

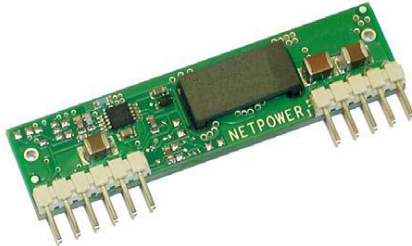


**THE DATASHEET OF
NAT1000N20R05**





20A Through-hole Point-of-Load Converter



Features

- High efficiency, 91% (12Vin, 3.3V/20A)
- Excellent thermal performance
- Over-voltage, over-current, short-circuit, and over temperature protection
- Monotonic start-up into pre-biased load
- Fixed frequency operation
- UL 60950-1 2nd edition recognized[†]

Options

- Negative / Positive enable logic
- Output over-voltage protection
- Output voltage tracking/ sequence

Part Numbering System

□□□	□	□□□	□	□□	□	□	□
Series Name	Input Voltage	Output Voltage	ON/OFF Logic	Output Current	Pin	Electrical Option	Other Option
NAT	1: 8.5-18V	000: variable*	P: positive N: negative	Unit: A 20:20A	Regular R: 0.180"	0: None 1: Voltage Tracking 2: OVP 3: Both VT&OVP 4: Synchronization 5: Both Sync & OVP	5: Open frame 6: Baseplate

* Consult the factory for semi-custom codes with the output voltage set to a specific value without using an external programming resistor.

Absolute Maximum Ratings

Excessive stresses over these absolute maximum ratings can cause permanent damage to the converter. Operation should be limited to the conditions outlined under the Electrical Specification Section.

Parameter	Symbol	Min	Max	Unit
Input Voltage (continuous)	V _i	-0.5	22	Vdc
Operating Ambient Temperature (See Thermal Consideration section)	T _o	-40	85*	°C
Storage Temperature	T _{stg}	-55	125	°C

* Derating curves provided in this datasheet end at 85°C ambient temperature. Operation above 85°C ambient temperature is allowed provided the temperatures of the key components or the baseplate do not exceed the limit stated in the Thermal Considerations section.

[†] UL is a registered trademark of Underwriters Laboratory Inc.



Electrical Specifications

These specifications are valid over the converter's full range of input voltage, resistive load, and operating temperature unless noted otherwise.

Input Specifications

Parameter	Symbol	Min	Typ	Max	Unit
Input Voltage	V_i	8.5	12	18	Vdc
Input Current	lin_Max	-	-	10	A
Quiescent Input Current (Typical V_{in})	lin_Qsnt	-	120	200	mA
Standby Input Current	lin_Stdby	-	2	-	mA
Input Reflected-ripple Current, Peak-to-peak (5 Hz to 20 MHz, 12 μ H source impedance)	-	-	20	-	mA _{p-p}
Input Ripple Rejection (120 Hz)	-	-	30	-	dB
Input Turn-on Voltage Threshold	-	-	8.3	-	V

Output Specifications

Parameter	Symbol	Min	Typ	Max	Unit
Output Voltage Set Point Accuracy (V_i = Typical V_{in} ; I_o = $I_{o,max}$; T_a = 25°C)	-	-2.0	-	+2.0	%
Output Voltage Set Point Accuracy (over all conditions)	-	-2.5	-	+3.5	%
Output Regulation:					
Line Regulation (full range input voltage, 1/2 full load)	-	-	0.2	-	% V_o
Load Regulation (full range load, Typical V_{in})	-	-	0.3	-	% V_o
Temperature (T_a = -40°C to 85 °C)	-	-	0.2	-	% V_o
Output Ripple and Noise Voltage					
RMS	-	-	-	1	% V_o
Peak-to-peak (5 Hz to 20 MHz bandwidth, Typical V_{in})	-	-	1.5	-	% V_o
External Load Capacitance	-	-	-	5,000	μ F
Output Current	I_o	0	-	20	A
Output Current-limit Trip Point (V_o = 90% of $V_{o,nom}$)	$I_{o,cli}$	-	200	-	% I_o
Efficiency (Typical V_{in} ; $I_{o,max}$, T_A = 25°C)	$V_o=0.75V$		73		%
	$V_o=1V$		78		
	$V_o=1.2V$		81		
	$V_o=1.5V$		84		
	$V_o=1.8V$		85.5		
	$V_o=2.5V$		88.5		
	$V_o=3.3V$		91		
Output Over Voltage trip point		115	125	135	% V_o
Output Ripple Frequency	-	270	300	330	kHz
Dynamic Response (V_i = Typical V_{in} ; T_a = 25°C; Load transient 0.1A/ μ s)					
Load steps from 50% to 75% of full load:					
Peak deviation			200		mV
Settling time (within 10% band of V_o deviation)			70		μ s
Load step from 50% to 25% of full load					
Peak deviation			200		mV
Settling time (within 10% band of V_o deviation)			70		μ s



General Specifications

Parameter	Symbol	Min	Typ	Max	Unit
Remote Enable Logic Low:					
$I_{ON/OFF} = 1.0\text{mA}$	$V_{ON/OFF}$	0	-	0.5	V
$V_{ON/OFF} = 0.0\text{V}$	$I_{ON/OFF}$	-	-	1.0	mA
Logic High:					
$I_{ON/OFF} = 0.0\mu\text{A}$	$V_{ON/OFF}$	3.5	-	$V_{in, \text{max}}$	V
Leakage Current	$I_{ON/OFF}$	-	-	50	μA
Calculated MTBF (Telecordia SR-332, 2011, Issue 3), full load, 40°C, 60% upper confidence level, typical V_{in}			11.7		10^6 -hour

Characteristic Curves

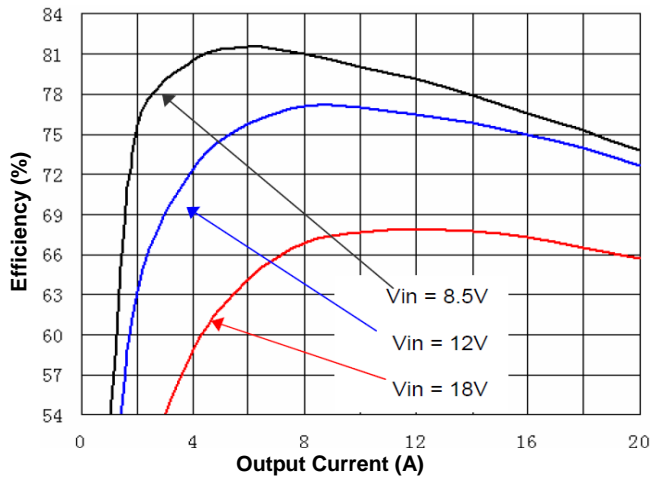


Figure 1(a). Efficiency vs. Load Current (25°C, 0.75V)

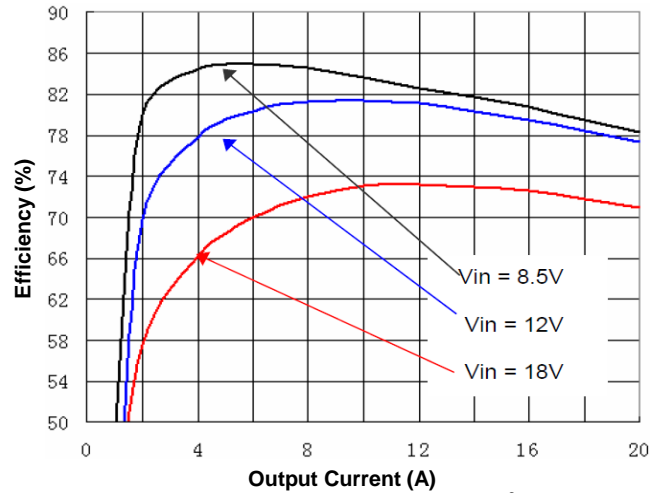


Figure 1(b). Efficiency vs. Load Current (25°C, 1.0V)

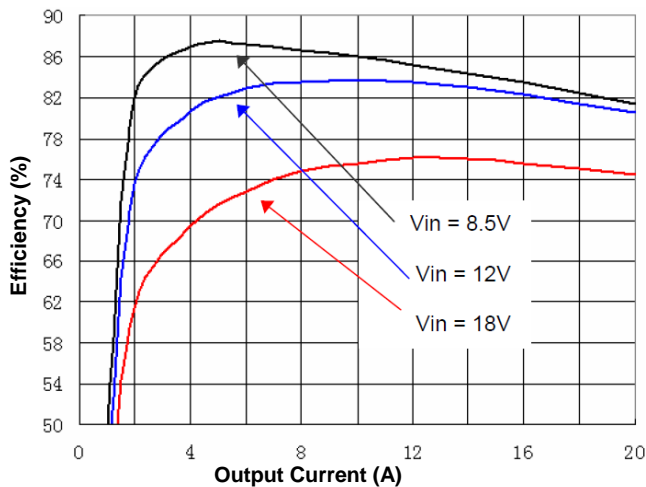


Figure 1(c). Efficiency vs. Load Current (25°C, 1.2V)

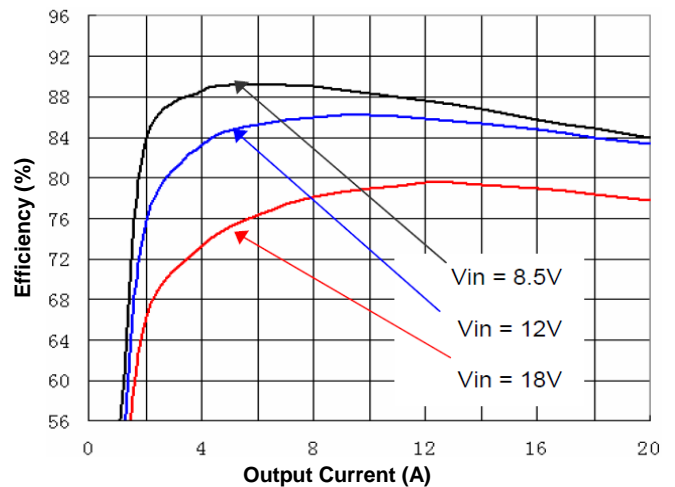


Figure 1(d). Efficiency vs. Load Current (25°C, 1.5V)

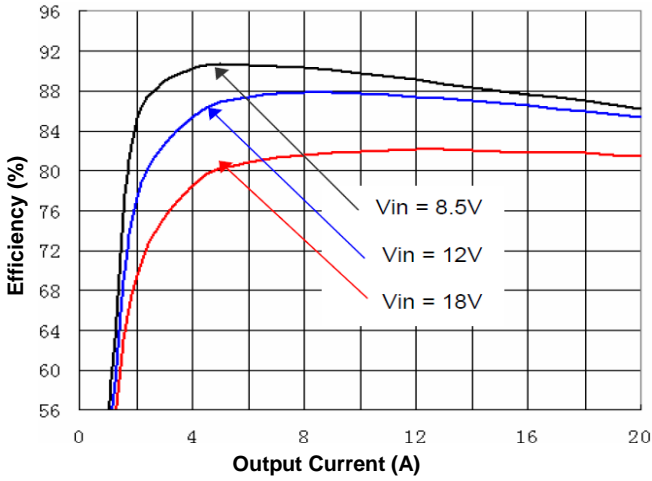


Figure 1(e). Efficiency vs. Load Current (25°C, 1.8V)

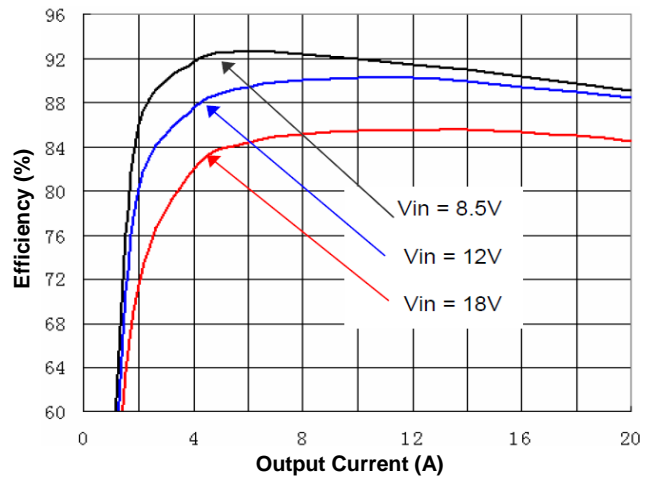


Figure 1(f). Efficiency vs. Load Current (25°C, 2.5V)

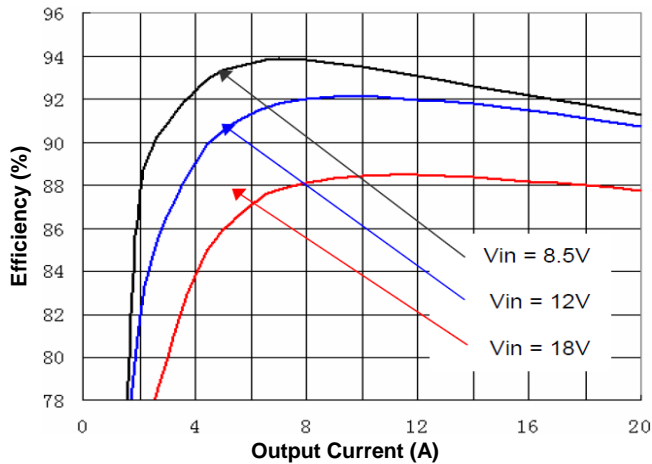


Figure 1(g). Efficiency vs. Load Current (25°C, 3.3V)

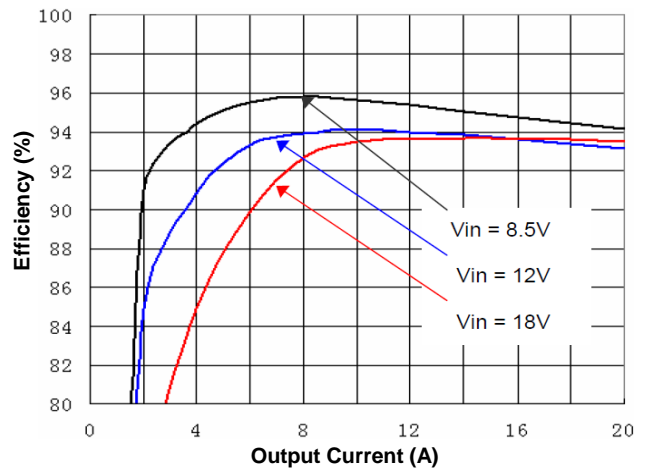


Figure 1(h). Efficiency vs. Load Current (25°C, 5V)

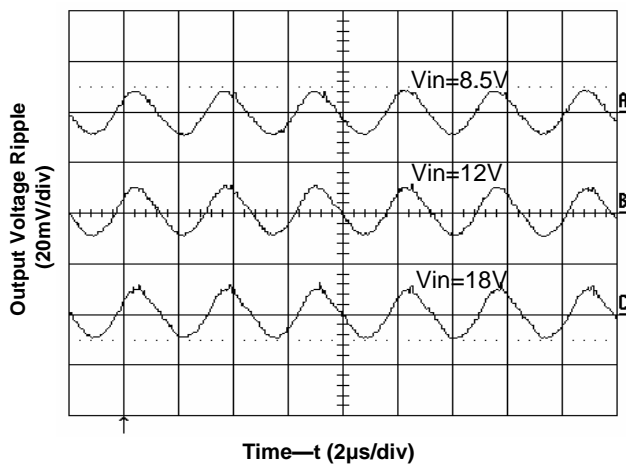


Figure 2. Output Ripple Voltage at 2.5V, 20A Output

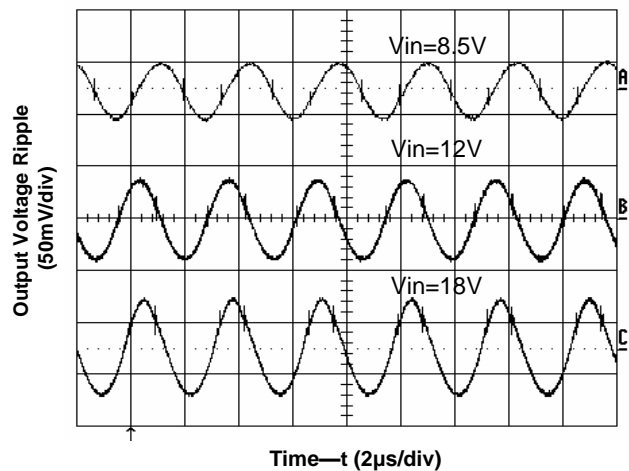


Figure 3. Output Ripple Voltage at 5V, 20A Output

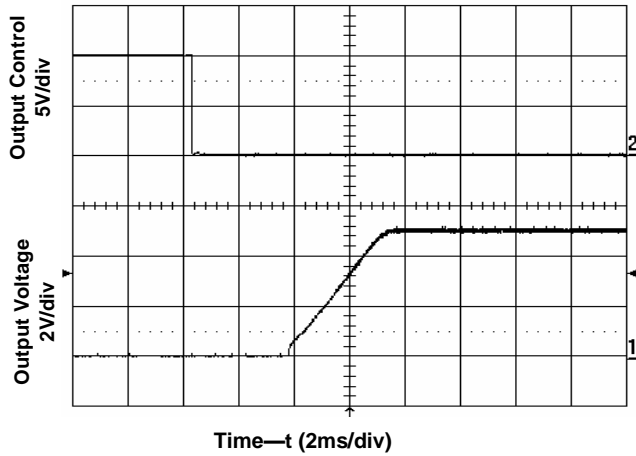


Figure 4. Start-Up from Enable Control
Input voltage 12V, Output current 0A

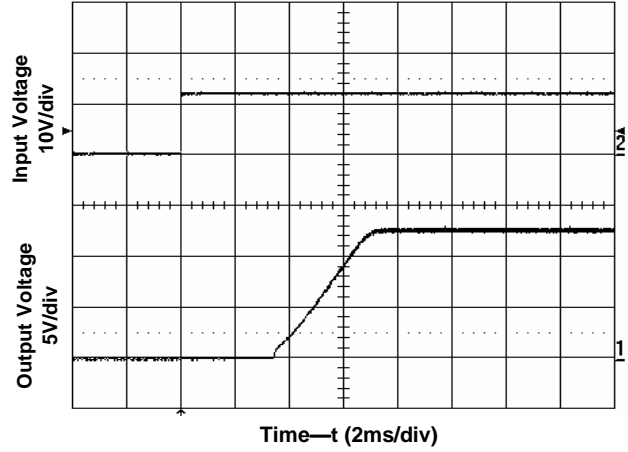


Figure 5. Start-up Application of Input Voltage
Input voltage 12V, Output current 0A

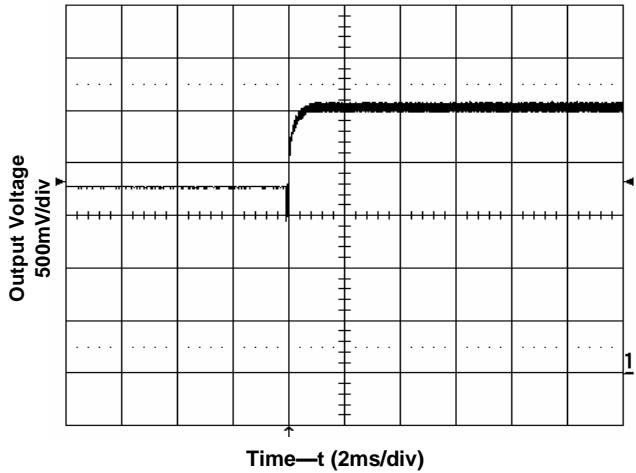


Figure 6. Start-Up with Prebias
Input voltage 12V, Output current 0A, Output voltage 2.5V, Prebias 1.2V

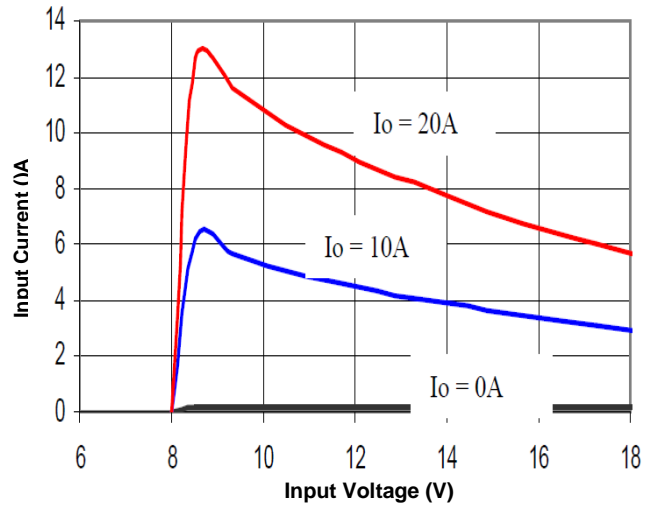


Figure 7. Input Characteristic (5V output)

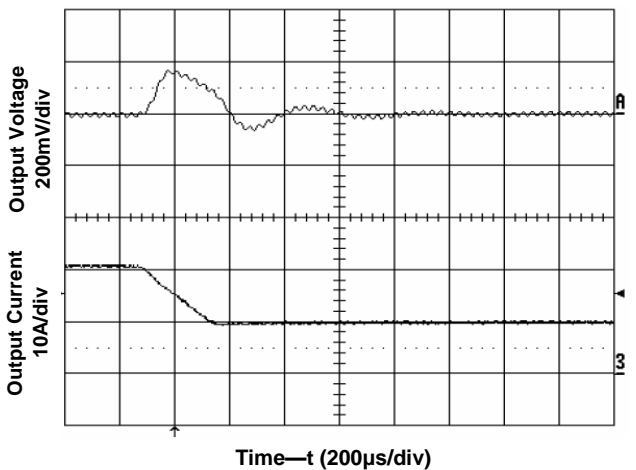


Figure 8. Transient Load Response
Input voltage 12V, Output current 20A->10A, Slew rate 0.5A/µs.

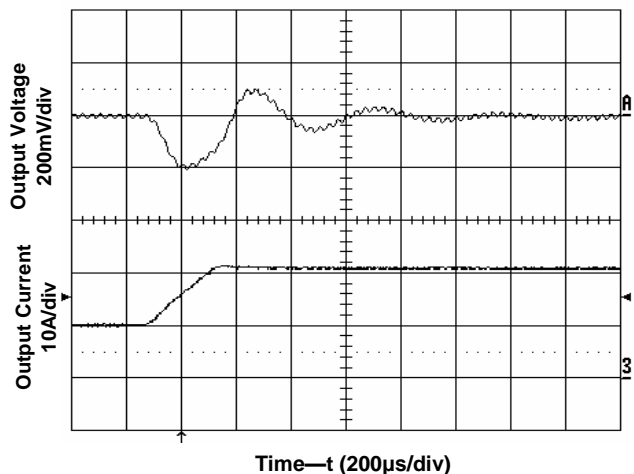


Figure 9. Transient Load Response
Input voltage 12V, Output current 10A -> 20A, Slew rate 0.5A/µs

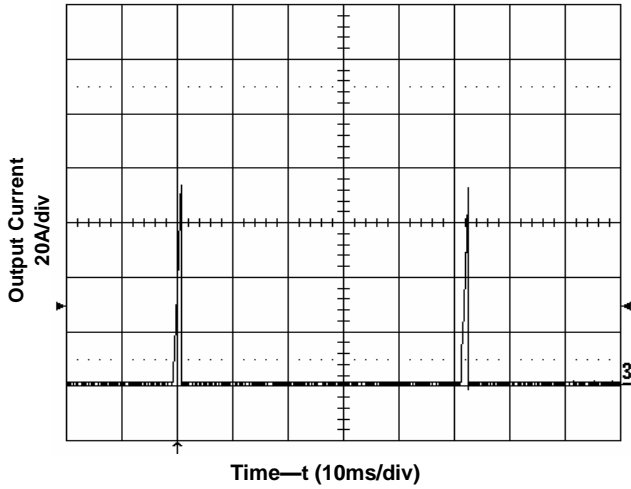


Figure 10. Short Circuit Current. $V_{in} = 12V$

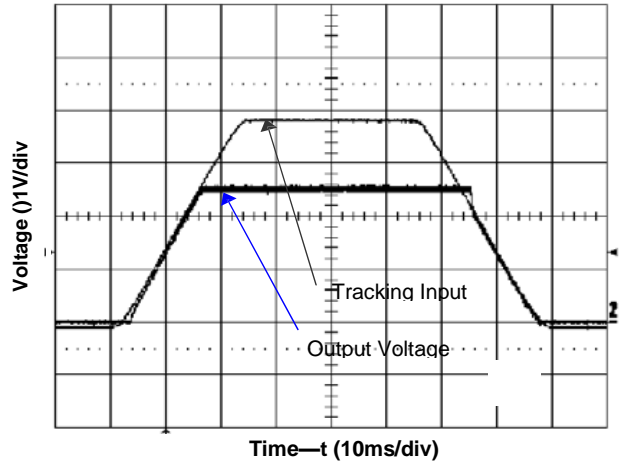


Figure 11. Voltage Tracking/Sequencing (with tracking option) $V_{in} = 12V$, $V_o = 2.5V$, $I_o = 0A$

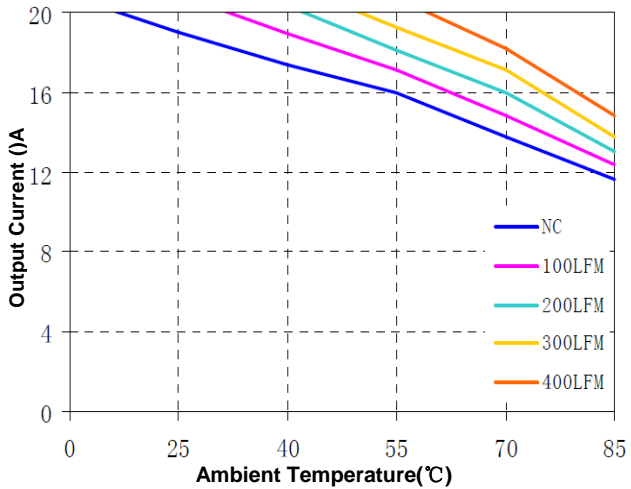


Figure 12(a). Current Derating Curve for 1.0V Output ($V_{in} = 12V$ open frame)

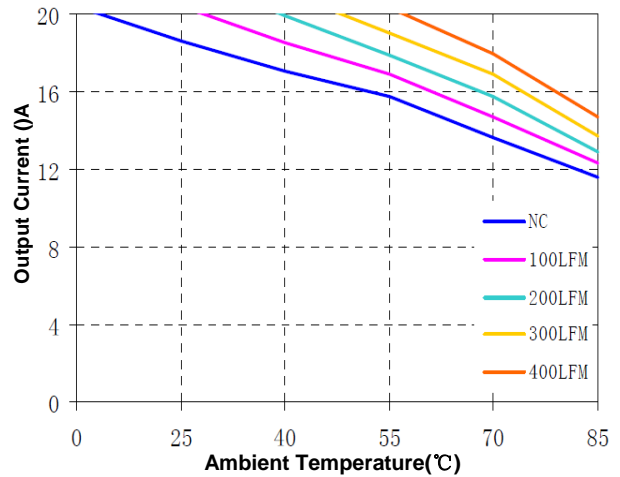


Figure 12(b). Current Derating Curve for 1.5V Output ($V_{in} = 12V$ open frame)

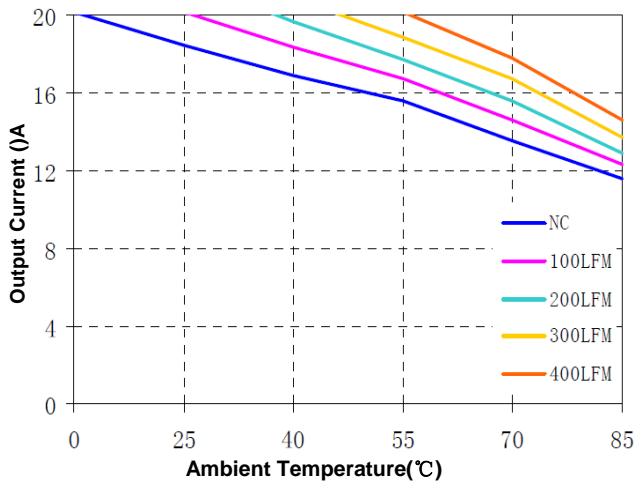


Figure 12(c). Current Derating Curve for 1.8V Output ($V_{in} = 12V$ open frame)

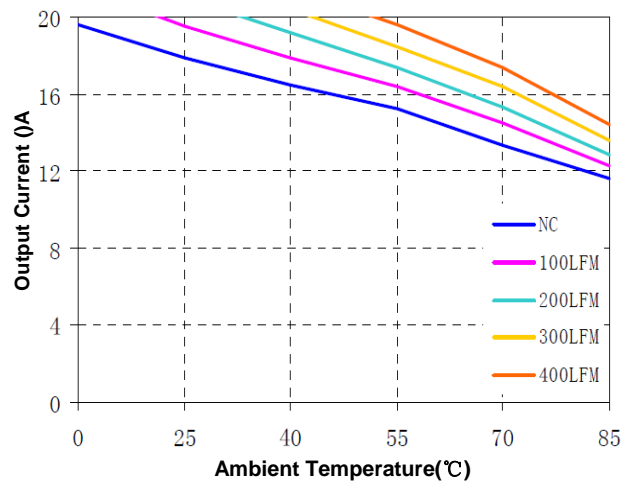


Figure 12(d). Current Derating Curve for 2.5V Output ($V_{in} = 12V$ open frame)

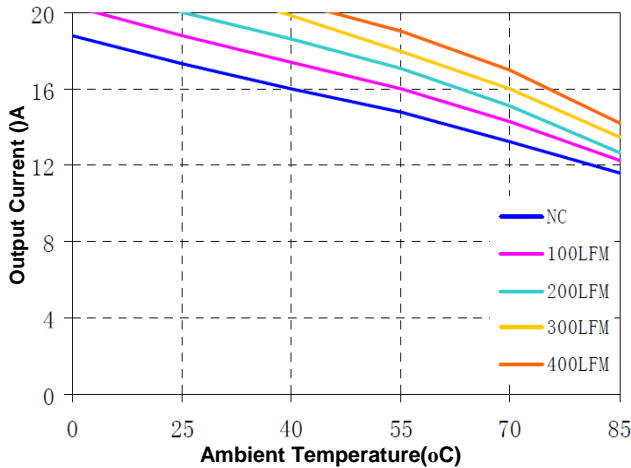


Figure 12(e). Current Derating Curve for 3.3V Output
($V_{in} = 12V$ open frame)

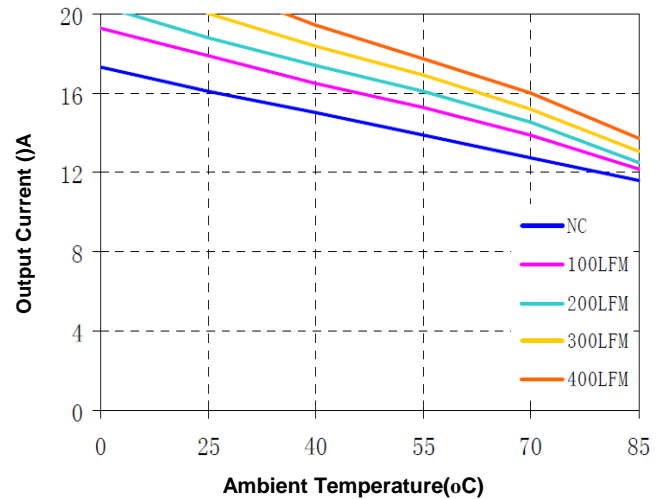


Figure 12(f). Current Derating Curve for 5V Output
($V_{in} = 12V$ open frame)

Feature Descriptions

Remote ON/OFF

The converter can be turned on and off by changing the voltage between the ON/OFF pin and $V_{in}(-)$. The NAT1 Series of converters are available with factory selectable positive logic and negative logic.

For the negative control logic, the converter is ON when the ON/OFF pin is at a logic low level and OFF when the ON/OFF pin is at a logic high level. For the positive control logic, the converter is ON when the ON/OFF pin is at a logic high level and OFF when the ON/OFF pin is at a logic low level. The converter is ON no matter what control logic is when ON/OFF pin is left open (unconnected).

Figure 13 is the recommended ON/Off control circuit for positive logic modules, while Figure 14 is for negative logic modules, Recommended value of the pull up resistor $R_{pull-up}$ is 50K. The maximum allowable leakage current from this pin at logic-high level is 20 μ A.

The logic low level is from 0V to 0.5V and the maximum sink current during logic low is 2mA. The external switch must be capable of maintaining a logic-low level while sinking up to this current.

Remote SENSE

The remote SENSE pin is used to sense the voltage at the load point to accurately regulate the load voltage and eliminate the impact of the voltage drop in the power distribution path.

The SENSE pin should be connected to the point where regulation is desired. The voltage difference between the output pins must not exceed the operating range of this converter shown in the specification table.

When remote sense is not used, the SENSE pin can be connected to the positive output terminals. If the SENSE pins are left floating, the converter will deliver an output voltage slightly higher than its specified typical output voltage.

Because the converter does not have remote sense connection for the return path, it is important to make sure that the connection resistance and voltage drop between GND pin and the load is small.

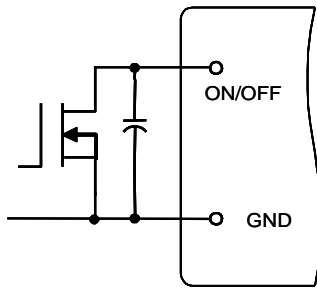


Fig. 13 Circuit for Positive Logic Control

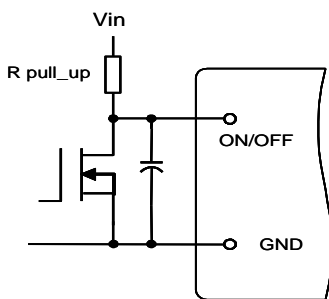


Fig. 14 Circuit for Negative Logic Control

Output Voltage Programming and Adjustment

This series of converters are available with variable output voltages. The output voltage is preset to 0.7525V, and can be programmed up to 5.5V using an external trim resistor connected between the Trim pin and GND pin as shown in Figure 15.

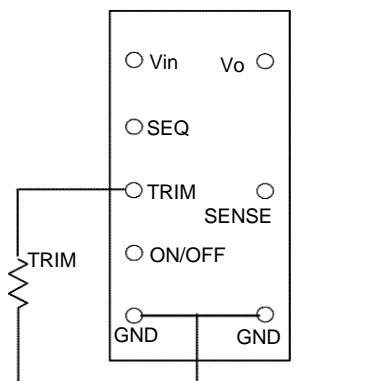


Fig. 15 Circuit to Trim Output Voltage.

The resistance of the external resistor for trimming up the output voltage can be calculated using the

equation below:

$$R_{trim} = \left(\frac{10.5}{\Delta} - 1\right)(k\Omega)$$

Where $\Delta = V_o - V_{onom}$

For variable output models, $V_{onom} = 0.7525$.

Because this converter uses GND as the reference for control, Rtrim should be placed as close to GND pin as possible, and the trace connecting GND pin and Rtrim should not carry significant current, to reduce the effect of voltage drop on the GND trace/plain affecting the output voltage accuracy.

When remote sense and trim functions are used simultaneously, please do not allow the output voltage at the converter output terminals to be outside the operating range.

Input Under-Voltage Lockout

This feature prevents the converter from turning on until the input voltage reaches 8.3V. However, for converters to output higher than 5.5V, the input under-voltage lockout setpoint is higher and the user should contact the factory for further assistance.

Output Over-Current Protection

As a standard feature, the converter turns off when the load current exceeds the current limit. If the over current or short circuit condition persists, the converter will operate in a hiccup mode (repeatedly trying to restart) until the over-current condition is cleared.

Thermal Shutdown

As a standard feature, the converter will shut down if an over-temperature condition is detected. The converter has a temperature sensor, which detects the thermal condition of key components of the converter.

The thermal shutdown circuit is designed to turn the converter off when the temperature at the sensor reaches 120°C. The converter will resume operation after the converter cools down.



Output Over-Voltage Protection

As an optional feature, if the voltage across the output pins exceeds the output voltage protection threshold as shown in the Specifications Table, the converter will clamp the output voltage to protect the converter and the load. The converter automatically resumes normal operation after the over voltage condition is removed.

The over-voltage protection setpoint is 6.25V for the adjustable output model

Voltage Tracking/Sequencing

An optional voltage tracking/sequencing feature is available with these converters. This feature is compatible with the “Voltage Sequencing” feature (DOSA) or the “Voltage Tracking” feature (POLA) seen in industry standards.

This feature forces the output of the converter to follow (track) the voltage at the SEQ pin on a 1:1 basis. When the voltage at the SEQ pin rises above the set point, the output of the converter will stay at the set point. This feature allows the user to program the output voltage waveform during turn-on and turn-off of the converter by applying a voltage signal of desired shape at the SEQ pin. When using this function, one should pay careful attention to the following aspects:

- 1). This feature is intended mainly for startup and shutdown sequencing control. In normal operation, the voltage at SEQ pin should be maintained higher than the output voltage set point;
- 2). The input voltage should be valid for this feature to work. During startup, it is recommended to have a delay of at least 10 ms between the establishment of a valid input voltage, and the application of a voltage at the SEQ pin;
- 3). The ON/OFF pin should be in “Enabled” state when this function is effective.
- 4). The converter’s pre-bias startup is affected by this function. The converter will still be able to start under a pre-bias condition, but the output voltage waveform will have a glitch during startup if this feature is selected.

Design Considerations

The stability of the NAT1 converters, as with any DC/DC converter, may be compromised if the source impedance is too high or too inductive. It’s desirable to keep the input source AC impedance as low as possible. To reduce switching frequency ripple current getting into the input circuit (especially the ground/return conductor), it is desirable to place some low ESR capacitors at the input of the converter. Due to the existence of some inductance (such as the trace inductance, connector inductance, filter inductance, etc) in the input circuitry, possible oscillation may occur at the input of the converter. Because of the relatively high input current of low input voltage power converters, it may not be practical or economical to have separate damping or soft start circuit in front of POL converters. A combination of ceramic capacitors and Tantalum/Polymer capacitors are recommended to be used at the input, so the relatively higher ERS of Tantalum/Polymer capacitors can help to damp the possible oscillation.

Similarly, although the converter is designed to be stable without external capacitor at the output, some low ESR capacitors at the output are desirable to further reduce the output voltage ripple and improve the transient response. A combination of ceramic capacitors and Tantalum/Polymer capacitors at the output usually yields good results.

Safety Considerations

The NAT1 Series of converters is designed in accordance with EN 60950 Safety of Information Technology Equipment Including Electrical Equipment. The converters are recognized by UL in both USA and Canada to meet the requirements in UL 60950, Safety of Information Technology Equipment and applicable Canadian Safety Requirement, and ULc 60950. Flammability ratings of the PWB and plastic components in the converter meet 94V-0.

The converter’s output meets SELV requirements if all of its input meets SELV requirements.

Thermal Considerations

The NAT1 converters can operate in various thermal environments. Due to high efficiency and optimal heat distribution, these converters exhibit excellent thermal performance.

The maximum allowable output power of any power converter is usually determined by the electrical design and the maximum operating temperature of its components. The NAT1 converters have been tested comprehensively under various conditions to generate the derating curves with consideration for long term reliability.

Thermal derating curves are highly influenced by derating guideline, the test conditions and setup, such as test temperatures, the interface method between the converter and the test fixture board, spacing and construction (especially copper weight, holes and openings) of the fixture board and the spacing board, temperature measurement method, and the ambient temperature measurement point. The thermal derating curves in this datasheet are obtained by thermal tests in a wind-tunnel. The converter's power pins are soldered to a 2-layer test fixture board through 18 AWG wires. The space between the test board and a PWB spacing board is 1". Usually, the end system board has more layer count, and has better thermal conductivity than our test fixture board.

Note that the natural convection condition was measured at 0.05 m/s to 0.15 m/s (10ft./min. to 30 ft./min).

Heat Transfer

Convection heat transfer is the primary cooling means for NAT1 converters. Therefore, airflow speed is important and increasing the airflow over the converter enhances the heat transfer via convection.

Figures 12 (a) - (f) show the current derating curves under typical input voltage 12V for a few output voltages. To maintain long-term reliability, the module should be operated within these curves in steady state.

Proper cooling in the end system can be verified by monitoring the temperature of the key components. Figure 16 shows the recommended temperature

monitoring points. The temperature at these locations should not exceed 120 °C continuously.

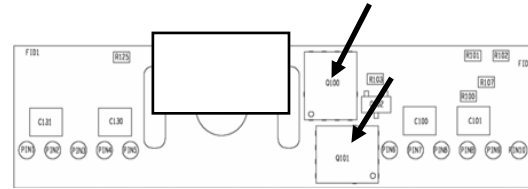


Figure 16. Temperature Monitoring Locations

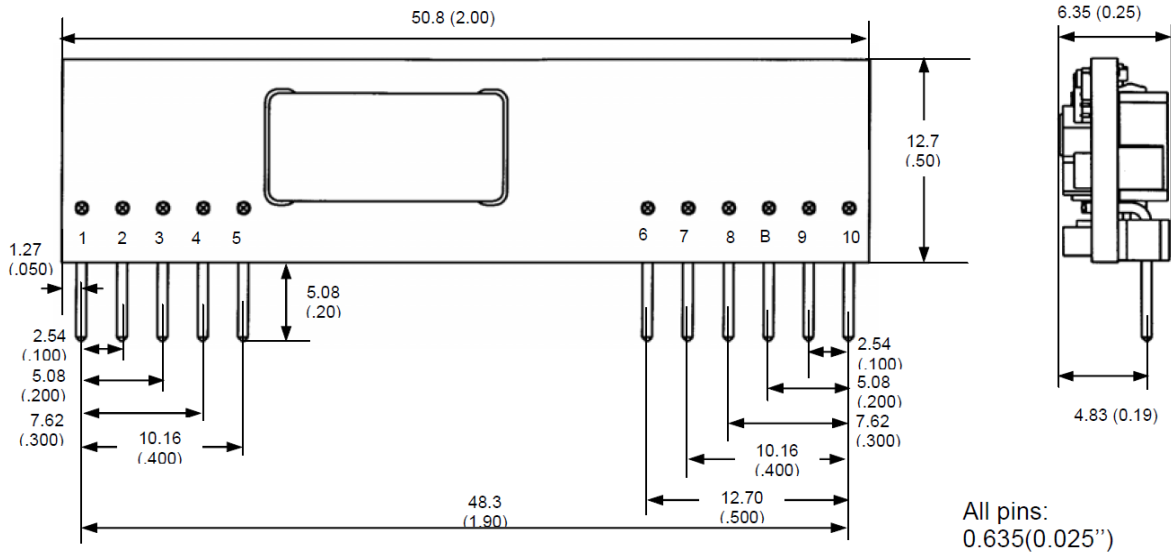
Heat Transfer with a Baseplate

The NAT1 Series of converters have the options of using a baseplate for enhanced thermal performance. The typical width of the converter with the baseplate option is 0.35".

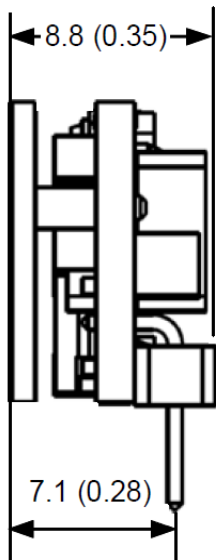
For reliable operation, the baseplate temperature should not continuously exceed 100 °C.



Mechanical Diagrams



Pin#	1	2	3	4	5	6	7	8	B	9	10
Function	Vo	Vo	Sense	Vo	GND	GND	Vin	Vin	SEQ	Trim	ON/OFF



Side View with Baseplate

Notes

- 1) All dimensions in mm (inch) (1 inch = 25.4mm). Tolerances:
.x (.xx): ± 0.5 (0.020")
.xxx: ± 0.25 (0.010")
- 2) All pins are 0.635mm (0.025") square.
- 3) A converter's thickness is increased to 0.35" with a baseplate option.
- 3) All pins are coated with 90%/10% solder finish, or Matte Tin, or Gold.
- 4) Weight: 7 g open frame converter
- 5) Workmanship: Meet or exceeds IPC-A-610 Class II
- 6) Baseplate flatness tolerance is 0.10mm (0.004") TIR for surface.

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