



**THE DATASHEET OF  
74ALVT16821DL,518**



# 74ALVT16821

20-bit bus interface D-type flip-flop; positive-edge trigger;  
3-state

Rev. 4 — 22 January 2018

Product data sheet

## 1 General description

The 74ALVT16821 high-performance BiCMOS device combines low static and dynamic power dissipation with high speed and high output drive. It is designed for  $V_{CC}$  operation at 2.5 V or 3.3 V with I/O compatibility to 5 V.

The 74ALVT16821 has two 10-bit, edge triggered registers, with each register coupled to a 3-state output buffer. The two sections of each register are controlled independently by the clock ( $nCP$ ) and output enable ( $n\overline{OE}$ ) control gates.

Each register is fully edge triggered. The state of each D input, one set-up time before the LOW-to-HIGH clock transition, is transferred to the corresponding flip-flops Q output.

The 3-state output buffers are designed to drive heavily loaded 3-state buses, MOS memories, or MOS microprocessors.

The active low output enable ( $n\overline{OE}$ ) controls all ten 3-state buffers independent of the register operation. When  $n\overline{OE}$  is LOW, the data in the register appears at the outputs. When  $n\overline{OE}$  is HIGH, the outputs are in high-impedance OFF-state, which means they will neither drive nor load the bus.

## 2 Features and benefits

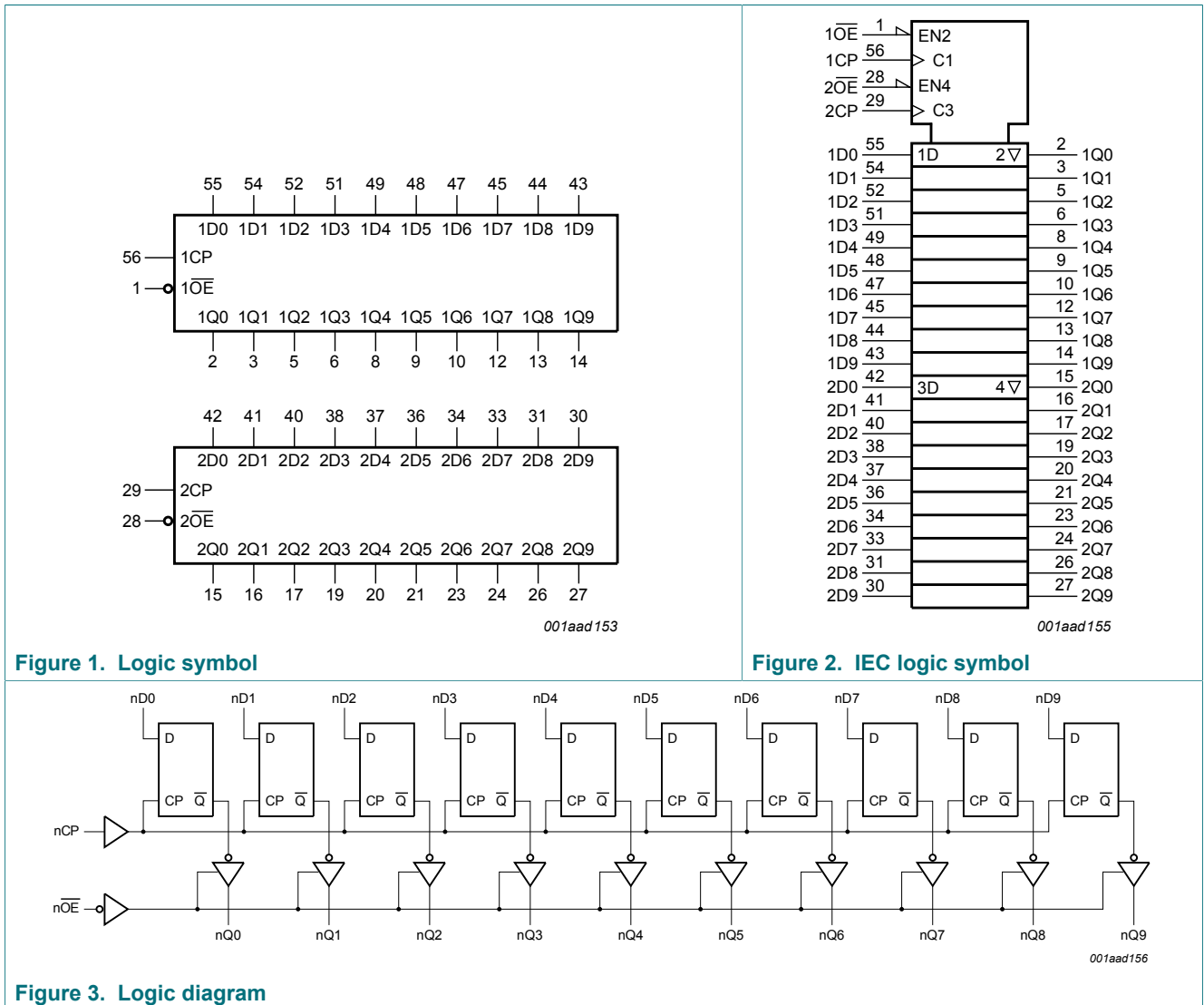
- 20-bit positive-edge triggered register
- 5 V I/O compatible
- Multiple  $V_{CC}$  and GND pins minimize switching noise
- Bus hold data inputs eliminate the need for external pull-up resistors to hold unused inputs
- Live insertion and extraction permitted
- Power-up reset
- Power-up 3-state
- Output capability: +64 mA and -32 mA
- Latch-up protection:
  - JESD78: exceeds 500 mA
- ESD protection:
  - MIL STD 883, method 3015: exceeds 2000 V
  - MM: exceeds 200 V

### 3 Ordering information

Table 1. Ordering information

| Type number    | Package           |         |  | Version  |
|----------------|-------------------|---------|--|----------|
|                | Temperature range | Name    | Description  |          |
| 74ALVT16821DGG | -40 °C to +85 °C  | TSSOP56 | plastic thin shrink small outline package; 56 leads; body width 6.1 mm | SOT364-1 |

### 4 Functional diagram



## 5 Pinning information

### 5.1 Pinning

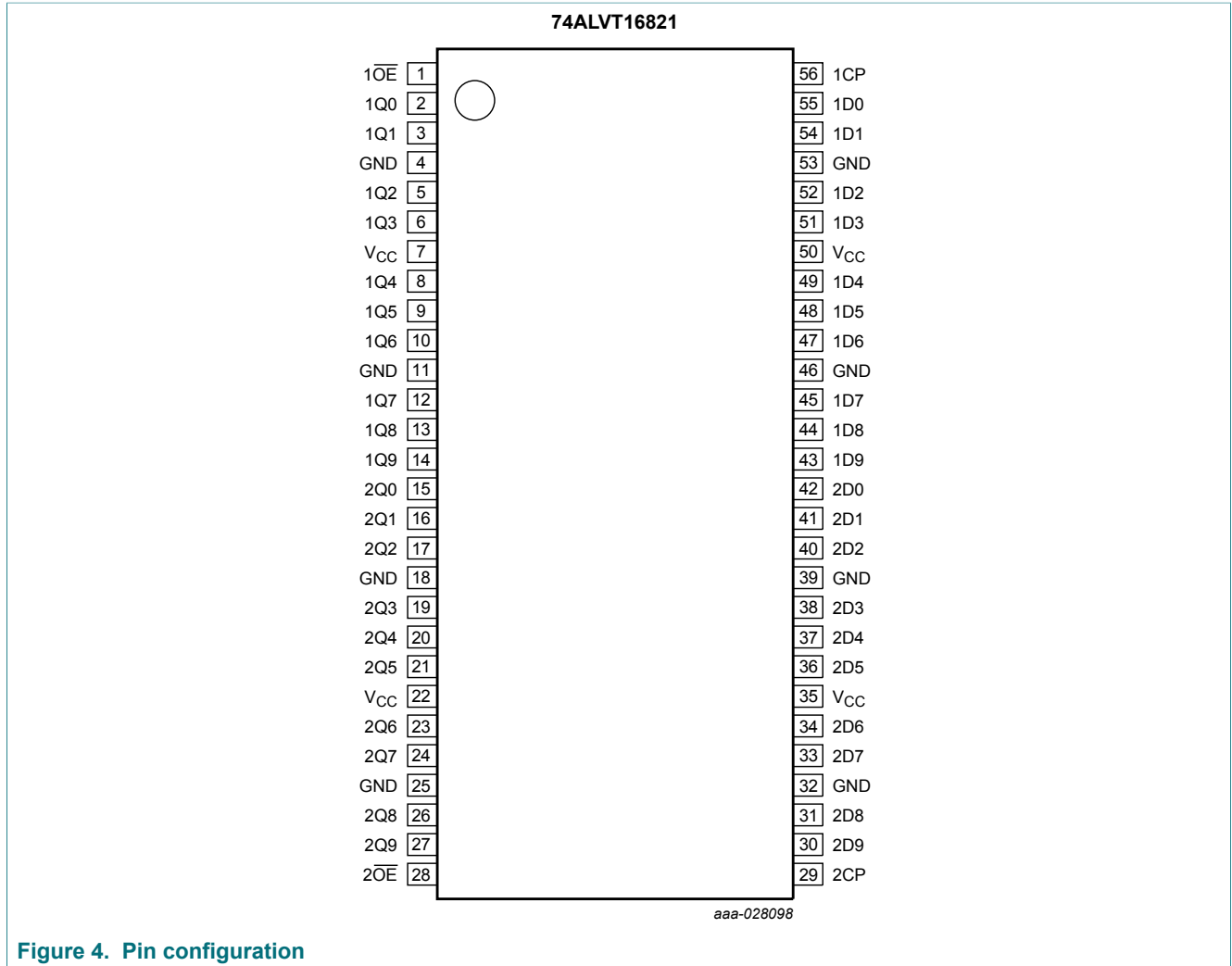


Figure 4. Pin configuration

## 5.2 Pin description

Table 2. Pin description

| Symbol  | Pin                                       | Description                             |
|---|---|---|
| 1D0, 1D1, 1D2, 1D3, 1D4,<br>1D5, 1D6, 1D7, 1D8, 1D9 | 55, 54, 52, 51, 49,<br>48, 47, 45, 44, 43 | data inputs                             |
| 1Q0, 1Q1, 1Q2, 1Q3, 1Q4,<br>1Q5, 1Q6, 1Q7, 1Q8, 1Q9 | 2, 3, 5, 6, 8,<br>9, 10, 12, 13, 14       | data outputs                            |
| 2D0, 2D1, 2D2, 2D3, 2D4,<br>2D5, 2D6, 2D7, 2D8, 2D9 | 42, 41, 40, 38, 37,<br>36, 34, 33, 31, 30 | data inputs                             |
| 2Q0, 2Q1, 2Q2, 2Q3, 2Q4,<br>2Q5, 2Q6, 2Q7, 2Q8, 2Q9 | 15, 16, 17, 19, 20,<br>21, 23, 24, 26, 27 | data outputs                            |
| 1 $\overline{OE}$ , 2 $\overline{OE}$               | 1, 28                                     | output enable inputs (active LOW)       |
| 1CP, 2CP  | 56, 29                                    | clock pulse inputs (active rising edge) |
| GND   | 4, 11, 18, 25,<br>32, 39, 46, 53          | ground (0 V)                            |
| V <sub>CC</sub>                                     | 7, 22, 35, 50                             | supply voltage                          |

## 6 Functional description

Table 3. Function table <sup>[1]</sup>

| Operating mode         | Input |     |     | Internal register | Output |
|------------------------|-------|-----|-----|-------------------|--------|
|                        | nOE   | nCP | nDn |                   |        |
| Load and read register | L     | ↑   | l   | L                 | L      |
|                        | L     | ↑   | h   | H                 | H      |
| Hold                   | L     | NC  | X   | NC                | NC     |
| Disable outputs        | H     | NC  | X   | NC                | Z      |
|                        | H     | ↑   | nDn | nDn               | Z      |

- [1] H = HIGH voltage level;  
 h = HIGH voltage level one set-up time prior to the LOW-to-HIGH clock transition;  
 L = LOW voltage level;  
 l = LOW voltage level one set-up time prior to the LOW-to-HIGH clock transition;  
 NC = no change;  
 X = don't care;  
 Z = high-impedance OFF-state;  
 ↑ = LOW-to-HIGH clock transition.

## 7 Limiting values

**Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol    | Parameter               | Conditions                        | Min      | Max  | Unit |
|-----------|-------------------------|-----------------------------------|----------|------|------|
| $V_{CC}$  | supply voltage          |                                   | -0.5     | +4.6 | V    |
| $V_I$     | input voltage           |                                   | [1] -1.2 | +7.0 | V    |
| $V_O$     | output voltage          | output in OFF-state or HIGH-state | [1] -0.5 | +7.0 | V    |
| $I_{IK}$  | input clamping current  | $V_I < 0$ V                       | -        | -50  | mA   |
| $I_{OK}$  | output clamping current | $V_O < 0$ V                       | -        | -50  | mA   |
| $I_O$     | output current          | output in LOW-state               | -        | 128  | mA   |
|           |                         | output in HIGH-state              | -        | -64  | mA   |
| $T_{stg}$ | storage temperature     |                                   | -65      | +150 | °C   |
| $T_j$     | junction temperature    |                                   | [2] -    | 150  | °C   |

[1] The input and output negative voltage ratings may be exceeded if the input and output clamp current ratings are observed.

[2] The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability.

## 8 Recommended operating conditions

**Table 5. Recommended operating conditions**

| Symbol              | Parameter                           | Conditions   | $V_{CC} = 2.5\text{ V} \pm 0.2\text{ V}$ |     | $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$ |     | Unit |
|---------------------|-------------------------------------|--|--|-----|--|-----|------|
|                     |                                     |  | Min                                      | Max | Min                                      | Max |      |
| $V_{CC}$            | supply voltage                      |  | 2.3                                      | 2.7 | 3.0                                      | 3.6 | V    |
| $V_I$               | input voltage                       |  | 0  | 5.5 | 0  | 5.5 | V    |
| $I_{OH}$            | HIGH-level output current           |  | -  | -8  | -  | -32 | mA   |
| $I_{OL}$            | LOW-level output current            | none   | -  | 8   | -  | 32  | mA   |
|                     |                                     | current duty cycle $\leq 50\%$ ;<br>$f \geq 1$ kHz | -  | 24  | -  | 64  | mA   |
| $\Delta t/\Delta V$ | input transition rise and fall rate | outputs enabled                                    | -  | 10  | -  | 10  | ns/V |
| $T_{amb}$           | ambient temperature                 | free-air   | -40                                      | +85 | -40                                      | +85 | °C   |

## 9 Static characteristics

**Table 6. Static characteristics**

At recommended operating conditions;  $T_{amb} = -40\text{ °C to }+85\text{ °C}$ ; voltages are referenced to GND (ground = 0 V).

| Symbol   | Parameter                          | Conditions   | Min            | Typ <sup>[1]</sup> | Max       | Unit          |
|--|------------------------------------|--|----------------|--------------------|-----------|---------------|
| <b><math>V_{CC} = 2.5\text{ V} \pm 0.2\text{ V}</math></b> |                                    |  |                |                    |           |               |
| $V_{IK}$   | input clamping voltage             | $V_{CC} = 2.3\text{ V}$ ; $I_{IK} = -18\text{ mA}$   | -              | -0.85              | -1.2      | V             |
| $V_{IH}$   | HIGH-level input voltage           |  | 1.7            | -                  | -         | V             |
| $V_{IL}$   | LOW-level input voltage            |  | -              | -                  | 0.7       | V             |
| $V_{OH}$   | HIGH-level output voltage          | $V_{CC} = 2.3\text{ V to }3.6\text{ V}$ ; $I_O = -100\text{ }\mu\text{A}$  | $V_{CC} - 0.2$ | $V_{CC}$           | -         | V             |
|  |                                    | $V_{CC} = 2.3\text{ V}$ ; $I_O = -8\text{ mA}$   | 1.8            | 2.1                | -         | V             |
| $V_{OL}$   | LOW-level output voltage           | $V_{CC} = 2.3\text{ V}$ ; $I_O = 100\text{ }\mu\text{A}$   | -              | 0.07               | 0.2       | V             |
|  |                                    | $V_{CC} = 2.3\text{ V}$ ; $I_O = 24\text{ mA}$   | -              | 0.3                | 0.5       | V             |
|  |                                    | $V_{CC} = 2.3\text{ V}$ ; $I_O = 8\text{ mA}$  | -              | -                  | 0.4       | V             |
| $V_{OL(pu)}$   | power-up LOW-level output voltage  | $V_{CC} = 2.7\text{ V}$ ; $I_O = 1\text{ mA}$ ; $V_I = V_{CC}$ or GND <sup>[2]</sup>   | -              | -                  | 0.55      | V             |
| $I_I$  | input leakage current              | all input pins   |                |                    |           |               |
|  |                                    | $V_{CC} = 0\text{ V or }2.7\text{ V}$ ; $V_I = 5.5\text{ V}$ <sup>[3]</sup>  | -              | 0.1                | 10        | $\mu\text{A}$ |
|  |                                    | control pins   |                |                    |           |               |
|  |                                    | $V_{CC} = 2.7\text{ V}$ ; $V_I = V_{CC}$ or GND  | -              | 0.1                | $\pm 1$   | $\mu\text{A}$ |
|  |                                    | data pins; <sup>[3]</sup>  |                |                    |           |               |
|  |                                    | $V_{CC} = 2.7\text{ V}$ ; $V_I = V_{CC}$   | -              | 0.1                | 1         | $\mu\text{A}$ |
|  |                                    | $V_{CC} = 2.7\text{ V}$ ; $V_I = 0\text{ V}$   | -              | 0.1                | -5        | $\mu\text{A}$ |
| $I_{OFF}$  | power-off leakage current          | $V_{CC} = 0\text{ V}$ ; $V_I$ or $V_O = 0\text{ V to }4.5\text{ V}$  | -              | 0.1                | $\pm 100$ | $\mu\text{A}$ |
| $I_{BHL}$  | bus hold LOW current               | data inputs; $V_{CC} = 2.3\text{ V}$ ; $V_I = 0.7\text{ V}$  | -              | 90                 | -         | $\mu\text{A}$ |
| $I_{BHH}$  | bus hold HIGH current              | data inputs; $V_{CC} = 2.3\text{ V}$ ; $V_I = 1.7\text{ V}$  | -              | -10                | -         | $\mu\text{A}$ |
| $I_{EX}$   | external current                   | output in HIGH-state; $V_O = 5.5\text{ V}$ ; $V_{CC} = 2.3\text{ V}$   | -              | 10                 | 125       | $\mu\text{A}$ |
| $I_{O(pu/pd)}$   | power-up/power-down output current | $V_{CC} \leq 1.2\text{ V}$ ; $V_O = 0.5\text{ V to }V_{CC}$ ; $V_I = \text{GND or }V_{CC}$ ; $n\text{OE} = \text{don't care}$ <sup>[4]</sup>   | -              | 1                  | $\pm 100$ | $\mu\text{A}$ |
| $I_{OZ}$   | OFF-state output current           | $V_{CC} = 2.7\text{ V}$ ; $V_I = V_{IL}$ or $V_{IH}$   |                |                    |           |               |
|  |                                    | output HIGH-state; $V_O = 2.3\text{ V}$  | -              | 0.5                | 5         | $\mu\text{A}$ |
|  |                                    | output LOW-state; $V_O = 0.5\text{ V}$   | -              | 0.5                | -5        | $\mu\text{A}$ |
| $I_{CC}$   | supply current                     | $V_{CC} = 2.7\text{ V}$ ; $V_I = \text{GND or }V_{CC}$ ; $I_O = 0\text{ A}$  |                |                    |           |               |
|  |                                    | outputs HIGH-state   | -              | 0.04               | 0.1       | mA            |
|  |                                    | outputs LOW-state  | -              | 2.3                | 4.5       | mA            |
|  |                                    | outputs disabled <sup>[5]</sup>  |                | 0.04               | 0.1       | mA            |
| $\Delta I_{CC}$  | additional supply current          | per input pin; $V_{CC} = 2.3\text{ V to }2.7\text{ V}$ ; one input at $V_{CC} - 0.6\text{ V}$ ; other inputs at $V_{CC}$ or GND <sup>[6]</sup> | -              | 0.04               | 0.4       | mA            |
| $C_I$  | input capacitance                  | $V_I = 0\text{ V or }V_{CC}$   | -              | 3                  | -         | pF            |
| $C_O$  | output capacitance                 | $V_O = 0\text{ V or }V_{CC}$   | -              | 9                  | -         | pF            |

## 20-bit bus interface D-type flip-flop; positive-edge trigger; 3-state

| Symbol                                | Parameter                          | Conditions   | Min                   | Typ <sup>[1]</sup> | Max  | Unit |    |
|---------------------------------------|------------------------------------|--|-----------------------|--------------------|------|------|----|
| <b>V<sub>CC</sub> = 3.3 V ± 0.3 V</b> |                                    |  |                       |                    |      |      |    |
| V <sub>IK</sub>                       | input clamping voltage             | V <sub>CC</sub> = 3.0 V; I <sub>IK</sub> = -18 mA  | -                     | -0.85              | -1.2 | V    |    |
| V <sub>IH</sub>                       | HIGH-level input voltage           |  | 2.0                   | -                  | -    | V    |    |
| V <sub>IL</sub>                       | LOW-level input voltage            |  | -                     | -                  | 0.8  | V    |    |
| V <sub>OH</sub>                       | HIGH-level output voltage          | V <sub>CC</sub> = 3.0 V to 3.6 V; I <sub>O</sub> = -100 μA   | V <sub>CC</sub> - 0.2 | V <sub>CC</sub>    | -    | V    |    |
|                                       |                                    | V <sub>CC</sub> = 3.0 V; I <sub>O</sub> = -32 mA   | 2.0                   | 2.3                | -    | V    |    |
| V <sub>OL</sub>                       | LOW-level output voltage           | V <sub>CC</sub> = 3.0 V  |                       |                    |      |      |    |
|                                       |                                    | I <sub>O</sub> = 100 μA  | -                     | 0.07               | 0.2  | V    |    |
|                                       |                                    | I <sub>O</sub> = 16 mA   | -                     | 0.25               | 0.4  | V    |    |
|                                       |                                    | I <sub>O</sub> = 32 mA   | -                     | 0.3                | 0.5  | V    |    |
| V <sub>OL(pu)</sub>                   | power-up LOW-level output voltage  | V <sub>CC</sub> = 3.0 V; I <sub>O</sub> = 64 mA  | -                     | 0.4                | 0.55 | V    |    |
|                                       |                                    | V <sub>CC</sub> = 3.6 V; I <sub>O</sub> = 1 mA; V <sub>I</sub> = V <sub>CC</sub> or GND  | [2]                   | -                  | -    | 0.55 | V  |
| I <sub>I</sub>                        | input leakage current              | all input pins;  | [3]                   |                    |      |      |    |
|                                       |                                    | V <sub>CC</sub> = 0 V or 3.6 V; V <sub>I</sub> = 5.5 V   | -                     | 0.1                | 10   | μA   |    |
|                                       |                                    | control pins   |                       |                    |      |      |    |
|                                       |                                    | V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = V <sub>CC</sub> or GND   | -                     | 0.1                | ±1   | μA   |    |
|                                       |                                    | data pins;   | [3]                   |                    |      |      |    |
| I <sub>OFF</sub>                      | power-off leakage current          | V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = V <sub>CC</sub>  | -                     | 0.5                | 1    | μA   |    |
|                                       |                                    | V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = 0 V  | -                     | 0.1                | -5   | μA   |    |
| I <sub>OFF</sub>                      | power-off leakage current          | V <sub>CC</sub> = 0 V; V <sub>I</sub> or V <sub>O</sub> = 0 V to 4.5 V   | -                     | 0.1                | ±100 | μA   |    |
| I <sub>BHL</sub>                      | bus hold LOW current               | data inputs; V <sub>CC</sub> = 3 V; V <sub>I</sub> = 0.8 V   | 75                    | 130                | -    | μA   |    |
| I <sub>BHH</sub>                      | bus hold HIGH current              | data inputs; V <sub>CC</sub> = 3 V; V <sub>I</sub> = 2.0 V   | -75                   | -140               | -    | μA   |    |
| I <sub>BHLO</sub>                     | bus hold LOW overdrive current     | data inputs; V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = 0 V to 3.6 V  | [7]                   | 500                | -    | μA   |    |
| I <sub>BHHO</sub>                     | bus hold HIGH overdrive current    | data inputs; V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = 0 V to 3.6 V  | [7]                   | -500               | -    | μA   |    |
| I <sub>EX</sub>                       | external current                   | output in HIGH-state when V <sub>O</sub> > V <sub>CC</sub> ;<br>V <sub>O</sub> = 5.5 V; V <sub>CC</sub> = 3.0 V                                  | -                     | 10                 | 125  | μA   |    |
| I <sub>O(pu/pd)</sub>                 | power-up/power-down output current | V <sub>CC</sub> ≤ 1.2 V; V <sub>O</sub> = 0.5 V to V <sub>CC</sub> ;<br>V <sub>I</sub> = GND or V <sub>CC</sub> ; n $\overline{OE}$ = don't care | [8]                   | -                  | 1    | ±100 | μA |
| I <sub>OZ</sub>                       | OFF-state output current           | V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = V <sub>IL</sub> or V <sub>IH</sub>   |                       |                    |      |      |    |
|                                       |                                    | output HIGH-state; V <sub>O</sub> = 3.0 V  | -                     | 0.5                | 5    | μA   |    |
|                                       |                                    | output LOW-state; V <sub>O</sub> = 0.5 V   | -                     | 0.5                | -5   | μA   |    |
| I <sub>CC</sub>                       | supply current                     | V <sub>CC</sub> = 3.6 V; V <sub>I</sub> = GND or V <sub>CC</sub> ; I <sub>O</sub> = 0 A  |                       |                    |      |      |    |
|                                       |                                    | outputs HIGH-state   | -                     | 0.07               | 0.1  | mA   |    |
|                                       |                                    | outputs LOW-state  | -                     | 5.1                | 7    | mA   |    |
|                                       |                                    | outputs disabled   | [5]                   | -                  | 0.07 | 0.1  | mA |

20-bit bus interface D-type flip-flop; positive-edge trigger; 3-state

| Symbol          | Parameter                 | Conditions   | Min | Typ <sup>[1]</sup> | Max | Unit |
|-----------------|---------------------------|--|-----|--------------------|-----|------|
| $\Delta I_{CC}$ | additional supply current | per input pin; $V_{CC} = 3\text{ V to }3.6\text{ V}$ ; one input at $V_{CC} - 0.6\text{ V}$ ; other inputs at $V_{CC}$ or GND <sup>[6]</sup> | -   | 0.04               | 0.4 | mA   |
| $C_I$           | input capacitance         | $V_I = 0\text{ V or }V_{CC}$   | -   | 3                  | -   | pF   |
| $C_O$           | output capacitance        | $V_O = 0\text{ V or }V_{CC}$   | -   | 9                  | -   | pF   |

- [1] All typical values for  $V_{CC} = 2.5\text{ V} \pm 0.2\text{ V}$  are measured at  $V_{CC} = 2.5\text{ V}$  and  $T_{amb} = 25\text{ }^\circ\text{C}$ .  
All typical values for  $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$  are measured at  $V_{CC} = 3.3\text{ V}$  and  $T_{amb} = 25\text{ }^\circ\text{C}$ .
- [2] For valid test results, data must not be loaded into the flip-flops (or latches) after applying power.
- [3] Unused pins at  $V_{CC}$  or GND.
- [4] This parameter is valid for any  $V_{CC}$  between 0 V and 1.2 V with a transition time of up to 10 ms.  
From  $V_{CC} = 1.2\text{ V}$  to  $(2.5 \pm 0.2)\text{ V}$  a transition time of 100  $\mu\text{s}$  is permitted. This parameter is valid for  $T_{amb} = 25\text{ }^\circ\text{C}$  only.
- [5]  $I_{CC}$  with outputs disabled is measured with outputs pulled to  $V_{CC}$  or GND.
- [6] This is the increase in supply current for each input at the specified voltage level other than  $V_{CC}$  or GND.
- [7] This is the bus hold overdrive current required to force the input to the opposite logic state.
- [8] This parameter is valid for any  $V_{CC}$  between 0 V and 1.2 V with a transition time of up to 10 ms.  
From  $V_{CC} = 1.2\text{ V}$  to  $(3.3 \pm 0.3)\text{ V}$  a transition time of 100  $\mu\text{s}$  is permitted. This parameter is valid for  $T_{amb} = 25\text{ }^\circ\text{C}$  only.

## 10 Dynamic characteristics

Table 7. Dynamic characteristics

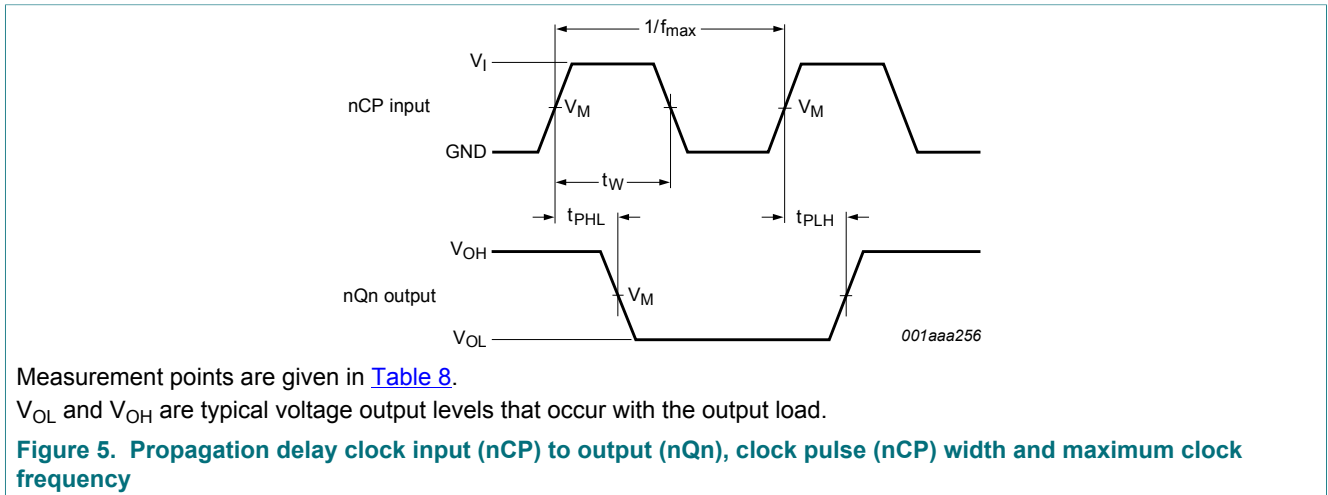
Voltages are referenced to GND (ground = 0 V);  $T_{amb} = -40\text{ }^\circ\text{C to }+85\text{ }^\circ\text{C}$ ; for test circuit see [Figure 8](#).

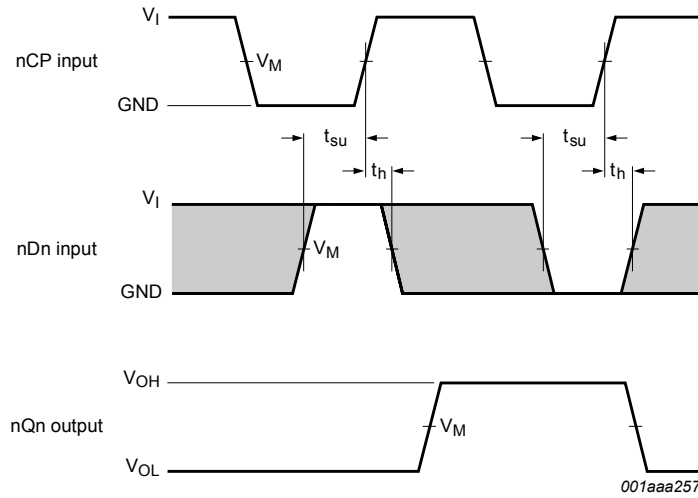
| Symbol   | Parameter                           | Conditions  | Min | Typ <sup>[1]</sup> | Max | Unit |
|--|-------------------------------------|---|-----|--------------------|-----|------|
| <b><math>V_{CC} = 2.5\text{ V} \pm 0.2\text{ V}</math></b> |                                     |   |     |                    |     |      |
| $t_{PLH}$  | LOW to HIGH propagation delay       | nCP to nQn; see <a href="#">Figure 5</a>              | 1.0 | 2.6                | 4.0 | ns   |
| $t_{PHL}$  | HIGH to LOW propagation delay       | nCP to nQn; see <a href="#">Figure 5</a>              | 1.0 | 2.7                | 4.4 | ns   |
| $t_{PZH}$  | OFF-state to HIGH propagation delay | $n\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.5 | 2.8                | 4.6 | ns   |
| $t_{PZL}$  | OFF-state to LOW propagation delay  | $n\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.0 | 1.8                | 4.1 | ns   |
| $t_{PHZ}$  | HIGH to OFF-state propagation delay | $n\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.5 | 2.7                | 4.4 | ns   |
| $t_{PLZ}$  | LOW to OFF-state propagation delay  | $n\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.0 | 2.1                | 3.3 | ns   |
| $t_{su}$   | set-up time                         | nDn to nCP; HIGH; see <a href="#">Figure 6</a>        | 1.5 | 0.1                | -   | ns   |
|  |                                     | nDn to nCP; LOW; see <a href="#">Figure 6</a>         | 2.0 | 0.5                | -   | ns   |
| $t_h$  | hold time                           | nDn to nCP; HIGH; see <a href="#">Figure 6</a>        | 0.3 | -0.5               | -   | ns   |
|  |                                     | nDn to nCP; LOW; see <a href="#">Figure 6</a>         | 0.5 | -0.1               | -   | ns   |
| $t_W$  | pulse width                         | nCP HIGH; see <a href="#">Figure 5</a>                | 1.5 | -                  | -   | ns   |
|  |                                     | nCP LOW   | 1.5 | -                  | -   | ns   |
| $f_{max}$  | maximum frequency                   | nCP; see <a href="#">Figure 5</a>                     | 150 | -                  | -   | MHz  |

| Symbol                                | Parameter                           | Conditions   | Min | Typ <sup>[1]</sup> | Max | Unit |
|---------------------------------------|-------------------------------------|--|-----|--------------------|-----|------|
| <b>V<sub>CC</sub> = 3.3 V ± 0.3 V</b> |                                     |  |     |                    |     |      |
| t <sub>PLH</sub>                      | LOW to HIGH propagation delay       | nCP to nQn; see <a href="#">Figure 5</a>               | 0.5 | 1.7                | 3.0 | ns   |
| t <sub>PHL</sub>                      | HIGH to LOW propagation delay       | nCP to nQn; see <a href="#">Figure 5</a>               | 0.5 | 1.8                | 3.2 | ns   |
| t <sub>PZH</sub>                      | OFF-state to HIGH propagation delay | n $\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.0 | 2.1                | 3.5 | ns   |
| t <sub>PZL</sub>                      | OFF-state to LOW propagation delay  | n $\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 0.5 | 1.4                | 3.0 | ns   |
| t <sub>PHZ</sub>                      | HIGH to OFF-state propagation delay | n $\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.5 | 2.9                | 4.2 | ns   |
| t <sub>PLZ</sub>                      | LOW to OFF-state propagation delay  | n $\overline{OE}$ to nQn; see <a href="#">Figure 7</a> | 1.5 | 2.4                | 3.4 | ns   |
| t <sub>su</sub>                       | set-up time                         | nDn to nCP; HIGH; see <a href="#">Figure 6</a>         | 1.5 | 0.1                | -   | ns   |
|                                       |                                     | nDn to nCP; LOW; see <a href="#">Figure 6</a>          | 1.5 | 0.1                | -   | ns   |
| t <sub>h</sub>                        | hold time                           | nDn to nCP; HIGH; see <a href="#">Figure 6</a>         | 0.5 | 0.1                | -   | ns   |
|                                       |                                     | nDn to nCP; LOW; see <a href="#">Figure 6</a>          | 0.5 | 0.1                | -   | ns   |
| t <sub>w</sub>                        | pulse width                         | nCP HIGH; see <a href="#">Figure 5</a>                 | 1.5 | -                  | -   | ns   |
|                                       |                                     | nCP LOW  | 1.5 | -                  | -   | ns   |
| f <sub>max</sub>                      | maximum frequency                   | nCP; see <a href="#">Figure 5</a>                      | 150 | -                  | -   | MHz  |

[1] All typical values for V<sub>CC</sub> = 2.5 V ± 0.2 V are measured at V<sub>CC</sub> = 2.5 V and T<sub>amb</sub> = 25 °C.  
 All typical values for V<sub>CC</sub> = 3.3 V ± 0.3 V are measured at V<sub>CC</sub> = 3.3 V and T<sub>amb</sub> = 25 °C.

### 10.1 Waveforms and test circuit



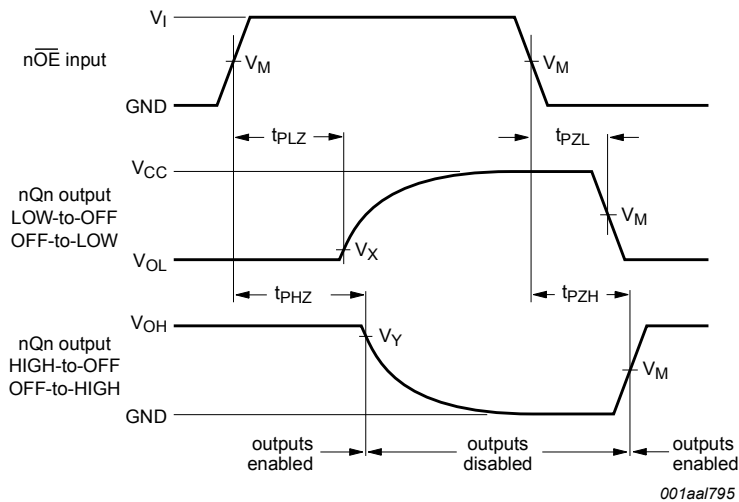


Measurement points are given in [Table 8](#).

$V_{OL}$  and  $V_{OH}$  are typical voltage output levels that occur with the output load.

The shaded areas indicate when the input is permitted to change for predictable output performance.

**Figure 6. Set-up times and hold times data input (nDn) to clock input (nCP)**



Measurement points are given in [Table 8](#).

$V_{OL}$  and  $V_{OH}$  are typical voltage output levels that occur with the output load.

**Figure 7. OFF-state to HIGH and LOW propagation delays and LOW and HIGH to OFF-state propagation delays**

**Table 8. Measurement points**

| $V_{CC}$                    | Input               | Output              |                           |                           |
|-----------------------------|---------------------|---------------------|---------------------------|---------------------------|
|                             | $V_M$               | $V_M$               | $V_X$                     | $V_Y$                     |
| $V_{CC} \leq 2.7 \text{ V}$ | $0.5 \times V_{CC}$ | $0.5 \times V_{CC}$ | $V_{OL} + 0.15 \text{ V}$ | $V_{OH} - 0.15 \text{ V}$ |
| $V_{CC} \geq 3.0 \text{ V}$ | 1.5 V               | 1.5 V               | $V_{OL} + 0.3 \text{ V}$  | $V_{OH} - 0.3 \text{ V}$  |

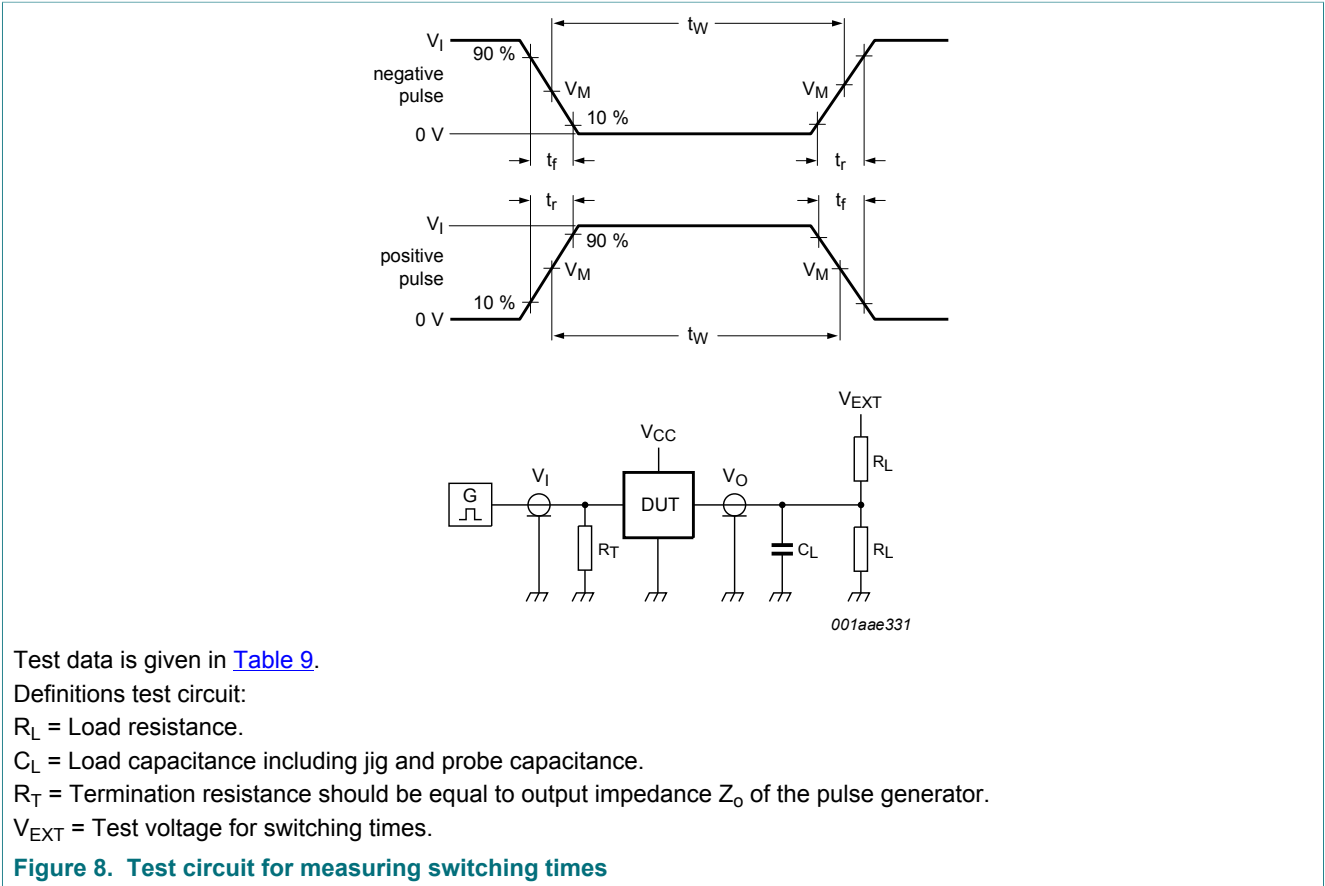


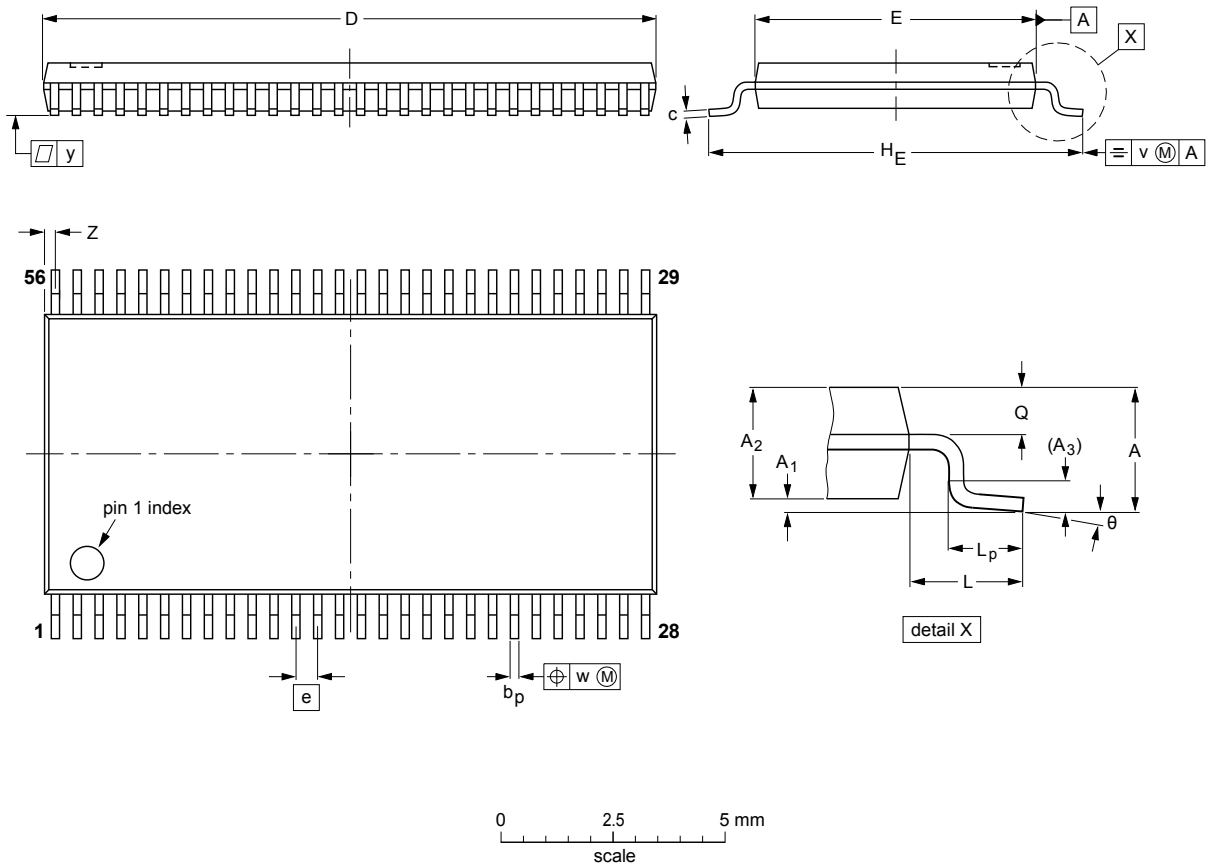
Table 9. Test data

| Input                               |               | Load   |               |       |              | $V_{EXT}$          |                          |                    |
|-------------------------------------|---------------|--------|---------------|-------|--------------|--------------------|--------------------------|--------------------|
| $V_I$                               | $f_i$         | $t_W$  | $t_r, t_f$    | $C_L$ | $R_L$        | $t_{PHZ}, t_{PZH}$ | $t_{PLZ}, t_{PZL}$       | $t_{PLH}, t_{PHL}$ |
| 3.0 V or $V_{CC}$ whichever is less | $\leq 10$ MHz | 500 ns | $\leq 2.5$ ns | 50 pF | 500 $\Omega$ | GND                | 6 V or $V_{CC} \times 2$ | open               |

11 Package outline

TSSOP56: plastic thin shrink small outline package; 56 leads; body width 6.1 mm

SOT364-1



DIMENSIONS (mm are the original dimensions).

| UNIT | A max. | A <sub>1</sub> | A <sub>2</sub> | A <sub>3</sub> | b <sub>p</sub> | c          | D <sup>(1)</sup> | E <sup>(2)</sup> | e   | H <sub>E</sub> | L | L <sub>p</sub> | Q            | v    | w    | y   | Z          | θ        |
|------|--------|----------------|----------------|----------------|----------------|------------|------------------|------------------|-----|----------------|---|----------------|--------------|------|------|-----|------------|----------|
| mm   | 1.2    | 0.15<br>0.05   | 1.05<br>0.85   | 0.25           | 0.28<br>0.17   | 0.2<br>0.1 | 14.1<br>13.9     | 6.2<br>6.0       | 0.5 | 8.3<br>7.9     | 1 | 0.8<br>0.4     | 0.50<br>0.35 | 0.25 | 0.08 | 0.1 | 0.5<br>0.1 | 8°<br>0° |

Notes

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

| OUTLINE VERSION | REFERENCES |        |       | EUROPEAN PROJECTION | ISSUE DATE           |
|-----------------|------------|--------|-------|---------------------|----------------------|
|                 | IEC        | JEDEC  | JEITA |                     |                      |
| SOT364-1        |            | MO-153 |       |                     | 99-12-27<br>03-02-19 |

Figure 9. Package outline SOT364-1 (TSSOP56)

## 12 Abbreviations

Table 10. Abbreviations

| Acronym | Description                                     |
|---------|---|
| BICMOS  | Bipolar Complementary Metal Oxide Semiconductor |
| DUT     | Device Under Test                               |
| ESD     | ElectroStatic Discharge                         |
| MIL     | Military  |
| MM      | Machine Model                                   |
| MOS     | Metal Oxide Semiconductor                       |

## 13 Revision history

Table 11. Revision history

| Document ID     | Release date  | Data sheet status     | Change notice | Supersedes      |
|-----------------|---|-----------------------|---------------|-----------------|
| 74ALVT16821 v.4 | 20180122  | Product data sheet    | -             | 74ALVT16821 v.3 |
| Modifications:  | <ul style="list-style-type: none"> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type number 74ALVT16821DL (SOT371-1 / SSOP56) removed.</li> </ul>   |                       |               |                 |
| 74ALVT16821 v.3 | 20050613  | Product data sheet    | -             | 74ALVT16821 v.2 |
| Modifications:  | <ul style="list-style-type: none"> <li>The format of this data sheet has been redesigned to comply with the new presentation and information standard of Philips Semiconductors.</li> <li><a href="#">Section 2</a>: modified 'JEDEC Std 17' into 'JESD78'.</li> <li><a href="#">Section 9</a>: changed maximum values of propagation delay, output enable time and output disable time.</li> </ul> |                       |               |                 |
| 74ALVT16821 v.2 | 19980213  | Product specification | -             | 74ALVT16821 v.1 |
| 74ALVT16821 v.1 | 19970501  | Product specification | -             | -               |

## 14 Legal information

### 14.1 Data sheet status

| Document status <sup>[1][2]</sup> | Product status <sup>[3]</sup> | Definition  |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet      | Development                   | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet    | Qualification                 | This document contains data from the preliminary specification.                       |
| Product [short] data sheet        | Production                    | This document contains the product specification.                                     |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nexperia.com>.

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Date of release: 22 January 2018  
Document identifier: 74ALVT16821

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