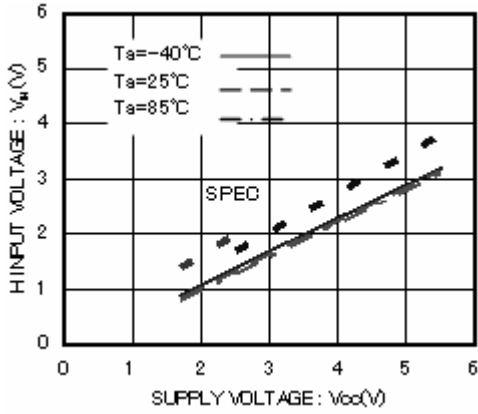


Figure 2. 'H' input voltage V_{IH}
(A2, SCL, SDA, WP)

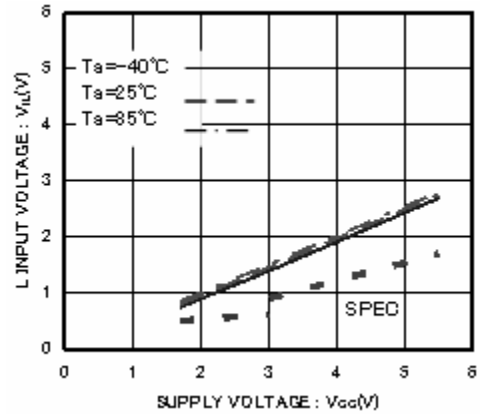


Figure 3. 'L' input voltage V_{IL}
(A2, SCL, SDA, WP)

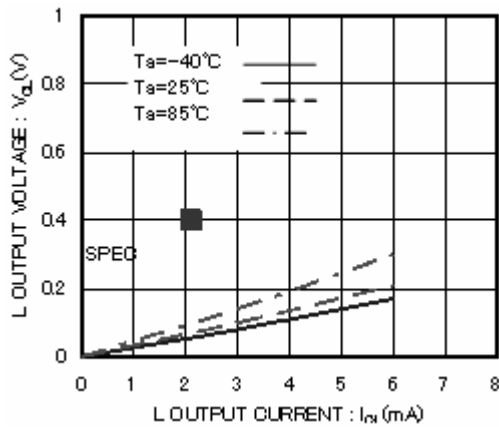


Figure 4. 'L' output voltage $V_{OL-I_{OL}}$
($V_{CC}=1.7V$)

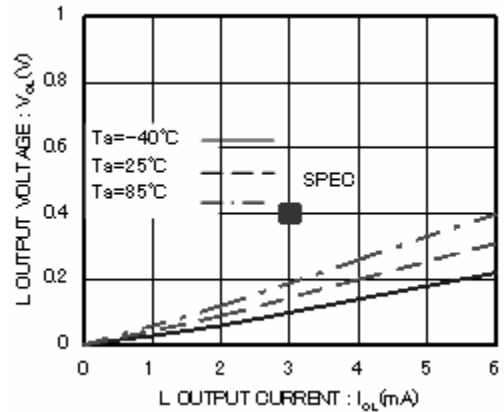


Figure 5. 'L' output voltage $V_{OL-I_{OL}}$
($V_{CC}=2.5V$)

● Typical Performance Curves - Continued

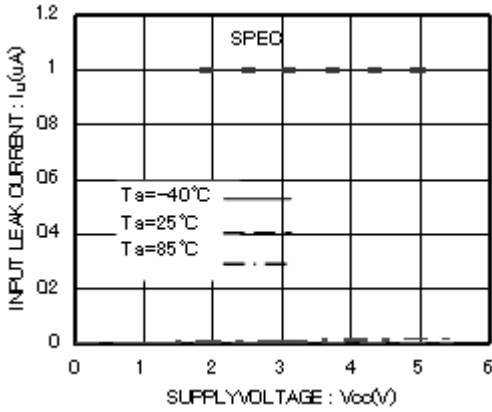


Figure 6. Input leak current I_{LI} (A2, SCL, WP)

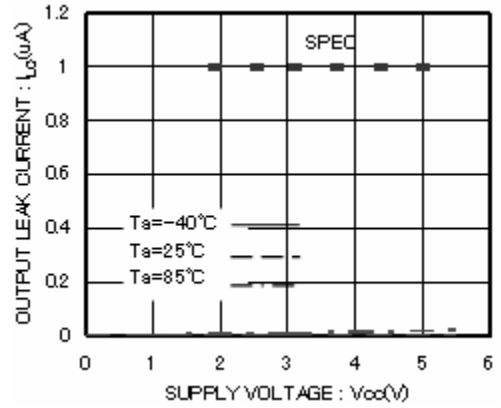


Figure 7. Output leak current I_{LO} (SDA)

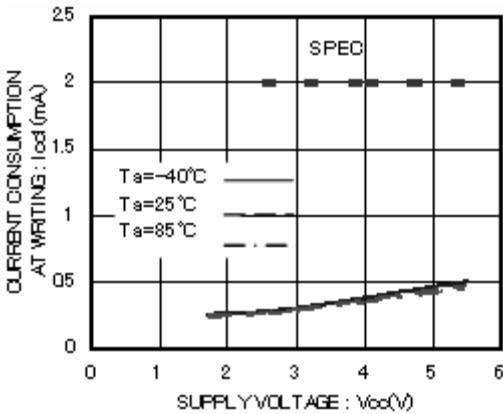


Figure 8. Current consumption at WRITE operation I_{cc1} (fsl=400kHz)

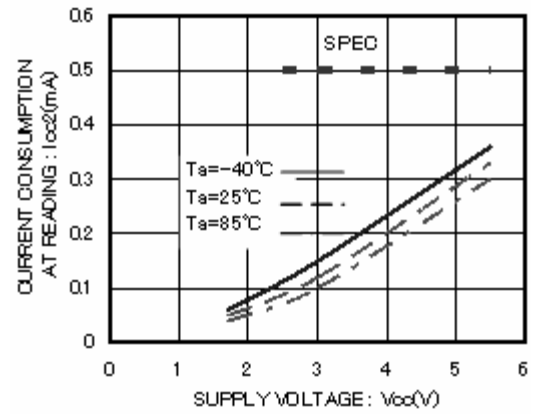


Figure 9. Current consumption at READ operation I_{cc2} (fsl=400kHz)

● Typical Performance Curves - Continued

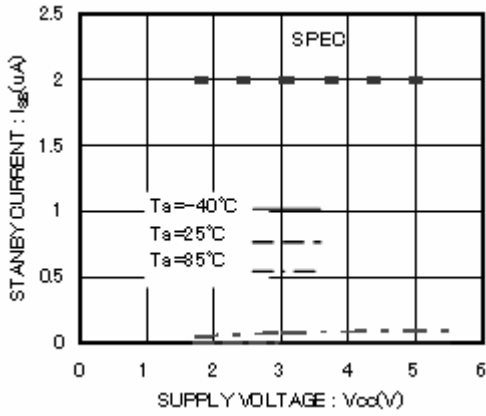


Figure 10. Standby operation I_{SB}

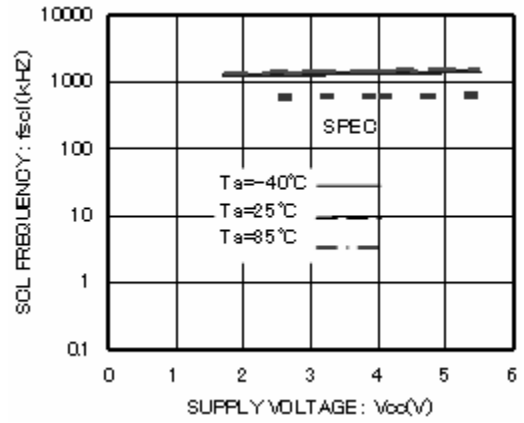


Figure 11. SCL frequency f_{SCL}

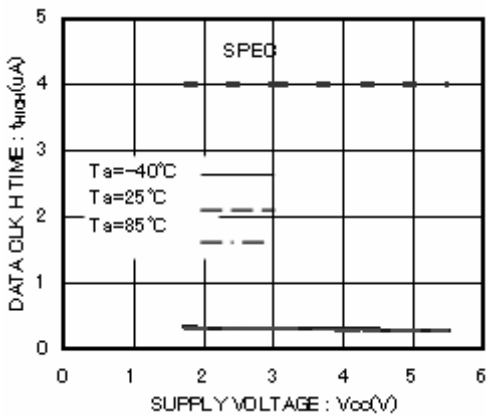


Figure 12. Data clock High Period t_{HIGH}

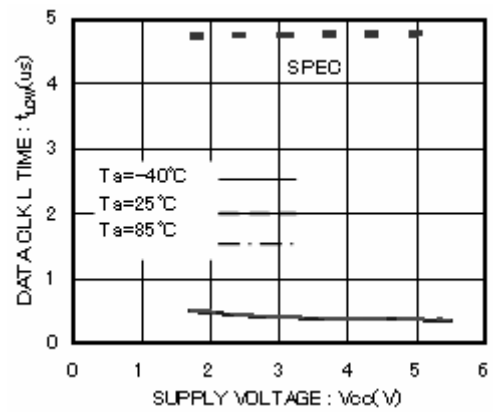


Figure 13. Data clock Low Period t_{LOW}

● Typical Performance Curves - Continued

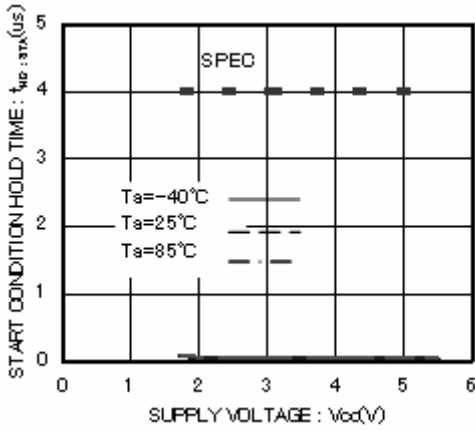


Figure 14. Start Condition Hold Time $t_{HD:STA}$

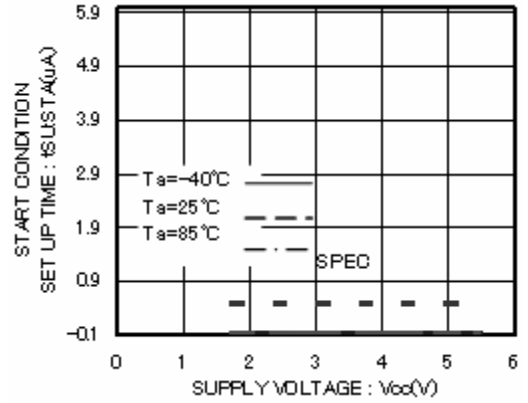


Figure 15. Start Condition Setup Time $t_{SU:STA}$

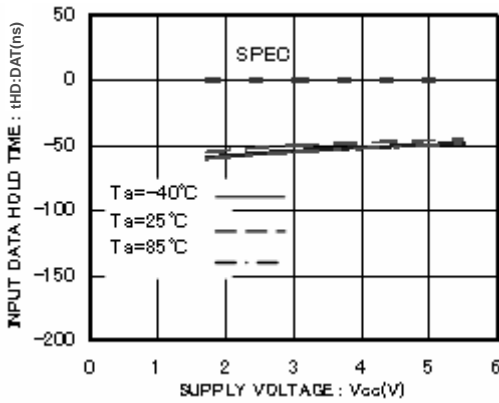


Figure 16. Input Data Hold Time $t_{HD:DAT(HIGH)}$

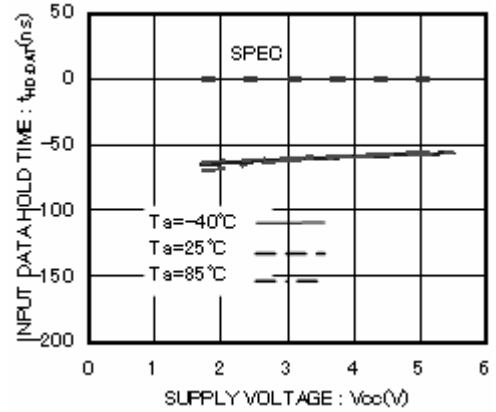


Figure 17. Input Data Hold Time $t_{HD:DAT(LOW)}$

● Typical Performance Curves - Continued

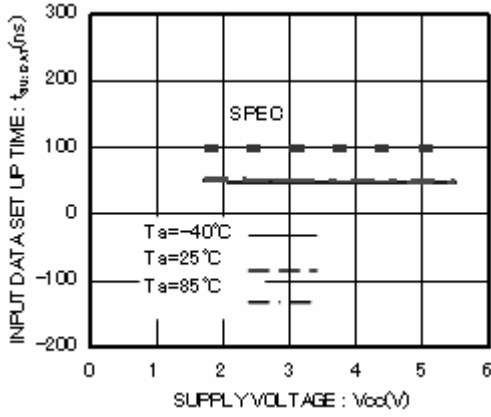


Figure 18. Input Data Setup Time $T_{SU:DAT(HIGH)}$

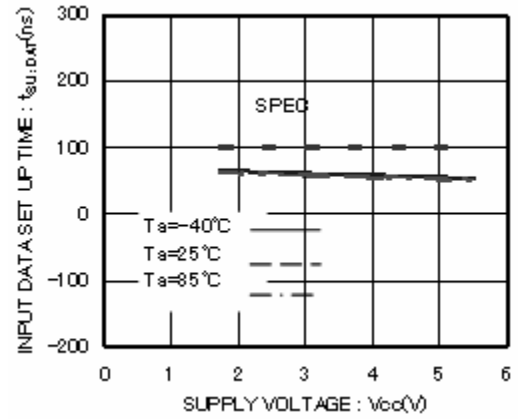


Figure 19. Input Data Setup Time $T_{SU:DAT(LOW)}$

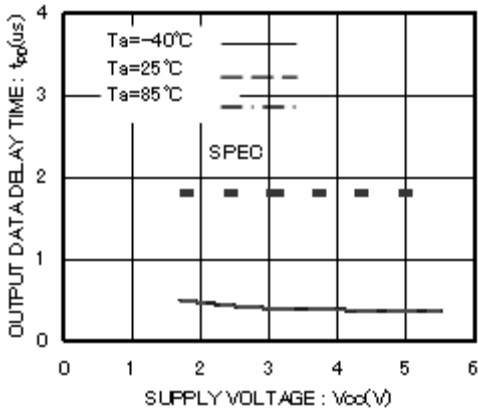


Figure 20. 'L' Data output delay time t_{PD0}

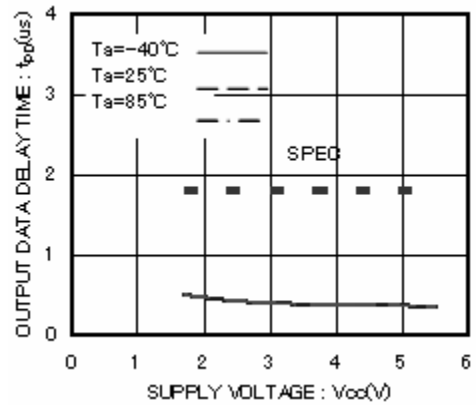


Figure 21. 'H' Data output delay time t_{PD1}

● Typical Performance Curves - Continued

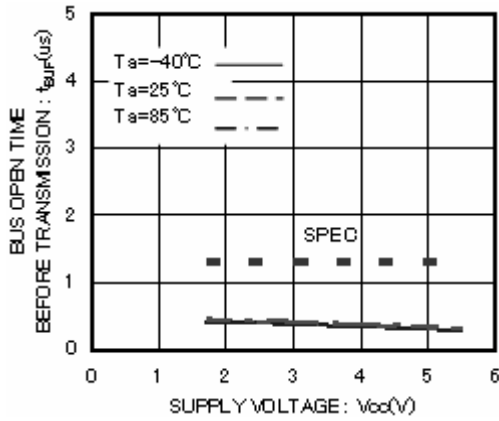


Figure 22. BUS open time before transmission t_{BUF}

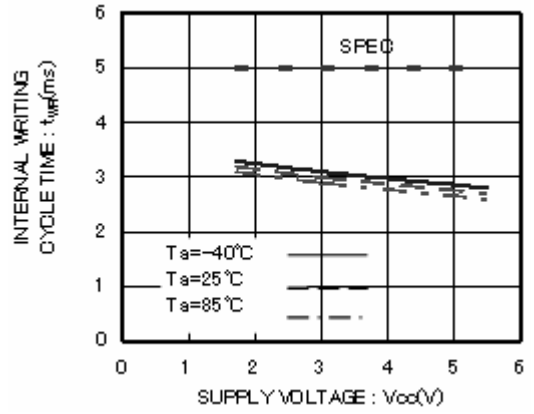


Figure 23. Internal writing cycle time t_{WR}

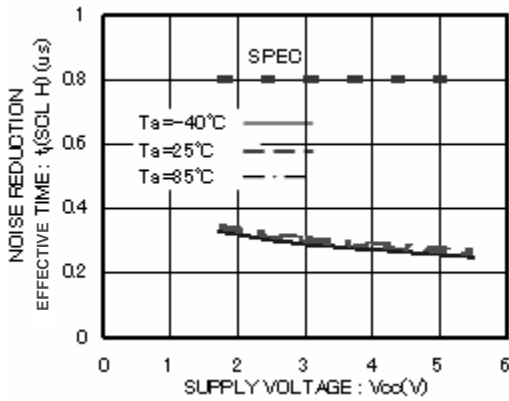


Figure 24. Noise reduction effective time t_1 (SCL H)

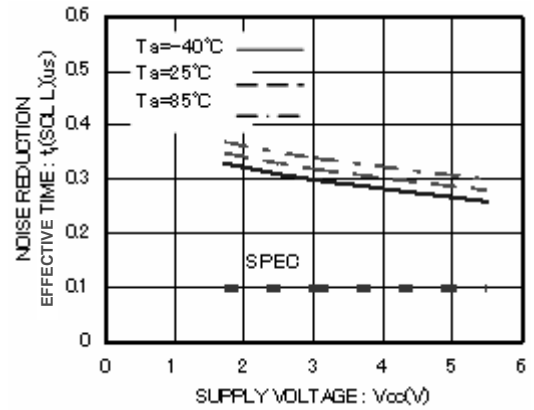


Figure 25. Noise reduction effective time t_1 (SCL L)

● Typical Performance Curves - Continued

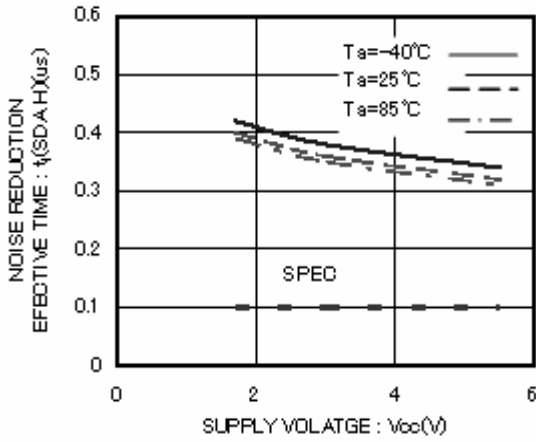


Figure 26. Noise reduction effective time t_1 (SDAH)

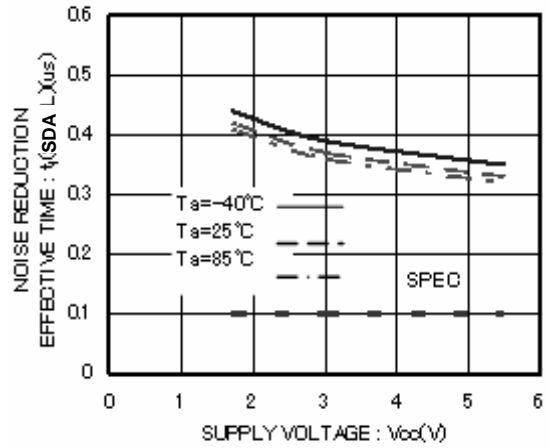


Figure 27. Noise reduction effective time t_1 (SDAL)

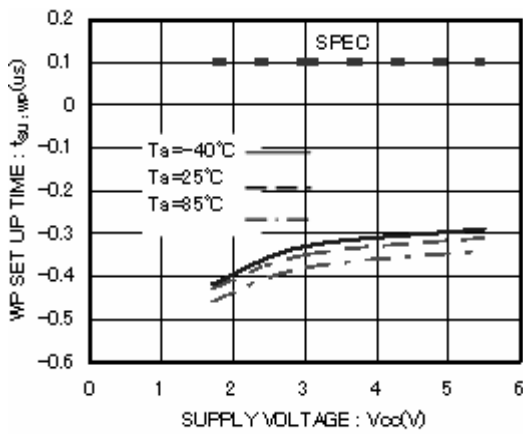


Figure 28. WP setup time $t_{su:wp}$

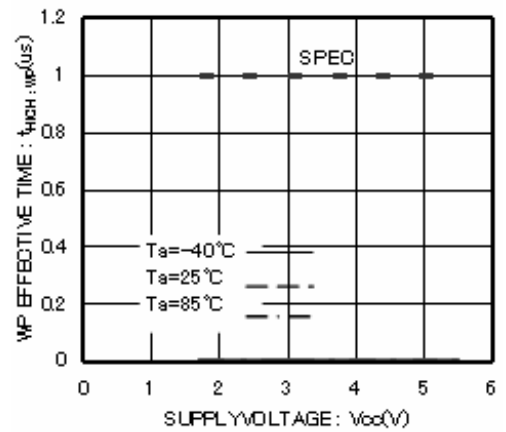


Figure 29. WP effective time $t_{high:wp}$

● I²C BUS communication

○ I²C BUS data communication

I²C BUS data communication starts by start condition input, and ends by stop condition input. Data is always 8bit long, and acknowledge is always required after each byte.

I²C BUS carries out data transmission with plural devices connected by 2 communication lines of serial data (SDA) and serial clock (SCL).

Among devices, there are “master” that generates clock and control communication start and end, and “slave” that is controlled by addresses peculiar to devices.

EEPROM becomes “slave”. And the device that outputs data to bus during data communication is called “transmitter”, and the device that receives data is called “receiver”.

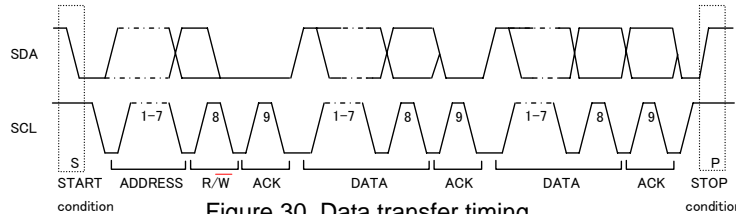


Figure 30. Data transfer timing

○ Start condition (start bit recognition)

- Before executing each command, start condition (start bit) where SDA goes from 'HIGH' down to 'LOW' when SCL is 'HIGH' is necessary.
- This IC always detects whether SDA and SCL are in start condition (start bit) or not, therefore, unless this condition is satisfied, any command is executed.

○ Stop condition (stop bit recognition)

- Each command can be ended by SDA rising from 'LOW' to 'HIGH' when stop condition (stop bit), namely, SCL is 'HIGH'

○ Acknowledge (ACK) signal

- This acknowledge (ACK) signal is a software rule to show whether data transfer has been made normally or not. In master and slave, the device (μ-COM at slave address input of write command, read command, and this IC at data output of read command) at the transmitter (sending) side releases the bus after output of 8bit data.
- The device (this IC at slave address input of write command, read command, and μ-COM at data output of read command) at the receiver (receiving) side sets SDA 'LOW' during 9 clock cycles, and outputs acknowledge signal (ACK signal) showing that it has received the 8bit data.
- This IC, after recognizing start condition and slave address (8bit), outputs acknowledge signal (ACK signal) 'LOW'.
- Each write action outputs acknowledge signal (ACK signal) 'LOW', at receiving 8bit data (word address and write data).
- Each read action outputs 8bit data (read data), and detects acknowledge signal (ACK signal) 'LOW'.
- When acknowledge signal (ACK signal) is detected, and stop condition is not sent from the master (μ-COM) side, this IC continues data output. When acknowledge signal (ACK signal) is not detected, this IC stops data transfer, and recognizes stop condition (stop bit), and ends read action. And this IC gets in standby status.

○ Device addressing

- Following a START condition, the master output the slave address to be accessed.
- The most significant four bits of the slave address are the “device type identifier,” for this device it is fixed as “1010”.
- The next bit (device address) identify the specified device on the bus. The device address is defined by the state of A2 input pin. This IC works only when the device address inputted from SDA pin correspond to the state of A2 input pin. Using this address scheme, up to two devices may be connected to the bus.
- The next two bits (P1, P0) are used by the master to select four 256 word page of memory.
 - P1, P0 set to “0” “0” ∙ ∙ ∙ 1page (000 to 0FF)
 - P1, P0 set to “0” “1” ∙ ∙ ∙ 1page (100 to 1FF)
 - P1, P0 set to “1” “0” ∙ ∙ ∙ 1page (200 to 2FF)
 - P1, P0 set to “1” “1” ∙ ∙ ∙ 1page (300 to 3FF)
- The last bit of the stream (R/W ∙ ∙ ∙ READ/WRITE) determines the operation to be performed. When set to “1”, a read operation is selected ; when set to “0”, a write operation is selected.

R/W set to “0” ∙ ∙ ∙ WRITE (including word address input of Random Read)
 R/W set to “1” ∙ ∙ ∙ READ

1 0 1 0	A2	P1	P0	R/W
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●Write Command

○Write cycle

- Arbitrary data is written to EEPROM. When to write only 1 byte, byte write normally used, and when to write continuous data of 2 bytes or more, simultaneous write is possible by page write cycle.

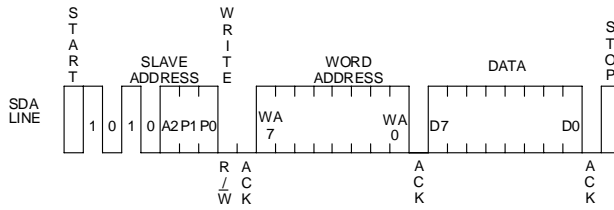


Figure 31. Byte write cycle

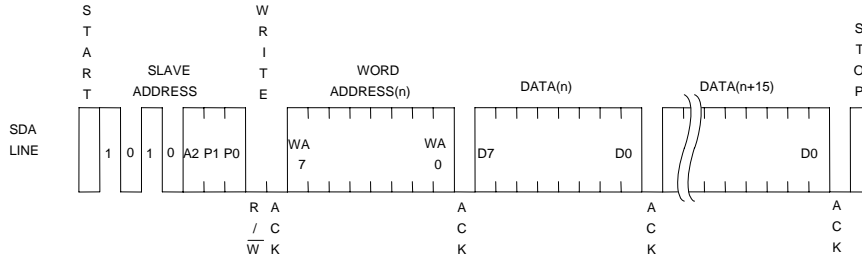


Figure 32. Page write cycle

- Data is written to the address designated by word address (n-th address).
- By issuing stop bit after 8bit data input, write to memory cell inside starts.
- When internal write is started, command is not accepted for t_{WR} (5ms at maximum).
- By page write cycle, the following can be written in bulk: Up to 16 bytes
And when data of the maximum bytes or higher is sent, data from the first byte is overwritten. (Refer to "Internal address increment" in Page14.)
- As for page write command, after page select bit(PS) of slave address is designated arbitrarily, by continuing data input of 2 bytes or more, the address of insignificant 4 bits is incremented internally, and data up to 16 bytes can be written.

○Notes on write cycle continuous input

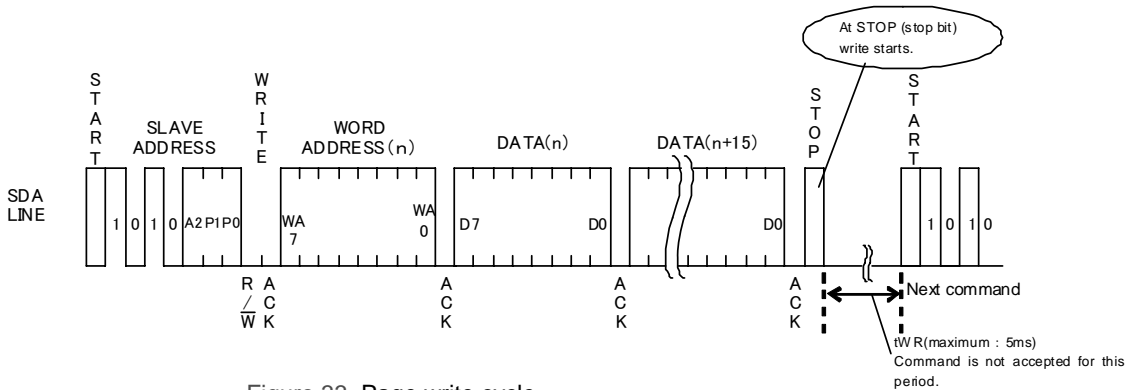


Figure 33. Page write cycle

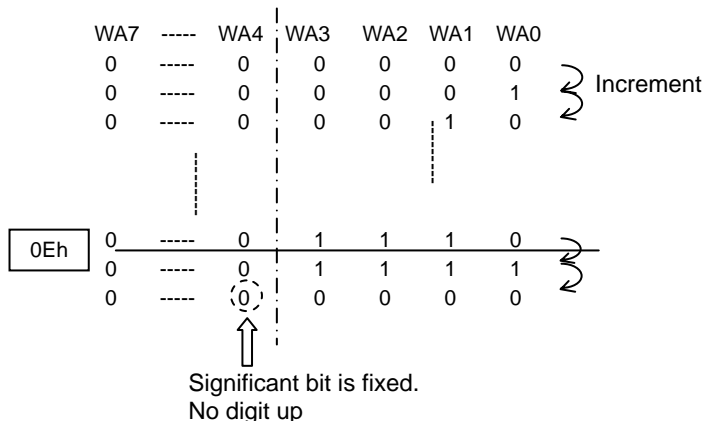
○Notes on page write cycle

Maximum page number is 16 bytes for this IC.
Any bytes below these can be written.

The page write cycle write time is 5ms at maximum for 16byte bulk write.
It does not stand 5ms at maximum × 16byte = 80ms(Max.).

○Internal address increment

Page write mode



For example, when it is started from address 0Eh, therefore, increment is made as below, 0Eh→0Fh→00h→01h..., which please note.

* 0Eh...16 in hexadecimal, therefore, 00001110 becomes a binary number.

○Write protect (WP) terminal

• Write protect (WP) function

When WP terminal is set Vcc (H level), data rewrite of all address is prohibited. When it is set GND (L level), data rewrite of all address is enabled. Be sure to connect this terminal to Vcc or GND, or control it to H level or L level. Do not use it open. At extremely low voltage at power ON/OFF, by setting the WP terminal 'H', mistake write can be prevented. During tWR, set the WP terminal always to 'L'. If it is set 'H', write is forcibly terminated.

●Read Command

○Read cycle

Data of EEPROM is read. In read cycle, there are random read cycle and current read cycle.

Random read cycle is a command to read data by designating address, and is used generally.

Current read cycle is a command to read data of internal address register without designating address, and is used when to verify just after write cycle. In both the read cycles, sequential read cycle is available, and the next address data can be read in succession.

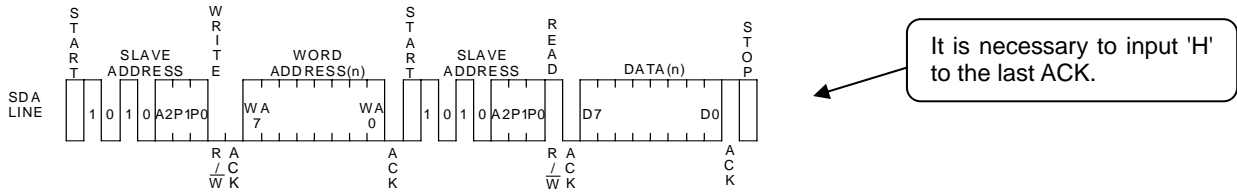


Figure 34. Random read cycle

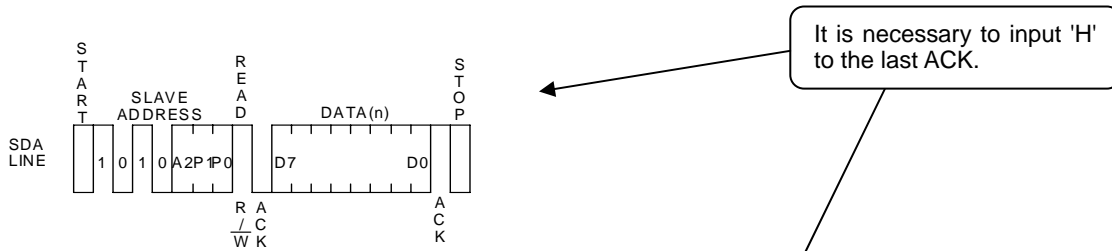


Figure 35. Current read cycle

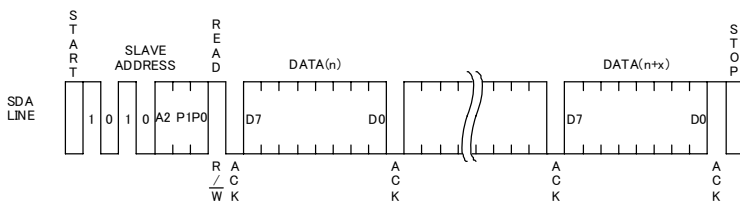


Figure 36. Sequential read cycle (in the case of current read cycle)

- In random read cycle, data of designated word address can be read.
- When the command just before current read cycle is random read cycle, current read cycle (each including sequential read cycle), data of incremented last read address (n)-th address, i.e., data of the (n+1)-th address is output.
- When ACK signal 'LOW' after D0 is detected, and stop condition is not sent from master (μ -COM) side, the next address data can be read in succession.
- Read cycle is ended by stop condition where 'H' is input to ACK signal after D0 and SDA signal is started at SCL signal 'H'.
- When 'H' is not input to ACK signal after D0, sequential read gets in, and the next data is output. Therefore, read command cycle cannot be ended. When to end read command cycle, be sure input stop condition to input 'H' to ACK signal after D0, and to start SDA at SCL signal 'H'.
- Sequential read is ended by stop condition where 'H' is input to ACK signal after arbitrary D0 and SDA is started at SCL signal 'H'.

●Software reset

Software reset is executed when to avoid malfunction after power on, and to reset during command input. Software reset has several kinds, and 3 kinds of them are shown in the figure below. (Refer to Figure 37-(a), Figure 37-(b), Figure 37-(c).) In dummy clock input area, release the SDA bus ('H' by pull up). In dummy clock area, ACK output and read data '0' (both 'L' level) may be output from EEPROM, therefore, if 'H' is input forcibly, output may conflict and over current may flow, leading to instantaneous power failure of system power source or influence upon devices.

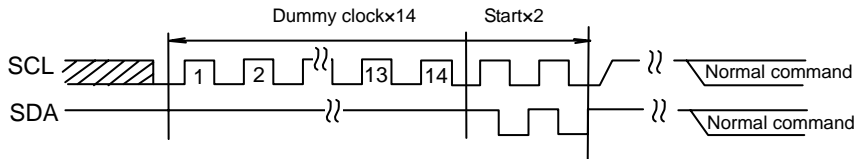


Figure 37-(a) The case of 14 Dummy clock + START + START+ command input

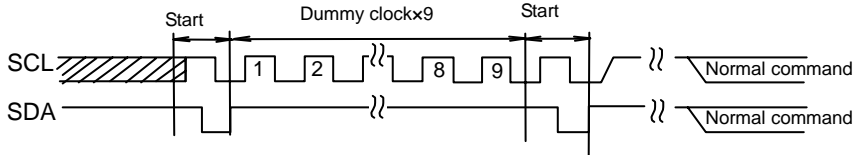


Figure 37-(b) The case of START+9 Dummy clock + START + command input

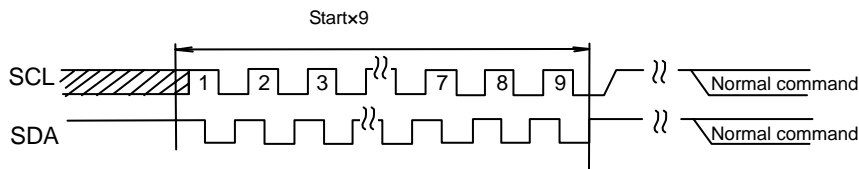


Figure 37-(c) START x 9 + command input

* Start command from START input.

●Acknowledge polling

During internal write, all input commands are ignored, therefore ACK is not sent back. During internal automatic write execution after write cycle input, next command (slave address) is sent, and if the first ACK signal sends back 'L', then it means end of write action, while if it sends back 'H', it means now in writing. By use of acknowledge polling, next command can be executed without waiting for $t_{WR} = 5ms$.

When to write continuously, $R/\bar{W} = 0$, when to carry out current read cycle after write, slave address $R/\bar{W} = 1$ is sent, and if ACK signal sends back 'L', then execute word address input and data so forth.

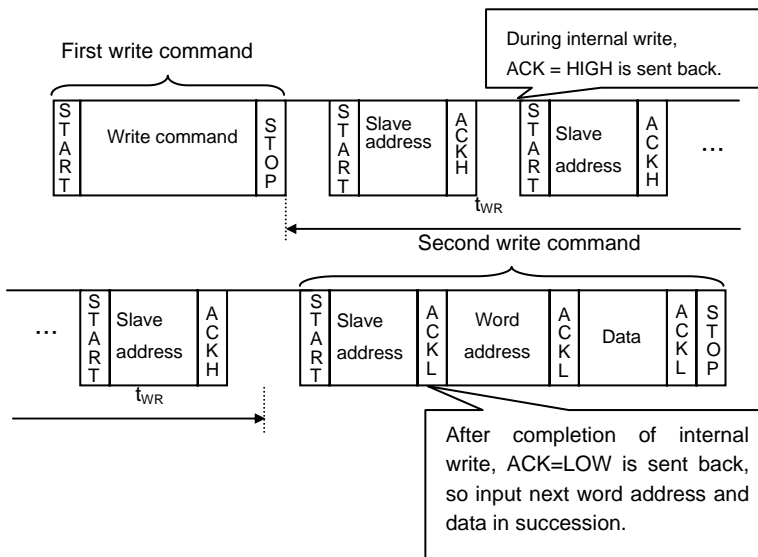


Figure 38. Case to continuously write by acknowledge polling

●WP valid timing (write cancel)

WP is usually fixed to 'H' or 'L', but when WP is used to cancel write cycle and so forth, pay attention to the following WP valid timing. During write cycle execution, in cancel valid area, by setting WP='H', write cycle can be cancelled. In both byte write cycle and page write cycle, the area from the first start condition of command to the rise of clock to taken in D0 of data (in page write cycle, the first byte data) is cancel invalid area.

WP input in this area becomes Don't care. Set the setup time to rise of D0 taken 100ns or more. The area from the rise of SCL to take in D0 to the end of internal automatic write (tWR) is cancel valid area. And, when it is set WP='H' during tWR, write is ended forcibly, data of address under access is not guaranteed, therefore, write it once again.(Refer to Figure 39.) After execution of forced end by WP standby status gets in, so there is no need to wait for tWR (5ms at maximum).

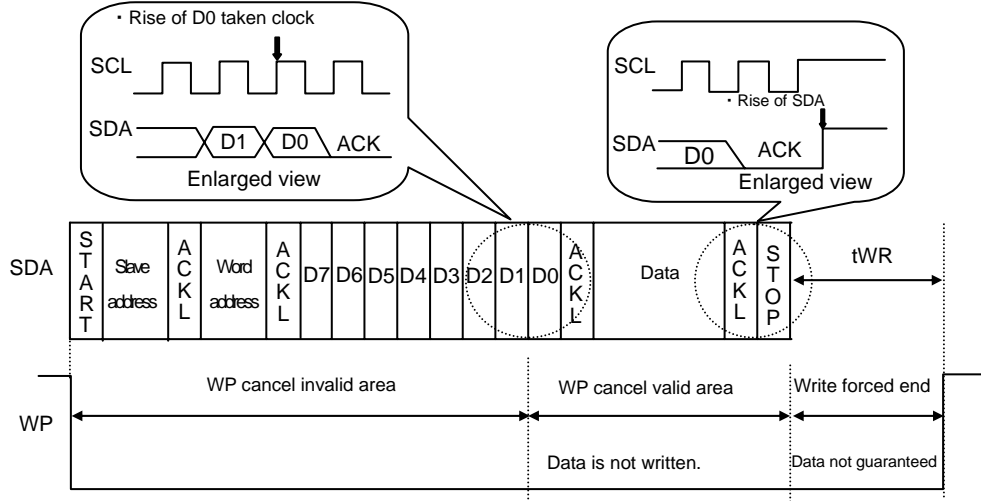


Figure 39. WP valid timing

●Command cancel by start condition and stop condition

During command input, by continuously inputting start condition and stop condition, command can be cancelled. (Refer to Figure 40.)

However, in ACK output area and during data read, SDA bus may output 'L', and in this case, start condition and stop condition cannot be input, so reset is not available. Therefore, execute software reset. And when command is cancelled by start, stop condition, during random read cycle, sequential read cycle, or current read cycle, internal setting address is not determined, therefore, it is not possible to carry out current read cycle in succession. When to carry out read cycle in succession, carry out random read cycle.

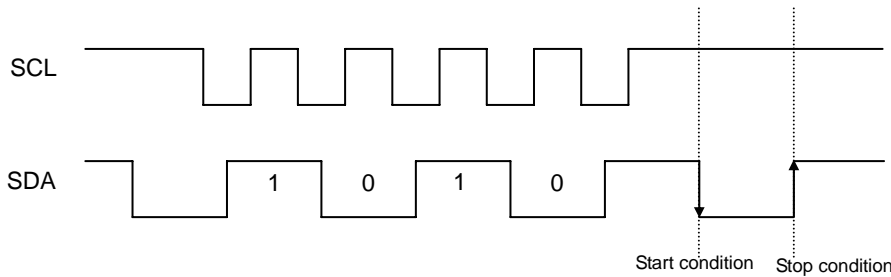


Figure 40. Case of cancel by start, stop condition during slave address input

● I/O peripheral circuit

○ Pull up resistance of SDA terminal

SDA is NMOS open drain, so requires pull up resistance. As for this resistance value (R_{PU}), select an appropriate value to this resistance value from microcontroller V_{IL} , I_L , and V_{OL} - I_{OL} characteristics of this IC. If R_{PU} is large, action frequency is limited. The smaller the R_{PU} , the larger the consumption current at action.

○ Maximum value of R_{PU}

The maximum value of R_{PU} is determined by the following factors.

(1) SDA rise time to be determined by the capacitance (CBUS) of bus line of R_{PU} and SDA should be t_R or below.

And AC timing should be satisfied even when SDA rise time is late.

(2) The bus electric potential Φ to be determined by input leak total (I_L) of device connected to bus output of 'H' to SDA bus and R_{PU} should sufficiently secure the input 'H' level (V_{IH}) of microcontroller and EEPROM including recommended noise margin $0.2V_{CC}$.

$$V_{CC} - I_L R_{PU} - 0.2V_{CC} \geq V_{IH}$$

$$\therefore R_{PU} \leq \frac{0.8V_{CC} - V_{IH}}{I_L}$$

Ex.) When $V_{CC} = 3V$, $I_L = 10\mu A$, $V_{IH} = 0.7V_{CC}$, from (2)

$$R_{PU} \leq \frac{0.8 \times 3 - 0.7 \times 3}{10 \times 10^{-6}}$$

$$\leq 300 \text{ [k}\Omega\text{]}$$

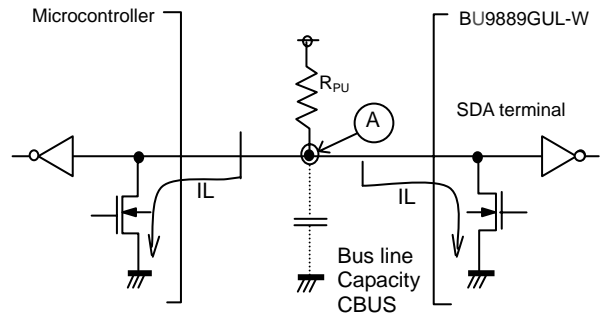


Figure 41. I/O circuit diagram

○ Minimum value of R_{PU}

The minimum value of R_{PU} is determined by the following factors.

(1) When IC outputs LOW, it should be satisfied that $V_{OLMAX} = 0.4V$ and $I_{OLMAX} = 3mA$.

$$\frac{V_{CC} - V_{OL}}{R_{PU}} \leq I_{OL}$$

$$\therefore R_{PU} \geq \frac{V_{CC} - V_{OL}}{I_{OL}}$$

(2) $V_{OLMAX} = 0.4V$ should secure the input 'L' level (V_{IL}) of microcontroller and EEPROM including recommended noise margin $0.1V_{CC}$.

$$V_{OLMAX} \leq V_{IL} - 0.1 V_{CC}$$

Ex.) When $V_{CC} = 3V$, $V_{OL} = 0.4V$, $I_{OL} = 3mA$, microcontroller, EEPROM $V_{IL} = 0.3V_{CC}$ from (1),

$$R_{PU} \geq \frac{3 - 0.4}{3 \times 10^{-3}}$$

$$\geq 867 \text{ [}\Omega\text{]}$$

And

$$V_{OL} = 0.4 \text{ [V]}$$

$$V_{IL} = 0.3 \times 3$$

$$= 0.9 \text{ [V]}$$

Therefore, the condition (2) is satisfied.

○ Pull up resistance of SCL terminal

When SCL control is made at CMOS output port, there is no need, but in the case there is timing where SCL becomes 'Hi-Z', add a pull up resistance. As for the pull up resistance, one of several $k\Omega$ to several ten $k\Omega$ is recommended in consideration of drive performance of output port of microcontroller.

● A2, WP process

○ Process of device address terminals (A2)

Check whether the set device address coincides with device address input sent from the master side or not, and select one among plural devices connected to a same bus. Connect this terminal to pull up or pull down, or V_{CC} or GND.

○ Process of WP terminal

WP terminal is the terminal that prohibits and permits write in hardware manner. In 'H' status, only READ is available and WRITE of all address is prohibited. In the case of 'L', both are available. In the case of use it as an ROM, it is recommended to connect it to pull up or V_{CC} . In the case to use both READ and WRITE, control WP terminal or connect it to pull down or GND.

●Cautions on microcontroller connection

○Rs

In I²C BUS, it is recommended that SDA port is of open drain input/output. However, when to use CMOS input / output of tri state to SDA port, insert a series resistance Rs between the pull up resistance Rpu and the SDA terminal of EEPROM. This is controls over current that occurs when PMOS of the microcontroller and NMOS of EEPROM are turned ON simultaneously. Rs also plays the role of protection of SDA terminal against surge. Therefore, even when SDA port is open drain input/output, Rs can be used.

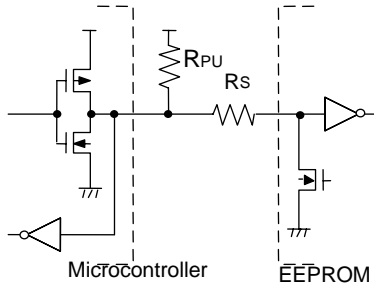
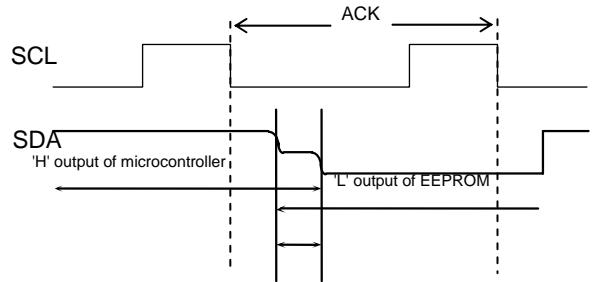


Figure 42. I/O circuit diagram



Over current flows to SDA line by 'H' output of microcontroller and 'L' output of EEPROM.

Figure 43. Input/output collision timing

○Maximum value of Rs

The maximum value of Rs is determined by following relations.

- (1)SDA rise time to be determined by the capacity (CBUS) of bus line of Rpu and SDA shoulder be tr or below. And AC timing should be satisfied even when SDA rise time is late.
- (2)The bus electric potential ϕ to be determined by Rpu and Rs the moment when EEPROM outputs 'L' to SDA bus should sufficiently secure the input 'L' level (VIL) of microcontroller including recommended noise margin 0.1Vcc.

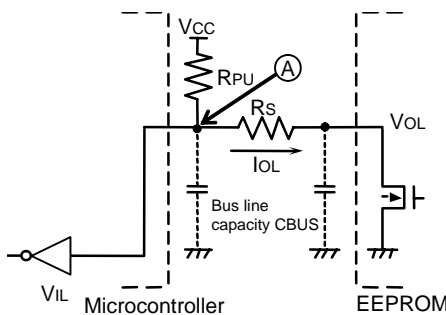


Figure 44. I/O circuit diagram

$$\frac{(VCC - VOL) \times RS}{RPU + RS} + VOL + 0.1VCC \leq VIL$$

$$\therefore RS \leq \frac{VIL - VOL - 0.1VCC}{1.1VCC - VOL} \times RPU$$

Example) When VCC=3V, VIL=0.3VCC, VOL=0.4V, RPU=20k Ω ,

$$\text{from(2), } RS \leq \frac{0.3 \times 3 - 0.4 - 0.1 \times 3}{1.1 \times 3 - 0.3 \times 3} \times 20 \times 10^3$$

$$\leq 1.67 [k\Omega]$$

○Maximum value of Rs

The minimum value of Rs is determined by over current at bus collision. When over current flows, noises in power source line, and instantaneous power failure of power source may occur. When allowable over current is defined as I, the following relation must be satisfied. Determine the allowable current in consideration of impedance of power source line in set and so forth. Set the over current to EEPROM 10mA or below.

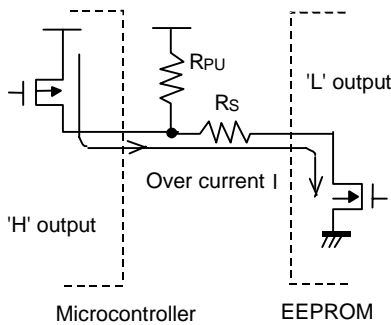


Figure 45. I/O circuit diagram

$$\frac{VCC}{RS} \leq I$$

$$\therefore RS \geq \frac{VCC}{I}$$

Example) When VCC=3V, I=10mA

$$RS \geq \frac{3}{10 \times 10^{-3}}$$

$$\geq 300 [\Omega]$$

● I²C BUS input / output circuit

○ Input (A2, SCL, WP)

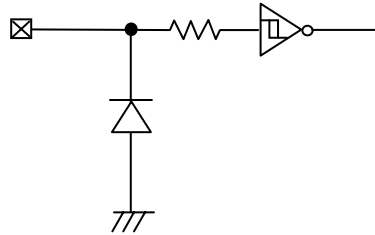


Figure 46. Input pin circuit diagram

○ Input/Output (SDA)

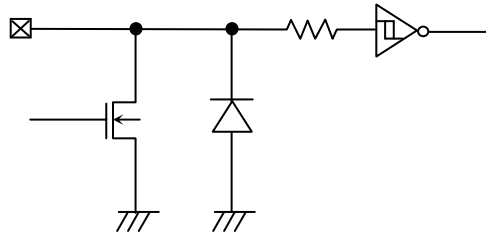


Figure 47. Input/output pin circuit diagram

● Notes on power ON

At power on, in IC internal circuit and set, Vcc rises through unstable low voltage area, and IC inside is not completely reset, and malfunction may occur. To prevent this, functions of POR circuit and LVCC circuit are equipped. To assure the action, observe the following condition at power on.

1. Set SDA = 'H' and SCL = 'L' or 'H'
2. Start power source so as to satisfy the recommended conditions of tr, toFF, and Vbot for operating POR circuit.

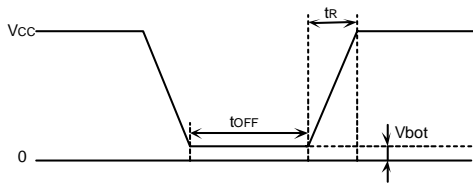


Figure 48. Rise waveform diagram

Recommended conditions of tr, toFF, Vbot

tr	toFF	Vbot
10ms or below	10ms or longer	0.3V or below
100ms or below	10ms or longer	0.2V or below

3. Set SDA and SCL so as not to become 'Hi-Z'.

When the above conditions 1 and 2 cannot be observed, take the following countermeasures.

- a) In the case when the above conditions 1 cannot be observed. When SDA becomes 'L' at power on.
→ Control SCL and SDA as shown below, to make SCL and SDA, 'H' and 'H'.

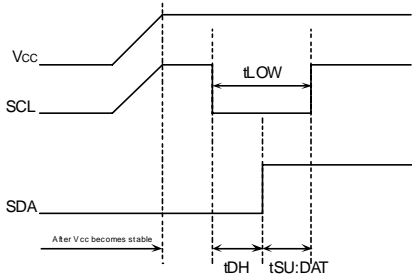


Figure 49. When SCL='H' and SDA='L'

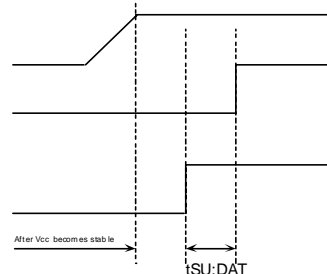


Figure 50. When SCL='H' and SDA='L'

- b) In the case when the above condition 2 cannot be observed.
→ After power source becomes stable, execute software reset (Page 16).
- c) In the case when the above conditions 1 and 2 cannot be observed.
→ Carry out a), and then carry out b).

●Low voltage malfunction prevention function

LVCC circuit prevents data rewrite action at low power, and prevents wrong write.
At LVCC voltage (Typ. =1.2V) or below, it prevent data rewrite.

●Vcc noise countermeasures

○Bypass capacitor

When noise or surge gets in the power source line, malfunction may occur, therefore, for removing these, it is recommended to attach a bypass capacitor (0.1 μ F) between IC Vcc and GND. At that moment, attach it as close to IC as possible.
And, it is also recommended to attach a bypass capacitor between board Vcc and GND.

●Cautions on use

- (1)Described numeric values and data are design representative values, and the values are not guaranteed.
- (2)We believe that application circuit examples are recommendable, however, in actual use, confirm characteristics further sufficiently. In the case of use by changing the fixed number of external parts, make your decision with sufficient margin in consideration of static characteristics and transition characteristics and fluctuations of external parts and our LSI.
- (3)Absolute maximum ratings
If the absolute maximum ratings such as impressed voltage and action temperature range and so forth are exceeded, LSI may be destructed. Do not impress voltage and temperature exceeding the absolute maximum ratings. In the case of fear exceeding the absolute maximum ratings, take physical safety countermeasures such as fuses, and see to it that conditions exceeding the absolute maximum ratings should not be impressed to LSI.
- (4)GND electric potential
Set the voltage of GND terminal lowest at any action condition. Make sure that each terminal voltage is lower than that of GND terminal.
- (5)Terminal design
In consideration of permissible loss in actual use condition, carry out heat design with sufficient margin.
- (6)Terminal to terminal shortcircuit and wrong packaging
When to package LSI onto a board, pay sufficient attention to LSI direction and displacement. Wrong packaging may destruct LSI. And in the case of shortcircuit between LSI terminals and terminals and power source, terminal and GND owing to foreign matter, LSI may be destructed.
- (7)Use in a strong electromagnetic field may cause malfunction, therefore, evaluate design sufficiently.

Status of this document

The Japanese version of this document is formal specification. A customer may use this translation version only for a reference to help reading the formal version.

If there are any differences in translation version of this document formal version takes priority.

●Ordering Information

B U 9 8 8 9 G U L - W

E 2

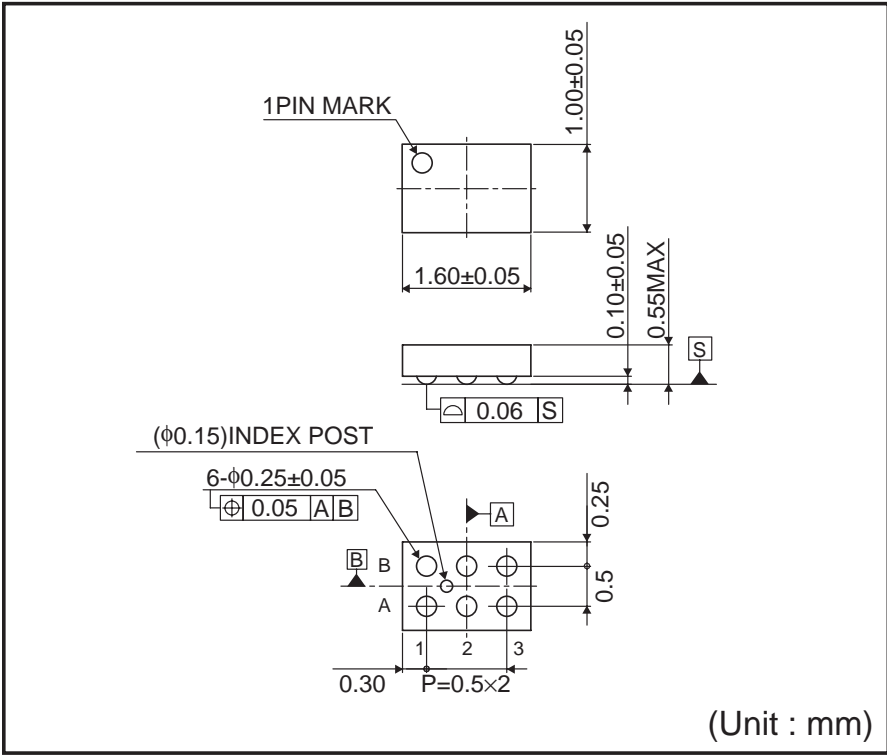
Part Number

Package
GUL: VCSP50L1(BU9889GUL-W)

Packaging and forming specification
E2: Embossed tape and reel

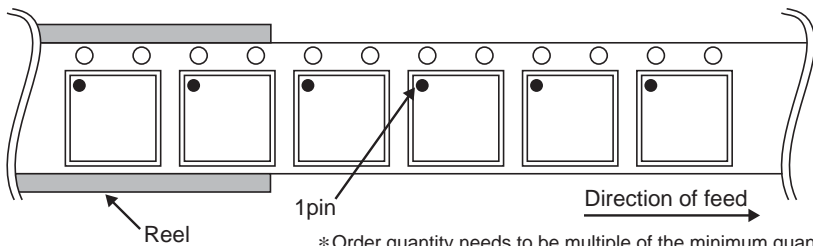
●Physical Dimension Tape and Reel Information

VCSP50L1 (BU9889GUL-W)



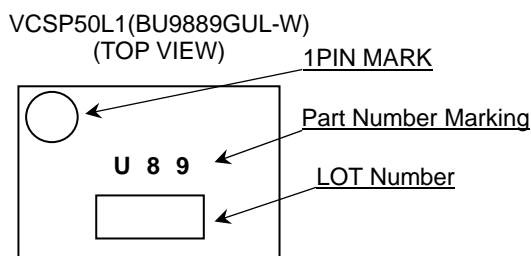
<Tape and Reel information>

Tape	Embossed carrier tape (heat sealing method)
Quantity	3000pcs
Direction of feed	E2 (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand)



*Order quantity needs to be multiple of the minimum quantity.

●Marking Diagram



●Revision History

Date	Revision	Changes
05.Sep.2012	001	New Release

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CLASS IV		CLASS III	

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 - Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
 - Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
 - Sealing or coating our Products with resin or other coating materials
 - Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
 - Use of the Products in places subject to dew condensation
- The Products are not subject to radiation-proof design.
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- De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- Confirm that operation temperature is within the specified range described in the product specification.
- ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

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- In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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