

# BQ27427 System-Side Impedance Track™ Fuel Gauge With Integrated Sense Resistor

## 1 Features

- Single-cell Li-ion battery fuel gauge
  - Resides on system board
  - Supports embedded or removable batteries
  - Powers directly from the battery with integrated LDO
  - Integrates low-value sense resistor: 7mΩ
- Ultra low power consumption
  - NORMAL mode: 50μA
  - SLEEP mode: 9μA
- Battery fuel gauging based on patented Impedance Track™ technology
  - Provides three selectable preprogrammed profiles for 4.2V, 4.35V, and 4.4V cells
  - Reports remaining capacity and state-of-charge (SOC) with smoothing filter
  - Adjusts automatically for battery aging, self-discharge, temperature, and rate changes
  - Estimates battery state-of-health (aging)
- Microcontroller peripheral interface supports:
  - I<sup>2</sup>C serial interface: 400kHz
  - Configurable SoC interrupt or battery low digital output warning
  - Internal temperature sensor or host reported temperature or external thermistor

## 2 Applications

- [Smartphones, feature phones, and tablets](#)
- [Wearables](#)
- [Building automation](#)
- [Portable medical and industrial handsets](#)
- [Portable audio](#)
- [Gaming](#)

## 3 Description

The Texas Instruments BQ27427 battery fuel gauge is a single-cell gauge that requires minimal user-configuration and system microcontroller firmware development, leading to quick system bring-up.

Three chemistry profiles are preprogrammed to enable minimal user-configuration and to help manage user inventory across projects with different battery chemistries. The BQ27427 battery fuel gauge has very low sleep power consumption, leading to longer battery run time. Configurable interrupts help to save system power and free the host from continuous polling. An external thermistor supports accurate temperature sensing.

The BQ27427 battery fuel gauge uses the patented Impedance Track™ algorithm for fuel gauging, and provides information such as remaining battery capacity (mAh), state-of-charge (%), and battery voltage (mV).

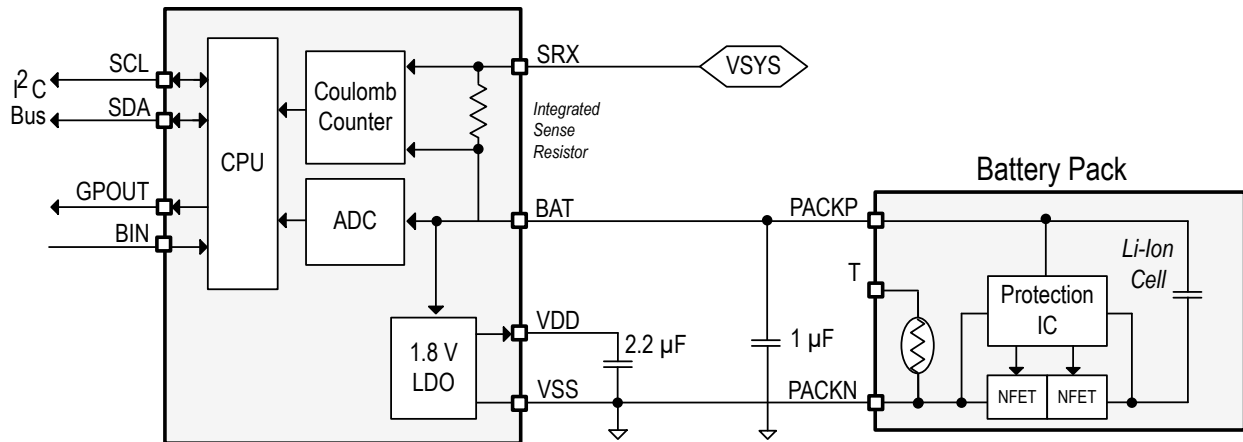
Battery fuel gauging with the BQ27427 fuel gauge requires connections only to PACK+ (P+) and PACK– (P–) for a removable battery pack or embedded battery circuit. The tiny, 9-ball, 1.62mm × 1.58mm, 0.5mm pitch NanoFree™ chip scale package (DSBGA) is appropriate for space-constrained applications.

### Package Information

PART NUMBER	PACKAGE <sup>(1)</sup>	PACKAGE SIZE <sup>(2)</sup>
BQ27427	DSBGA (YZF, 9)	1.62mm × 1.58mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

(2) The package size (length × width) is a nominal value and includes pins, where applicable.



Simplified Schematic

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## 4 Pin Configuration and Functions

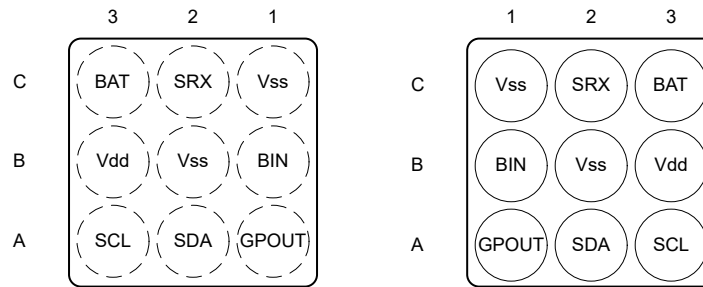


Figure 4-1. Top and Bottom View

Table 4-1. Pin Functions

PIN		TYPE <sup>(1)</sup>	DESCRIPTION
NAME	NUMBER		
BAT	C3	PI, AI	LDO regulator input and battery voltage measurement input. Kelvin sense connect to positive battery terminal (PACKP). Connect a capacitor (1 $\mu$ F) between BAT and V <sub>SS</sub> . Place the capacitor close to the gauge.
BIN	B1	DI	Battery insertion detection input. If <i>OpConfig</i> [BI_PU_EN] = 1 (default), a logic low on the pin is detected as battery insertion. For a removable pack, the BIN pin can be connected to V <sub>SS</sub> through a pull-down resistor on the pack, typically the 10k $\Omega$ thermistor; the system board should use a 1.8M $\Omega$ pullup resistor to V <sub>DD</sub> to verify the BIN pin is high when a battery is removed. If the battery is embedded in the system, leave [BI_PU_EN] = 1 and use a 10k $\Omega$ pull-down resistor from BIN to V <sub>SS</sub> . If [BI_PU_EN] = 0, then the host must inform the gauge of battery insertion and removal with the <i>BAT_INSERT</i> and <i>BAT_REMOVE</i> subcommands. Place a 10k $\Omega$ pull-down resistor between BIN and V <sub>SS</sub> , even if this pin is unused. <b>NOTE:</b> Do not short the BIN pin directly to V <sub>CC</sub> or V <sub>SS</sub> and verify that any pullup resistor on the BIN pin only connects to V <sub>DD</sub> and not an external voltage rail. If an external thermistor is used for temperature input, verify that the thermistor connected between this pin and V <sub>SS</sub> .
GPOUT	A1	DO	This open-drain output can be configured to indicate BAT_LOW when the <i>OpConfig</i> [BATLOWEN] bit is set. By default [BATLOWEN] is cleared and this pin performs an interrupt function (SOC_INT) by pulsing for specific events, such as a change in state-of-charge. Signal polarity for these functions is controlled by the [GPIOPOL] configuration bit. This pin should not be left floating, even if unused; therefore, a 10k $\Omega$ pullup resistor is recommended. If the device is in SHUTDOWN mode, toggling GPOUT will make the gauge exit SHUTDOWN. Connect GPOUT to a GPIO of the host MCU so that in case of any inadvertent shutdown condition, the gauge can be commanded to come out of SHUTDOWN.
SCL	A3	DIO	Peripheral I <sup>2</sup> C serial bus for communication with system (primary). Open-drain pins. Use with external 10k $\Omega$ pullup resistors (typical) for each pin. If the external pullup resistors are disconnected from these pins during normal operation, use external 1M $\Omega$ pull-down resistors to V <sub>SS</sub> at each pin to avoid floating inputs.
SDA	A2	DIO	
SRX	C2	AI	Integrated high-side sense resistor and coulomb counter input, connected between battery pack and system power rail VSYS.
V <sub>DD</sub>	B3	PO	1.8V regulator output. Decouple with 2.2 $\mu$ F ceramic capacitor to V <sub>SS</sub> . This pin is not intended to provide power for other devices in the system.
V <sub>SS</sub>	B2, C1	PI	Ground pin

(1) IO = Digital input-output, AI = Analog input, P = Power connection

## 5 Specifications

### 5.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
V <sub>BAT</sub>	BAT pin input voltage range	-0.3	6	V
V <sub>SRX</sub>	SRX pin input voltage range	V <sub>BAT</sub> - 0.3	V <sub>BAT</sub> + 0.3	V
V <sub>DD</sub>	V <sub>DD</sub> pin supply voltage range (LDO output)	-0.3	2	V
V <sub>IOD</sub>	Open-drain IO pins (SDA, SCL)	-0.3	6	V
V <sub>IOPP</sub>	Push-pull IO pins (BIN)	-0.3	V <sub>DD</sub> + 0.3	V
T <sub>A</sub>	Operating free-air temperature range	-40	85	°C
Storage temperature, T <sub>stg</sub>		-65	150	°C

- (1) Operation outside the Absolute Maximum Ratings may cause permanent device damage. Absolute Maximum Ratings do not imply functional operation of the device at these or any other conditions beyond those listed under Recommended Operating Conditions. If outside the Recommended Operating Conditions but within the Absolute Maximum Ratings, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

### 5.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1500	V
		Charged-device model (CDM), per JEDEC specification ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±250	

- (1) JEDEC document JEP155 states that 500V HBM allows safe manufacturing with a standard ESD control process.  
 (2) JEDEC document JEP157 states that 250V CDM allows safe manufacturing with a standard ESD control process.

### 5.3 Recommended Operating Conditions

T<sub>A</sub> = 30°C and V<sub>REGIN</sub> = V<sub>BAT</sub> = 3.6V (unless otherwise noted)

			MIN	NOM	MAX	UNIT
C <sub>BAT</sub> <sup>(1)</sup>	External input capacitor for internal LDO between BAT and V <sub>SS</sub>	Nominal capacitor values specified. Recommend a 5% ceramic X5R-type capacitor located close to the device.		0.1		µF
C <sub>LDO18</sub> <sup>(1)</sup>	External output capacitor for internal LDO between V <sub>DD</sub> and V <sub>SS</sub>			2.2		µF
V <sub>PU</sub> <sup>(1)</sup>	External pullup voltage for open-drain pins (SDA, SCL, GPOUT)		1.62	3.6		V

- (1) Specified by design. Not production tested.

### 5.4 Thermal Information

THERMAL METRIC <sup>(1)</sup>		BQ27427	UNIT
		YZF (DSBGA)	
		9 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	107.8	°C/W
R <sub>θJCTop</sub>	Junction-to-case (top) thermal resistance	0.7	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	60.4	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	3.5	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	60.4	°C/W
R <sub>θJCbott</sub>	Junction-to-case (bottom) thermal resistance	NA	°C/W

- (1) For more information about traditional and new thermal metrics, see the [IC Package Thermal Metrics Application Report, SPRA953](#).

## 5.5 Supply Current

$T_A = 30^\circ\text{C}$  and  $V_{\text{REGIN}} = V_{\text{BAT}} = 3.6\text{V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{\text{CC}}$ <sup>(1)</sup>	NORMAL mode current	$I_{\text{LOAD}} > \text{Sleep Current}$ <sup>(2)</sup>		50		$\mu\text{A}$
$I_{\text{SLP}}$ <sup>(1)</sup>	SLEEP mode current	$I_{\text{LOAD}} < \text{Sleep Current}$ <sup>(2)</sup>		9		$\mu\text{A}$
$I_{\text{SD}}$ <sup>(1)</sup>	SHUTDOWN mode current	Fuel gauge in host commanded SHUTDOWN mode. (LDO regulator output disabled)		0.6		$\mu\text{A}$

- (1) Specified by design. Not production tested.  
(2) Wake Comparator Disabled.

## 5.6 Digital Input and Output DC Characteristics

$T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ , typical values at  $T_A = 30^\circ\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{IH(OD)}}$	Input voltage, high <sup>(2)</sup>	External pullup resistor to $V_{\text{PU}}$	$V_{\text{PU}} \times 0.7$			V
$V_{\text{IH(PP)}}$	Input voltage, high <sup>(3)</sup>		1.4			V
$V_{\text{IL}}$	Input voltage, low <sup>(2) (3)</sup>				0.6	V
$V_{\text{OL}}$	Output voltage, low <sup>(2)</sup>				0.6	V
$I_{\text{OH}}$	Output source current, high <sup>(2)</sup>				0.5	mA
$I_{\text{OL(OD)}}$	Output sink current, low <sup>(2)</sup>				-3	mA
$C_{\text{IN}}$ <sup>(1)</sup>	Input capacitance <sup>(2) (3)</sup>				5	pF
$I_{\text{Ikg}}$	Input Leakage Current (SCL, SDA, BIN, GPOUT)				1	$\mu\text{A}$

- (1) Specified by design. Not production tested.  
(2) Open Drain pins: (SCL, SDA, GPOUT)  
(3) Push-Pull pin: (BIN)

## 5.7 LDO Regulator, Wake-up, and Auto-Shutdown DC Characteristics

$T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ , typical values at  $T_A = 30^\circ\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

<sup>(1)</sup>

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{BAT}}$	BAT pin regulator input		2.45		4.5	V
$V_{\text{DD}}$	Regulator output voltage			1.85		V
$UVLO_{\text{IT+}}$	$V_{\text{BAT}}$ undervoltage lock-out LDO wake-up rising threshold			2		V
$UVLO_{\text{IT-}}$	$V_{\text{BAT}}$ undervoltage lock-out LDO auto-shutdown falling threshold			1.95		V
$V_{\text{WU+}}$ <sup>(1)</sup>	GPOUT (input) LDO Wake-up rising edge threshold <sup>(2)</sup>	LDO Wake-up from SHUTDOWN mode	1.2			V

- (1) Specified by design. Not production tested.  
(2) If the device is commanded to SHUTDOWN via I<sup>2</sup>C with  $V_{\text{BAT}} > UVLO_{\text{IT+}}$ , a wake-up rising edge trigger is required on GPOUT.

## 5.8 LDO Regulator, Wake-up, and Auto-Shutdown AC Characteristics

$T_A = -40^\circ\text{C}$  to  $85^\circ\text{C}$ , typical values at  $T_A = 30^\circ\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{SHDN}}$ <sup>(1)</sup>	SHUTDOWN entry time	Time delay from SHUTDOWN command to LDO output disable.			250	ms
$t_{\text{SHUP}}$ <sup>(1)</sup>	SHUTDOWN GPOUT low time	Minimum low time of GPOUT (input) in SHUTDOWN before WAKEUP	10			$\mu\text{s}$
$t_{\text{VDD}}$ <sup>(1)</sup>	Initial $V_{\text{DD}}$ output delay			13		ms

## 5.8 LDO Regulator, Wake-up, and Auto-Shutdown AC Characteristics (continued)

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ , typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$t_{\text{WUVDD}}$ <sup>(1)</sup> Wake-up $V_{\text{DD}}$ output delay	Time delay from rising edge of GPOUT (input) to nominal $V_{\text{DD}}$ output		8		ms
$t_{\text{PUCD}}$ Power-up communication delay	Time delay from rising edge of REGIN to the Active state. Includes firmware initialization time		250		ms

(1) Specified by design. Not production tested.

## 5.9 ADC (Temperature and Cell Measurement) Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

<sup>(1)</sup>

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{IN(BAT)}}$ BAT pin voltage measurement range	Voltage divider enabled	2.45		4.5	V
$t_{\text{ADC_CONV}}$ Conversion time			125		ms
Effective resolution			15		bits

(1) Specified by design. Not tested in production.

## 5.10 Integrating ADC (Coulomb Counter) Characteristics

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

<sup>(1)</sup>

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{\text{SR}}$ Input voltage range from BAT to SRX pins			BAT $\pm$ 25		mV
$t_{\text{SR_CONV}}$ Conversion time	Single conversion		1		s
Effective Resolution	Single conversion		16		bits

(1) Specified by design. Not tested in production.

## 5.11 Integrated Sense Resistor Characteristics, $-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$

 $T_A = -40^{\circ}\text{C}$  to  $85^{\circ}\text{C}$ ; typical values at  $T_A = 30^{\circ}\text{C}$  and  $V_{\text{REGIN}} = 3.6\text{V}$  (unless otherwise noted)

<sup>(1)</sup>

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$\text{SRX}_{\text{RES}}$ <sup>(2)</sup> Resistance of Integrated Sense Resistor from SRX to $V_{\text{SS}}$	$T_A = 30^{\circ}\text{C}$		7		$\text{m}\Omega$
$I_{\text{SRX}}$ <sup>(1)</sup> Recommended sense resistor input current.	Long term RMS, average device utilization			2000	mA
	Peak RMS current, 10% device utilization, $-40^{\circ}\text{C}$ to $70^{\circ}\text{C}$ <sup>(3)</sup>			3500	
	Peak RMS current, 10% device utilization, $-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$ <sup>(3)</sup>			2500	mA
	Peak pulsed current, 250ms max, 1% device utilization, $-40^{\circ}\text{C}$ to $70^{\circ}\text{C}$ <sup>(3)</sup>			4500	
	Peak pulsed current, 250ms max, 1% device utilization, $-40^{\circ}\text{C}$ to $85^{\circ}\text{C}$ <sup>(3)</sup>			3500	mA

(1) Specified by design; not tested in production.

(2) Firmware compensation applied for temperature coefficient of resistor.

(3) Device utilization is the long-term usage profile at a specific condition compared to the average condition.

### 5.12 I<sup>2</sup>C-Compatible Interface Communication Timing Characteristics

T<sub>A</sub> = -40°C to 85°C; typical values at T<sub>A</sub> = 30°C and V<sub>REGIN</sub> = 3.6V (unless otherwise noted)

		MIN	NOM	MAX	UNIT
<b>STANDARD MODE (100kHz)</b>					
t <sub>d(STA)</sub>	Start to first falling edge of SCL	4			μs
t <sub>w(L)</sub>	SCL pulse duration (low)	4.7			μs
t <sub>w(H)</sub>	SCL pulse duration (high)	4			μs
t <sub>su(STA)</sub>	Setup for repeated start	4.7			μs
t <sub>su(DAT)</sub>	Data setup time	Host drives SDA	250		ns
t <sub>h(DAT)</sub>	Data hold time	Host drives SDA	0		ns
t <sub>su(STOP)</sub>	Setup time for stop	4			μs
t <sub>(BUF)</sub>	Bus free time between stop and start	Includes Command Waiting Time	66		μs
t <sub>f</sub>	SCL or SDA fall time <sup>(1)</sup>			300	ns
t <sub>r</sub>	SCL or SDA rise time <sup>(1)</sup>			300	ns
f <sub>SCL</sub>	Clock frequency <sup>(2)</sup>			100	kHz
<b>FAST MODE (400kHz)</b>					
t <sub>d(STA)</sub>	Start to first falling edge of SCL	600			ns
t <sub>w(L)</sub>	SCL pulse duration (low)	1300			ns
t <sub>w(H)</sub>	SCL pulse duration (high)	600			ns
t <sub>su(STA)</sub>	Setup for repeated start	600			ns
t <sub>su(DAT)</sub>	Data setup time	Host drives SDA	100		ns
t <sub>h(DAT)</sub>	Data hold time	Host drives SDA	0		ns
t <sub>su(STOP)</sub>	Setup time for stop	600			ns
t <sub>(BUF)</sub>	Bus free time between stop and start	Includes Command Waiting Time	66		μs
t <sub>f</sub>	SCL or SDA fall time <sup>(1)</sup>			300	ns
t <sub>r</sub>	SCL or SDA rise time <sup>(1)</sup>			300	ns
f <sub>SCL</sub>	Clock frequency <sup>(2)</sup>			400	kHz

- (1) Specified by design. Not production tested.
- (2) If the clock frequency (f<sub>SCL</sub>) is > 100kHz, use 1-byte write commands for proper operation. All other transactions types are supported at 400kHz. (See Section 6.3.1.1 and Section 6.3.1.3.)

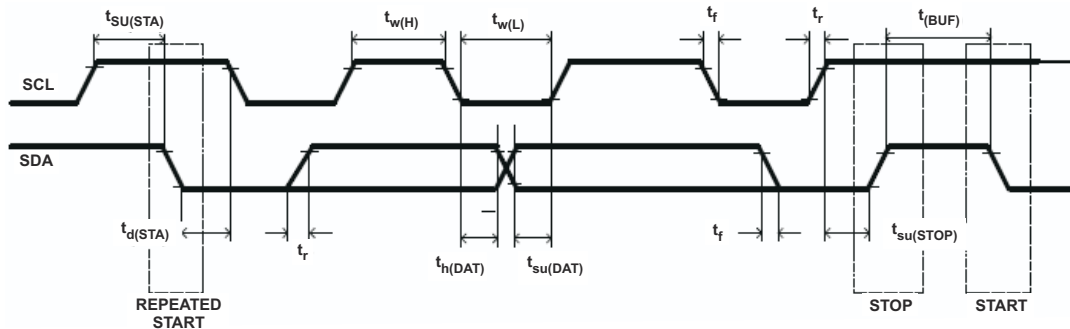
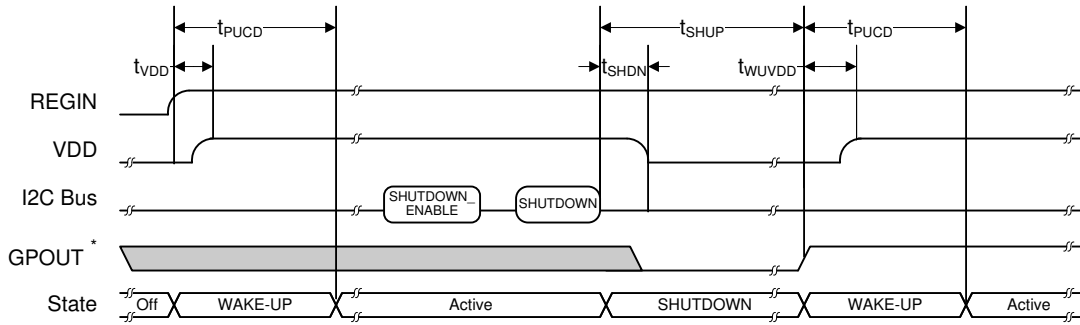


Figure 5-1. I<sup>2</sup>C-Compatible Interface Timing Diagrams

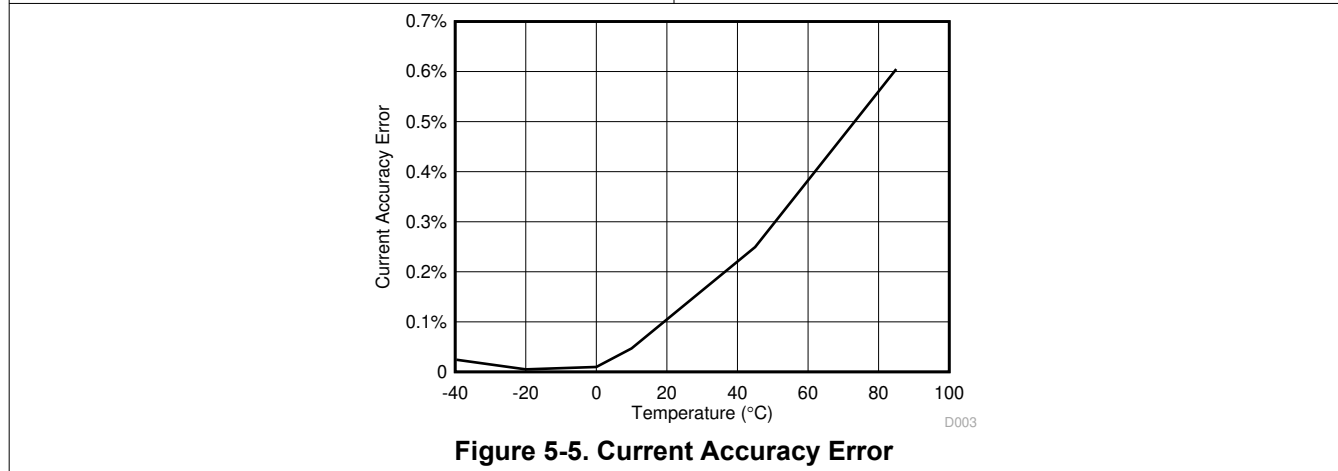
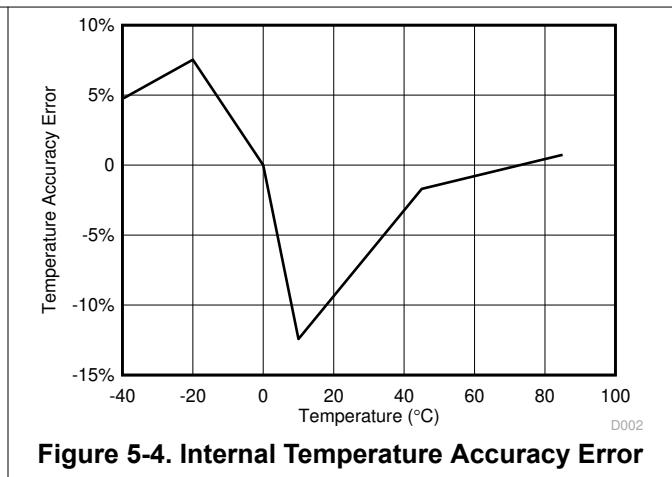
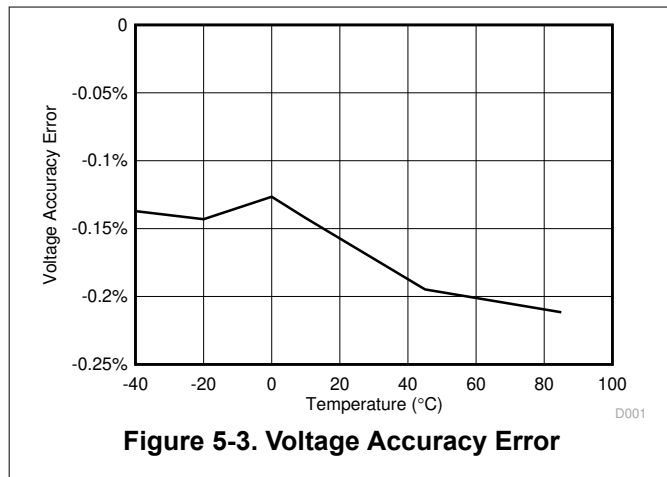
### 5.13 SHUTDOWN and WAKE-UP Timing



\* GPOUT is configured as an input for wake-up signaling.

**Figure 5-2. SHUTDOWN and WAKE-UP Timing Diagram**

### 5.14 Typical Characteristics



## 6 Detailed Description

### 6.1 Overview

The BQ27427 fuel gauge accurately predicts the battery capacity and other operational characteristics of a single Li-based rechargeable cell. Interrogate the BQ27427 fuel gauge by a system processor to provide cell information, such as state-of-charge (SOC).

#### Note

The following formatting conventions are used in this document:

**Commands:** *italics* with parentheses() and no breaking spaces, for example, *Control()*.

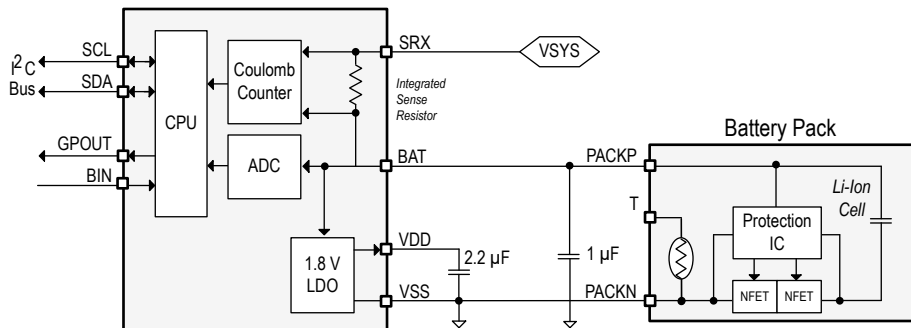
**Data flash:** *italics*, **bold**, and breaking spaces, for example, ***Design Capacity*** .

**Register bits and flags:** *italics* with brackets [ ], for example, *[TDA]*

**Data flash bits:** *italics*, **bold**, and brackets [ ], for example, ***[LED1]***

**Modes and states:** ALL CAPITALS, for example, UNSEALED mode

### 6.2 Functional Block Diagram



### 6.3 Feature Description

Access information through a series of commands, called *Standard Commands*. The additional *Extended Commands* set provide further capabilities. Both sets of commands, indicated by the general format *Command()*, are used to read and write information contained within the control and status registers, as well as data locations. The I<sup>2</sup>C serial communications engine sends commands from the system to the gauge. Execute the commands during application development, system manufacture, or end-equipment operation.

The key to the high-accuracy gas gauging prediction is the Texas Instruments proprietary Impedance Track™ algorithm. The Impedance Track™ algorithm uses cell measurements, characteristics, and properties to create state-of-charge predictions that achieve high accuracy across a wide variety of operating conditions and over the lifetime of the battery.

The fuel gauge measures the charging and discharging of the battery by monitoring the voltage across an integrated small-value sense resistor. When a cell is attached to the fuel gauge, cell impedance computes based on cell current, cell open-circuit voltage (OCV), and cell voltage under loading conditions.

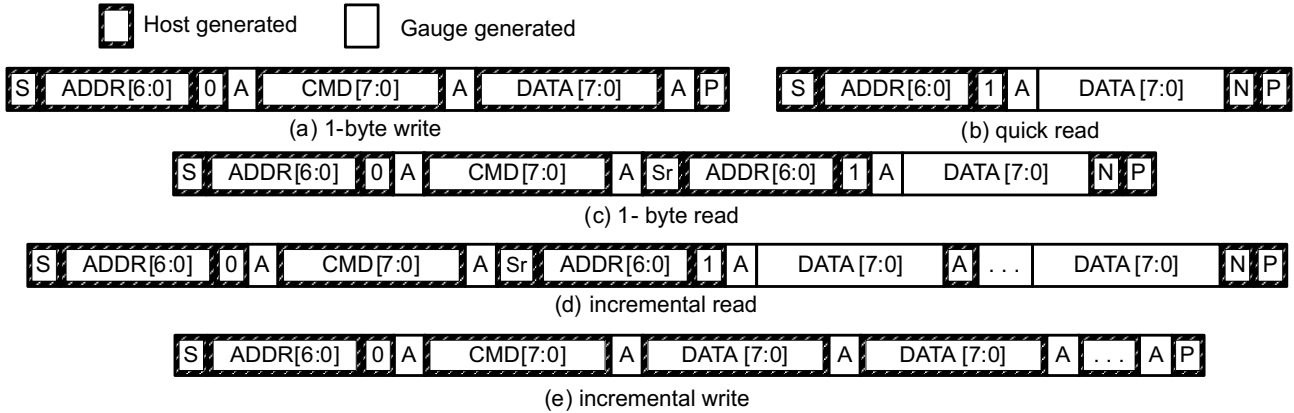
The fuel gauge uses an integrated temperature sensor for estimating cell temperature. Alternatively, the host processor provided temperature data for the fuel gauge.

For more details, see the [BQ27427 Technical Reference Manual](#).

### 6.3.1 Communications

#### 6.3.1.1 I<sup>2</sup>C Interface

The fuel gauge supports the standard I<sup>2</sup>C read, incremental read, quick read, one-byte write, and incremental write functions. The 7-bit device address (ADDR) is the most significant 7 bits of the hex address and is fixed as 1010101. The first 8 bits of the I<sup>2</sup>C protocol are 0xAA for write or 0xAB for read.

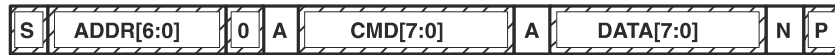


(S = Start, Sr = Repeated Start, A = Acknowledge, N = No Acknowledge, and P = Stop).

**Figure 6-1. I<sup>2</sup>C Interface**

The quick read returns data at the address indicated by the address pointer. The address pointer, a register internal to the I<sup>2</sup>C communication engine, increments whenever data is acknowledged by the fuel gauge or the I<sup>2</sup>C primary. The *Quick writes* functions in the same manner and are a convenient means of sending multiple bytes to consecutive command locations (such as two-byte commands that require two bytes of data).

The following command sequences are not supported:



**Figure 6-2. Attempt To Write a Read-only Address (NACK After Data Sent By Primary)**



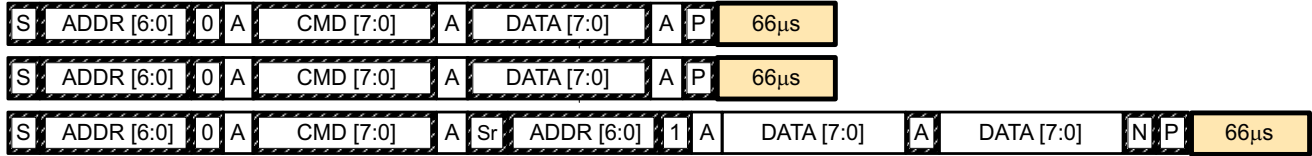
**Figure 6-3. Attempt To Read an Address Above 0x6B (NACK Command)**

#### 6.3.1.2 I<sup>2</sup>C Time Out

The I<sup>2</sup>C engine releases SDA and SCL if the I<sup>2</sup>C bus is held low for two seconds. If the fuel gauge is holding the lines, releasing them frees them for the primary to drive the lines. If an external condition is holding either of the lines low, the I<sup>2</sup>C engine enters the low-power SLEEP mode.

#### 6.3.1.3 I<sup>2</sup>C Command Waiting Time

For proper operation at 400kHz, insert a  $t_{(BUF)} \geq 66\mu s$  bus-free waiting time between all of the packets addressed to the fuel gauge. In addition, if the SCL clock frequency ( $f_{SCL}$ ) is  $> 100kHz$ , use individual 1-byte write commands for proper data flow control. The following diagram shows the standard waiting time required between issuing the control subcommand the reading the status result. For read-write standard command, a minimum of 2 seconds is required to update the results. For read-only standard commands, there is no waiting time required, but the host must not issue any standard command more than two times per second. Otherwise, the gauge can result in a reset issue due to the expiration of the watchdog timer.



Waiting time inserted between two 1-byte write packets for a subcommand and reading results  
(required for  $100 \text{ kHz} < f_{\text{scl}} \leq 400 \text{ kHz}$ )



Waiting time inserted between incremental 2-byte write packet for a subcommand and reading results  
(acceptable for  $f_{\text{scl}} \leq 100 \text{ kHz}$ )



Waiting time inserted after incremental read

**Figure 6-4. I<sup>2</sup>C Command Waiting Time**

### 6.3.1.4 I<sup>2</sup>C Clock Stretching

A clock stretch can occur during all modes of fuel gauge operation. In SLEEP mode, a short  $\leq 100\mu\text{s}$  clock stretch occurs on all I<sup>2</sup>C traffic as the device must wake-up to process the packet. In the other modes (INITIALIZATION, NORMAL), a  $\leq 4\text{ms}$  clock stretching period can occur within packets addressed for the fuel gauge as the I<sup>2</sup>C interface performs normal data-flow control.

## 6.4 Device Functional Modes

To minimize power consumption, the fuel gauge has several power modes:

- INITIALIZATION
- NORMAL
- SLEEP
- SHUTDOWN

The fuel gauge passes automatically between these modes, depending upon the occurrence of specific events. A system processor initiates some of these modes directly. For more details, see the [BQ27427 Technical Reference Manual](#).

## 7 Application and Implementation

### Note

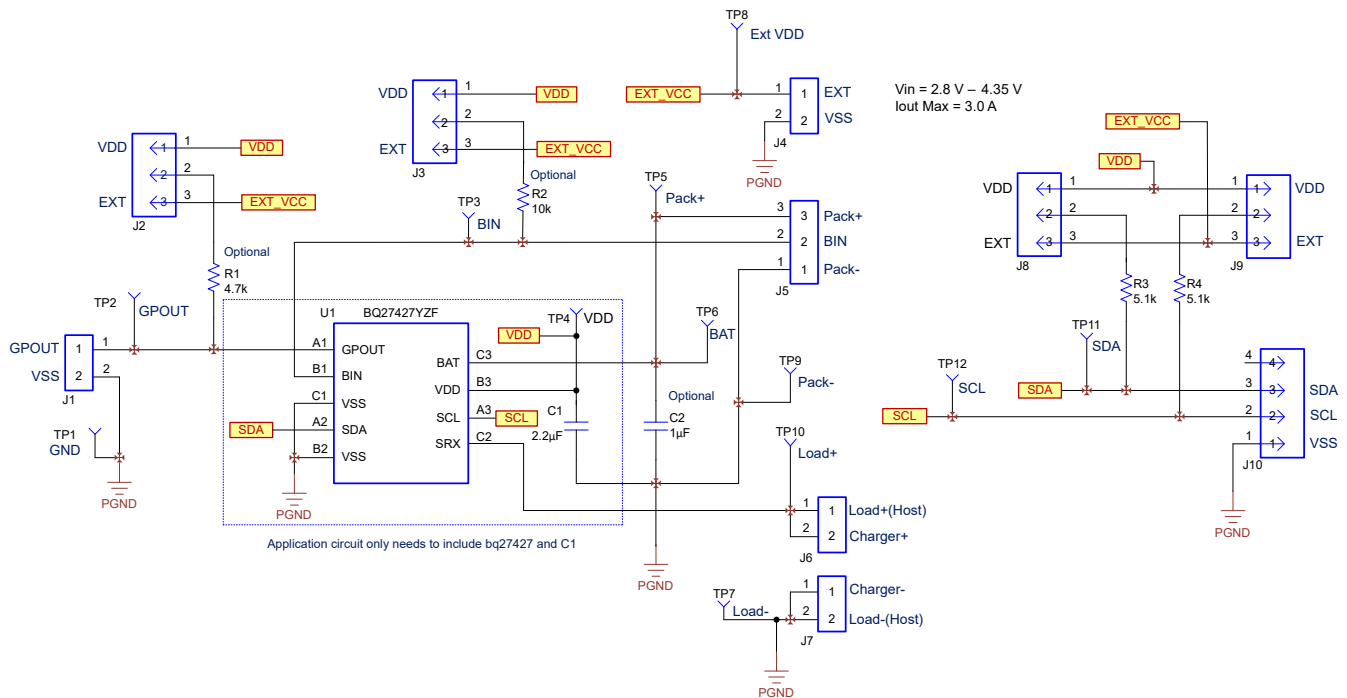
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 7.1 Application Information

The BQ27427 fuel gauge is a microcontroller peripheral that provides system-side fuel gauging for single-cell, Li-Ion batteries. Battery fuel gauging with the fuel gauge requires connections only to PACK+ and PACK– for a removable battery pack or embedded battery circuit. To allow for prime performance in the end application, take special consideration to establish minimization of measurement error through proper printed circuit board (PCB) board layout. Such requirements are detailed in [Section 7.2.1](#).

### 7.2 Typical Applications

The BQ27427 device can be used without current sense resistor (as shown in the schematic below).



**Figure 7-1. Typical Application with High-Side Current Sense Resistor**

#### 7.2.1 Design Requirements

As shipped from the Texas Instruments factory, the BQ27427 fuel gauge comes with three preprogrammed chemistry profiles and gauging parameters in ROM. Upon device reset, the contents of ROM are copied to associated volatile RAM-based data memory blocks. For proper operation, all parameters in RAM-based data memory require initialization. This can be done by updating data memory parameters in a lab/evaluation situation or by downloading the parameters from a host. The *BQ27427 Technical Reference Manual* shows the default and typically expected values appropriate for most applications.

## 7.2.2 Detailed Design Procedure

### 7.2.2.1 BAT Voltage Sense Input

Use a ceramic capacitor at the input to the BAT pin to bypass AC voltage ripple to ground, greatly reducing the BAT voltage sense input influence on battery voltage measurements. This method proves most effective in applications with load profiles that exhibit high-frequency current pulses (for example, cell phones) but is recommended for use in all applications to reduce noise on BAT, which is a sensitive high-impedance measurement node.

### 7.2.2.2 Integrated LDO Capacitor

The fuel gauge has an integrated LDO with an output on the  $V_{DD}$  pin of approximately 1.8V. Connect a capacitor with a capacitance value at least  $2.2\mu\text{F}$  between the  $V_{DD}$  pin and  $V_{SS}$ . Place the capacitor close to the gauge IC and establish short traces to both the  $V_{DD}$  and  $V_{SS}$  pins. Do not use this LDO to provide power for other devices in the system.

### 7.2.3 External Thermistor Support

The fuel gauge temperature sensing circuitry is designed to work with a negative temperature coefficient-type (NTC) thermistor with a characteristic  $10\text{k}\Omega$  resistance at room temperature ( $25^\circ\text{C}$ ). The default curve-fitting coefficients configured in the fuel gauge specifically assume a Semitec 103AT type thermistor profile and so that is the default recommendation for thermistor selection purposes. Moving to a separate thermistor resistance profile (for example, JT-2 or others) requires an update to the default thermistor coefficients which can be modified in RAM for the highest accuracy temperature measurement performance.

### 7.2.4 Application Curves

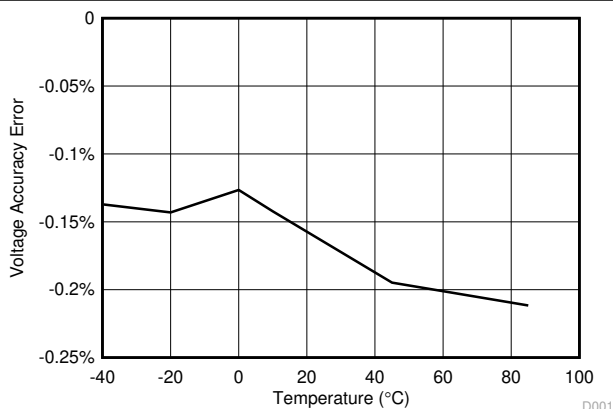


Figure 7-2. Voltage Accuracy Error

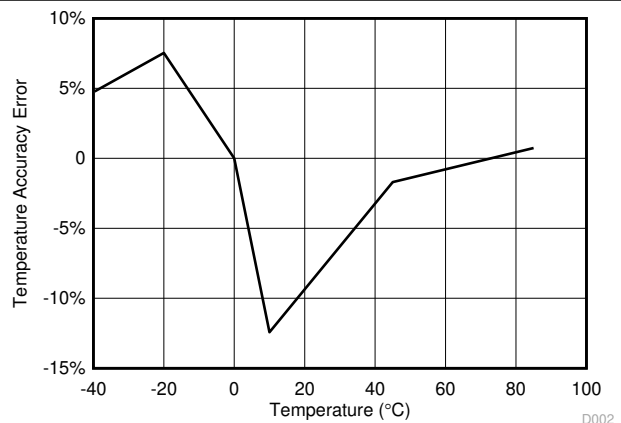


Figure 7-3. Internal Temperature Accuracy Error

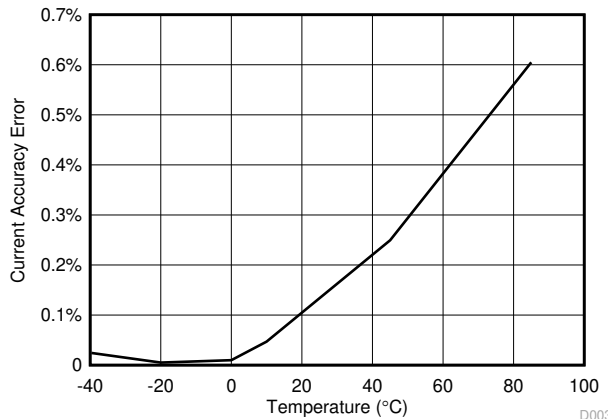


Figure 7-4. Current Accuracy Error

## 7.3 Power Supply Recommendation

### 7.3.1 Power Supply Decoupling

The battery connection on the BAT pin is used for two purposes:

- To supply power to the fuel gauge
- To provide an input for voltage measurement of the battery.

Connect a capacitor of value of at least 1  $\mu\text{F}$  between BAT and  $V_{\text{SS}}$ . Place the capacitor close to the gauge IC and have short traces to both the BAT pin and  $V_{\text{SS}}$ .

The fuel gauge has an integrated LDO with an output on the  $V_{\text{DD}}$  pin of approximately 1.8V. Connect a capacitor of value at least 2.2  $\mu\text{F}$  between the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ . Place the capacitor close to the gauge IC and have short traces to both the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ . Do not use this regulator to provide power for other devices in the system.

## 7.4 Layout

### 7.4.1 Layout Guidelines

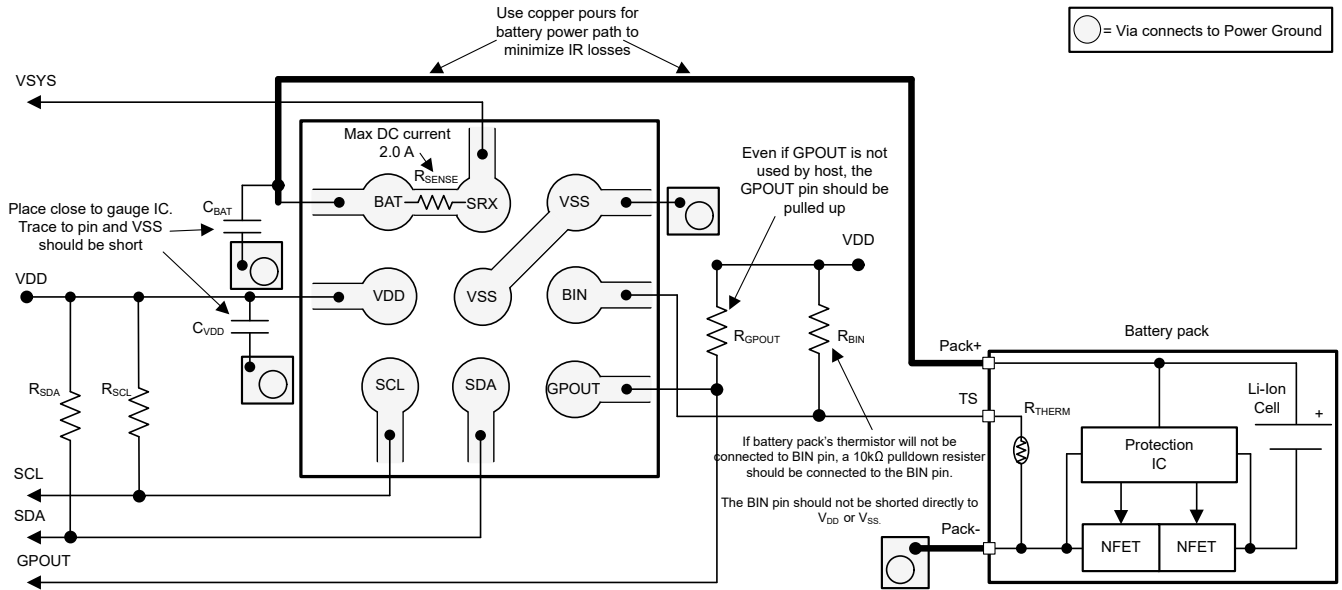
- A capacitor of a value of at least 2.2 $\mu\text{F}$  is connected between the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ . Place the capacitor close to the gauge IC and establish short traces to both the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ . Do not use the regulator to provide power for other devices in the system.
- Confirm there is a capacitor of at least 1.0 $\mu\text{F}$  that connects between the BAT pin and  $V_{\text{SS}}$  if the connection between the battery pack and the gauge BAT pin has the potential to pick up noise. Place the capacitor close to the gauge IC and provide short traces to both the  $V_{\text{DD}}$  pin and  $V_{\text{SS}}$ .
- Use external 1M $\Omega$  pull-down resistors to  $V_{\text{SS}}$  to avoid floating inputs to the I<sup>2</sup>C engine if the external pullup resistors on the SCL and SDA lines disconnect from the host during low-power operation.
- When establishing the value of the SCL and SDA pullup resistors, take into consideration the pullup voltage and the bus capacitance. Some recommended values, assuming a bus capacitance of 10pF, are in [Table 7-1](#).

**Table 7-1. Recommended Values for SCL and SDA Pullup Resistors**

VPU	1.8V		3.3V	
	Range	Typical	Range	Typical
$R_{\text{PU}}$	$400\Omega \leq R_{\text{PU}} \leq 37.6\text{k}\Omega$	10k $\Omega$	$900\Omega \leq R_{\text{PU}} \leq 29.2\text{k}\Omega$	5.1k $\Omega$

- If the host is not using the GPOUT functionality, connect GPOUT to a GPIO of the host. In cases where the device is in SHUTDOWN, toggling GPOUT wakes up the gauge from the SHUTDOWN state.
- If the battery pack thermistor is not connected to the BIN pin, pull down the BIN pin to  $V_{\text{SS}}$  with a 10k $\Omega$  resistor.
- Do not directly short the BIN pin to  $V_{\text{DD}}$  or  $V_{\text{SS}}$ .
- The actual device ground is  $V_{\text{SS}}$ .
- Kelvin connects the BAT pin to the battery PACKP terminal.

### 7.4.2 Layout Example



**Figure 7-5. BQ27427 Board Layout**

## 8 Device and Documentation Support

### 8.1 Documentation Support

#### 8.1.1 Third-Party Products Disclaimer

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#### 8.1.2 Related Documentation

- Texas Instruments, [BQ27427 Technical Reference Manual](#)
- Texas Instruments, [ESD and RF Mitigation in Handheld Battery Electronics application note](#)
- Texas Instruments, [Single Cell Gas Gauge Circuit Design application note](#)
- Texas Instruments, [Single Cell Impedance Track Printed-Circuit Board Layout Guide application note](#)

### 8.2 Trademarks

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### 8.3 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 8.4 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

## 9 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision A (October 2023) to Revision B (September 2025)	Page
• Updated the numbering format for tables, figures, and cross-references throughout the document.....	1
• Updated <i>Top and Bottom View</i> diagram with pin names.....	3

Changes from Revision * (December 2022) to Revision A (October 2023)	Page
• Updated <a href="#">Typical Applications</a> .....	12
• Changed the LDO output capacitor value from 0.47μF to 2.2μF in <a href="#">Power Supply Decoupling</a> .....	14

## 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
<a href="#">BQ27427YZFR</a>	Active	Production	DSBGA (YZF)   9	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27427
BQ27427YZFR.A	Active	Production	DSBGA (YZF)   9	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	BQ27427

(1) **Status:** For more details on status, see our [product life cycle](#).

(2) **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

(3) **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

(4) **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

(5) **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

(6) **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

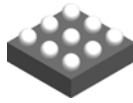
Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ27427YZFR	DSBGA	YZF	9	3000	180.0	8.4	1.78	1.78	0.69	4.0	8.0	Q1

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ27427YZFR	DSBGA	YZF	9	3000	182.0	182.0	20.0

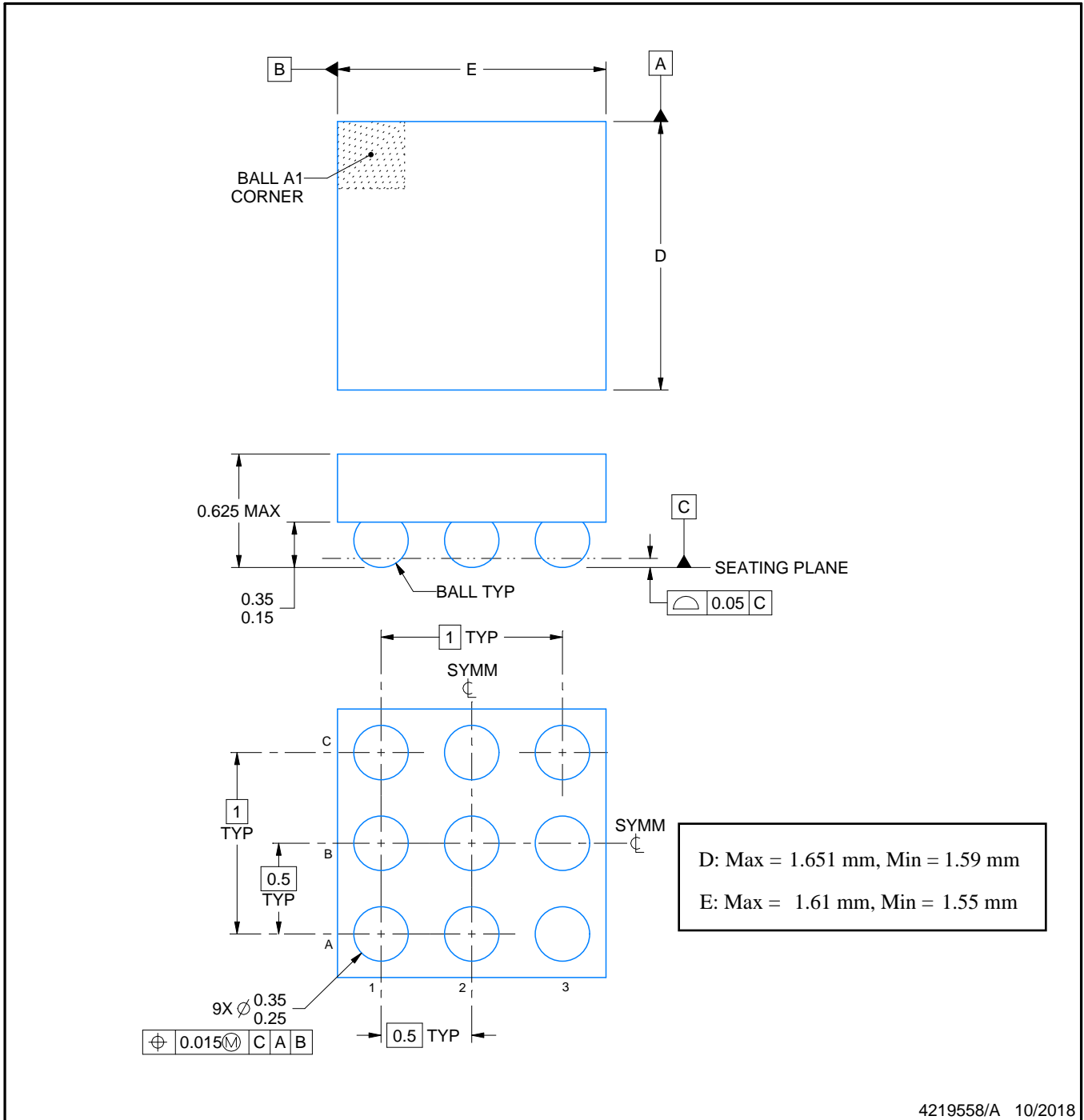
YZF0009



# PACKAGE OUTLINE

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



NOTES:

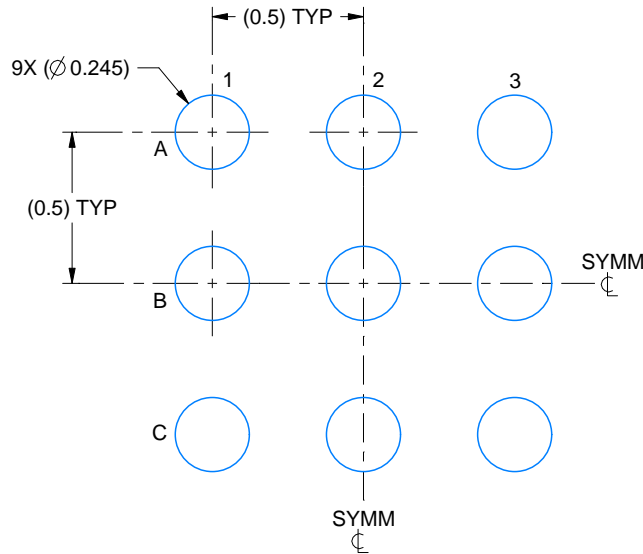
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

# EXAMPLE BOARD LAYOUT

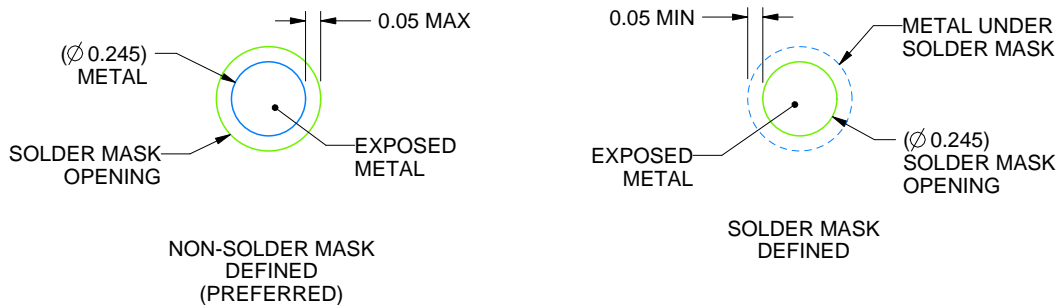
YZF0009

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE: 40X



SOLDER MASK DETAILS  
NOT TO SCALE

4219558/A 10/2018

NOTES: (continued)

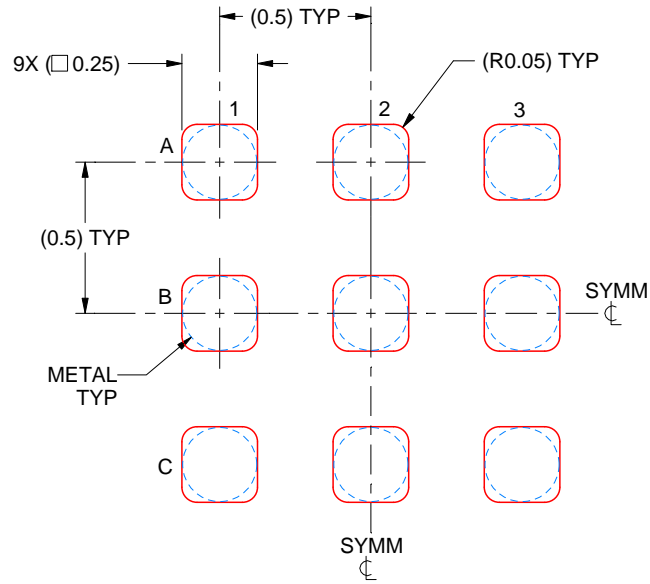
- 3. Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. See Texas Instruments Literature No. SNVA009 ([www.ti.com/lit/snva009](http://www.ti.com/lit/snva009)).

# EXAMPLE STENCIL DESIGN

YZF0009

DSBGA - 0.625 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE  
BASED ON 0.1 mm THICK STENCIL  
SCALE: 40X

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NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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