



**THE DATASHEET OF
MC9S08SV8CBM**





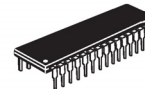
MC9S08SV16 Series

Covers: MC9S08SV16 and
MC9S08SV8

MC9S08SV16



32-Pin LQFP
873A-03



32-Pin SDIP
1376-02

Features:

- 8-Bit HCS08 Central Processor Unit (CPU)
 - Up to 40 MHz CPU at 2.7 V to 5.5 V across temperature range of –40 °C to 85 °C
 - HC08 instruction set with added BGND instruction
 - Support for up to 32 interrupt/reset sources
- On-Chip Memory
 - Up to 16 KB flash read/program/erase over full operating voltage and temperature
 - Up to 1024-byte random-access memory (RAM)
 - Security circuitry to prevent unauthorized access to RAM and flash contents
- Power-Saving Modes
 - Two low power stop modes; reduced power wait mode
 - Allows clocks to remain enabled to specific peripherals in stop3 mode
- Clock Source Options
 - Oscillator (XOSC) — Loop-control Pierce oscillator; crystal or ceramic resonator range of 31.25 kHz to 39.0625 kHz or 1 MHz to 16 MHz
 - Internal Clock Source (ICS) — Internal clock source module containing a frequency-locked-loop (FLL) controlled by internal or external reference; precision trimming of internal reference allows 0.2% resolution and 2% deviation over temperature and voltage; supporting bus frequencies up to 20 MHz
- System Protection
 - Watchdog computer operating properly (COP) reset with option to run from dedicated 1 kHz internal clock source or bus clock
 - Low-voltage detection with reset or interrupt; selectable trip points
 - Illegal opcode detection with reset
 - Illegal address detection with reset
 - Flash block protection
- Development Support
 - Single-wire background debug interface
 - Breakpoint capability to allow single breakpoint setting during in-circuit debugging (plus two more breakpoints)
- On-chip in-circuit emulator (ICE) debug module containing two comparators and nine trigger modes
- Peripherals
 - **IPC** — Interrupt priority controller to provide hardware based nested interrupt mechanism
 - **ADC** — 12-channel, 10-bit resolution; 2.5 μs conversion time; automatic compare function; 1.7 mV/°C temperature sensor; internal bandgap reference channel; operation in stop; optional hardware trigger; fully functional from 2.7 V to 5.5 V
 - **TPM** — One 6-channel and one 2-channel timer/pulse-width modulators (TPM) modules; selectable input capture, output compare, or buffered edge- or center-aligned PWM on each channel
 - **MTIM16** — One 16-bit modulo timer
 - **SCI** — One serial communications interface module with optional 13-bit break; LIN extensions
 - **SPI** — One serial peripheral interface module in 8-bit data length mode with a receiving data buffer hardware match function
 - **IIC** — Inter-integrated circuit bus module capable of operation up to 100 kbps with maximum bus loading; multi-master operation; programmable slave address; interrupt-driven byte-by-byte data transfer; broadcast mode; 10-bit addressing
 - **ACMP** — Analog comparator with option to compare to internal reference
 - **RTC** — Real time counter
 - **KBI** — 8-pin keyboard interrupt module with software selectable polarity on edge or edge/level modes
- Input/Output
 - 30 GPIOs including one output-only pin and one input-only pin
- Package Options
 - 32-pin SDIP
 - 32-pin LQFP

This document contains information on a product under development. Freescale reserves the right to change or discontinue this product without notice.

Table of Contents

| | | | | | |
|-----|--|----|--------|--------------------------------------|----|
| 1 | MCU Block Diagram | 3 | 5.9.1 | Control Timing | 23 |
| 2 | System Clock Distribution | 4 | 5.9.2 | TPM Module Timing | 24 |
| 3 | Pin Assignments | 5 | 5.9.3 | SPI Timing | 25 |
| 4 | Memory Map | 8 | 5.10 | Analog Comparator (ACMP) Electricals | 27 |
| 5 | Electrical Characteristics | 9 | 5.11 | ADC Characteristics | 28 |
| 5.1 | Introduction | 9 | 5.12 | Flash Specifications | 30 |
| 5.2 | Parameter Classification | 9 | 5.13 | EMC Performance | 31 |
| 5.3 | Absolute Maximum Ratings | 9 | 5.13.1 | Radiated Emissions | 31 |
| 5.4 | Thermal Characteristics | 10 | 6 | Ordering Information | 32 |
| 5.5 | ESD Protection and Latch-Up Immunity | 11 | 7 | Package Information | 33 |
| 5.6 | DC Characteristics | 12 | 7.1 | Mechanical Drawings | 33 |
| 5.7 | Supply Current Characteristics | 18 | | | |
| 5.8 | External Oscillator (XOSC) and ICS Characteristics | 21 | | | |
| 5.9 | AC Characteristics | 23 | | | |

Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

<http://freescale.com/>

The following revision history table summarizes changes contained in this document.

| Rev | Date | Description of Changes |
|-----|-----------|--|
| 1 | 4/2/2009 | Initial public release. |
| 2 | 7/20/2009 | Updated Section 5.13 , "EMC Performance." Corrected Table 1 . Corrected default trim value to 31.25 kHz. |

Related Documentation

Find the most current versions of all documents at: <http://www.freescale.com>

Reference Manual (MC9S08SV16RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

1 MCU Block Diagram

The block diagram, [Figure 1](#), shows the structure of MC9S08SV16 series MCU.

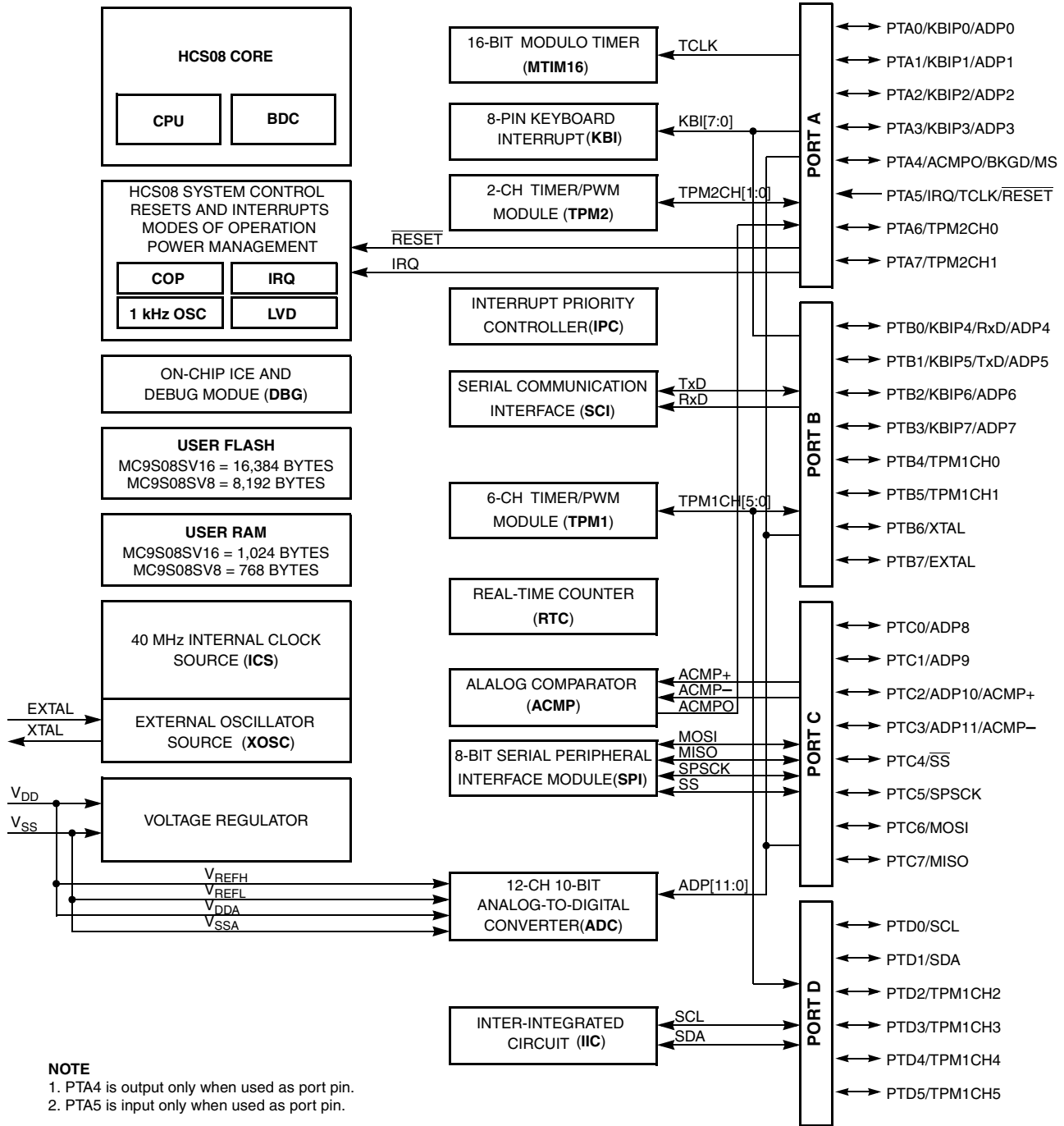


Figure 1. MC9S08SV16 Series Block Diagram

2 System Clock Distribution

MC9S08SV16 series use ICS module as clock sources. The ICS module can use internal or external clock source as reference to provide up to 40 MHz CPU clock. The output of ICS module includes,

- OSCOUT— XOSC output provides EXTAL reference clock to ADC and RTC.
- ICSIRCLK — ICS internal clock reference provides clock source of RTC.
- ICSFFCLK — ICS fixed frequency clock reference (around 32.768 kHz) provides double of the fixed lock signal to TPMs and MTIM16.
- ICSOUT — ICS CPU clock provides double of bus clock which is basic clock reference of peripherals.
- ICSLCLK — Alternate BDC clock provides debug signal to BDC module.

The TCLK pin is an extra external clock source. When TCLK is enabled, it can provide alternate clock source to TPMs and MTIM16. The on-chip 1 kHz clock can provide clock source of RTC and COP modules.

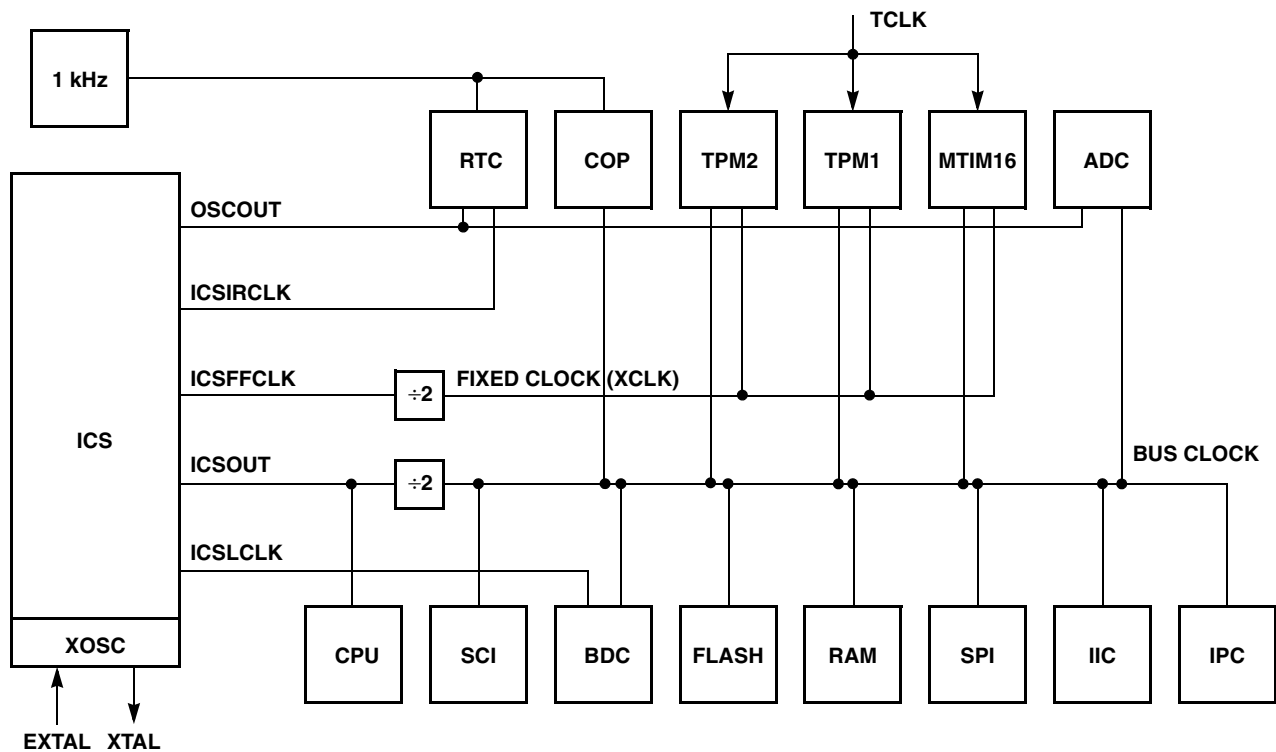


Figure 2. System Clock Distribution Diagram

3 Pin Assignments

This section shows the pin assignments for the MC9S08SV16 series devices.

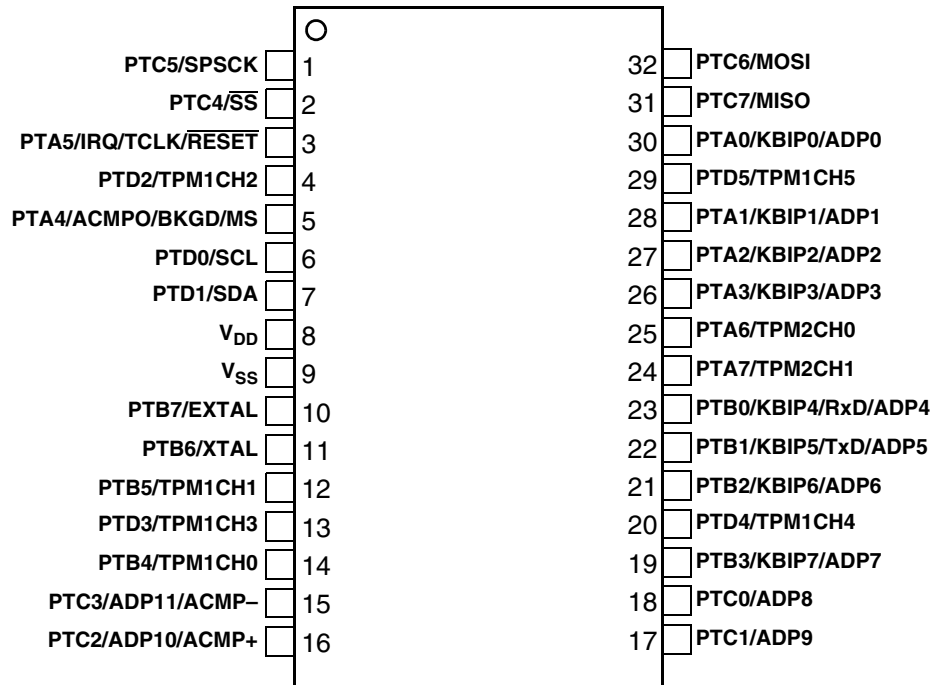


Figure 3. MC9S08SV16 Series 32-Pin SDIP Package

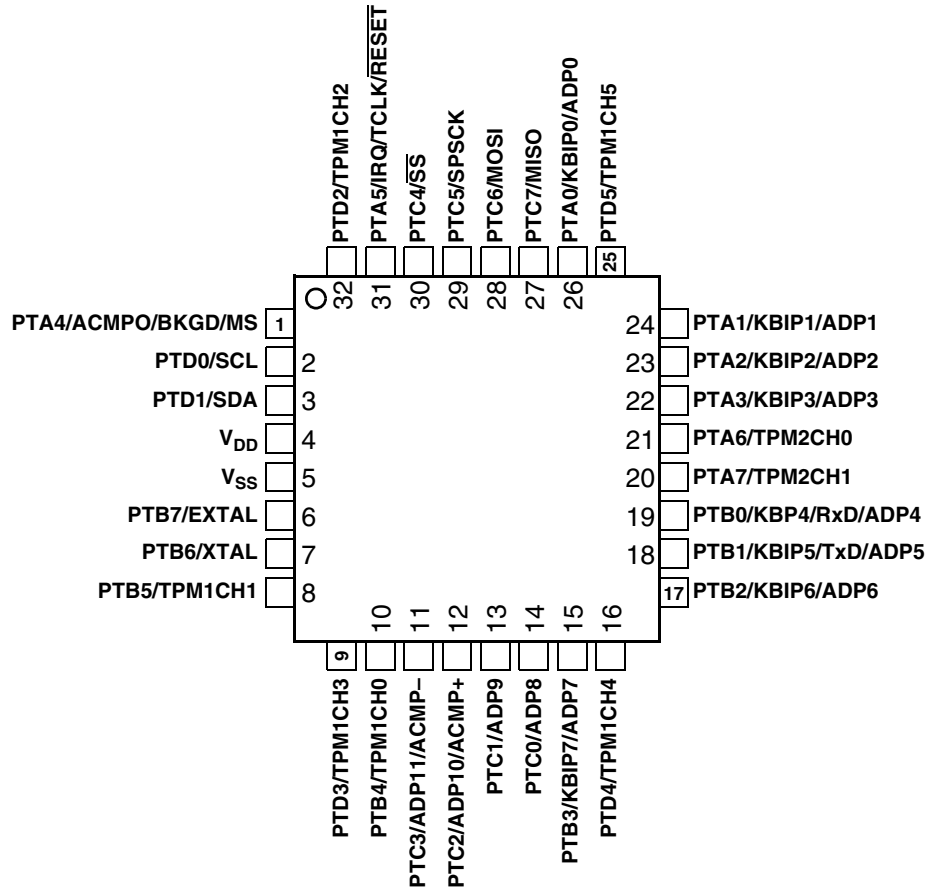


Figure 4. MC9S08SV16 Series 32-Pin LQFP Package

Table 1. Pin Availability by Package Pin-Count

| Pin Number | | <-- Lowest Priority --> Highest | | | | | | | |
|------------|---------|---------------------------------|-----|-----------------|-----|---------|-----|--------------------|-----|
| 32-SDIP | 32-LQFP | Port Pin | I/O | Alt 1 | I/O | Alt 2 | I/O | Alt 3 | I/O |
| 1 | 29 | PTC5 | I/O | SPSCK | I/O | | | | |
| 2 | 30 | PTC4 | I/O | \overline{SS} | I/O | | | | |
| 3 | 31 | PTA5 | I | IRQ | I | TCLK | I | \overline{RESET} | I |
| 4 | 32 | PTD2 | I/O | | | TPM1CH2 | I/O | | |
| 5 | 1 | PTA4 | O | ACMPO | O | BKGD | I | MS | I |
| 6 | 2 | PTD0 | I/O | SCL | I/O | | | | |
| 7 | 3 | PTD1 | I/O | SDA | I/O | | | | |
| 8 | 4 | | | | | | | V_{DD} | I |
| 9 | 5 | | | | | | | V_{SS} | I |
| 10 | 6 | PTB7 | I/O | EXTAL | I | | | | |
| 11 | 7 | PTB6 | I/O | XTAL | O | | | | |
| 12 | 8 | PTB5 | I/O | | | TPM1CH1 | I/O | | |
| 13 | 9 | PTD3 | I/O | | | TPM1CH3 | I/O | | |
| 14 | 10 | PTB4 | I/O | | | TPM1CH0 | I/O | | |

Table 1. Pin Availability by Package Pin-Count (continued)

| Pin Number | | <-- Lowest Priority --> Highest | | | | | | | |
|------------|---------|---------------------------------|-----|-------|-----|---------|-----|-------|-----|
| 32-SDIP | 32-LQFP | Port Pin | I/O | Alt 1 | I/O | Alt 2 | I/O | Alt 3 | I/O |
| 15 | 11 | PTC3 | I/O | | | ADP11 | I | ACMP- | I |
| 16 | 12 | PTC2 | I/O | | | ADP10 | I | ACMP+ | I |
| 17 | 13 | PTC1 | I/O | | | ADP9 | I | | |
| 18 | 14 | PTC0 | I/O | | | ADP8 | I | | |
| 19 | 15 | PTB3 | I/O | KBIP7 | I | ADP7 | I | | |
| 20 | 16 | PTD4 | I/O | | | TPM1CH4 | I/O | | |
| 21 | 17 | PTB2 | I/O | KBIP6 | I | ADP6 | I | | |
| 22 | 18 | PTB1 | I/O | KBIP5 | I | TxD | I/O | ADP5 | I |
| 23 | 19 | PTB0 | I/O | KBIP4 | I | RxD | I | ADP4 | I |
| 24 | 20 | PTA7 | I/O | | | TPM2CH1 | I/O | | |
| 25 | 21 | PTA6 | I/O | | | TPM2CH0 | I/O | | |
| 26 | 22 | PTA3 | I/O | KBIP3 | I | ADP3 | I | | |
| 27 | 23 | PTA2 | I/O | KBIP2 | I | ADP2 | I | | |
| 28 | 24 | PTA1 | I/O | KBIP1 | I | ADP1 | I | | |
| 29 | 25 | PTD5 | I/O | | | TPM1CH5 | I/O | | |
| 30 | 26 | PTA0 | I/O | KBIP0 | I | ADP0 | I | | |
| 31 | 27 | PTC7 | I/O | MISO | I/O | | | | |
| 32 | 28 | PTC6 | I/O | MOSI | I/O | | | | |

NOTE

When an alternative function is first enabled, it is possible to get a spurious edge to the module. User software must clear out any associated flags before interrupts are enabled. [Table 1](#) illustrates the priority if multiple modules are enabled. The highest priority module will have control over the pin. Selecting a higher priority pin function with a lower priority function already enabled can cause spurious edges to the lower priority module. Disable all modules that share a pin before enabling another module.

4 Memory Map

Figure 5 shows the memory map for the MC9S08SV16 series. On-chip memory in the MC9S08SV16 series of MCUs consist of RAM, flash program memory for nonvolatile data storage, plus I/O and control/status registers. The registers are divided into two groups:

- Direct-page registers (0x0000 through 0x003F)
- High-page registers (0x1800 through 0x187F)

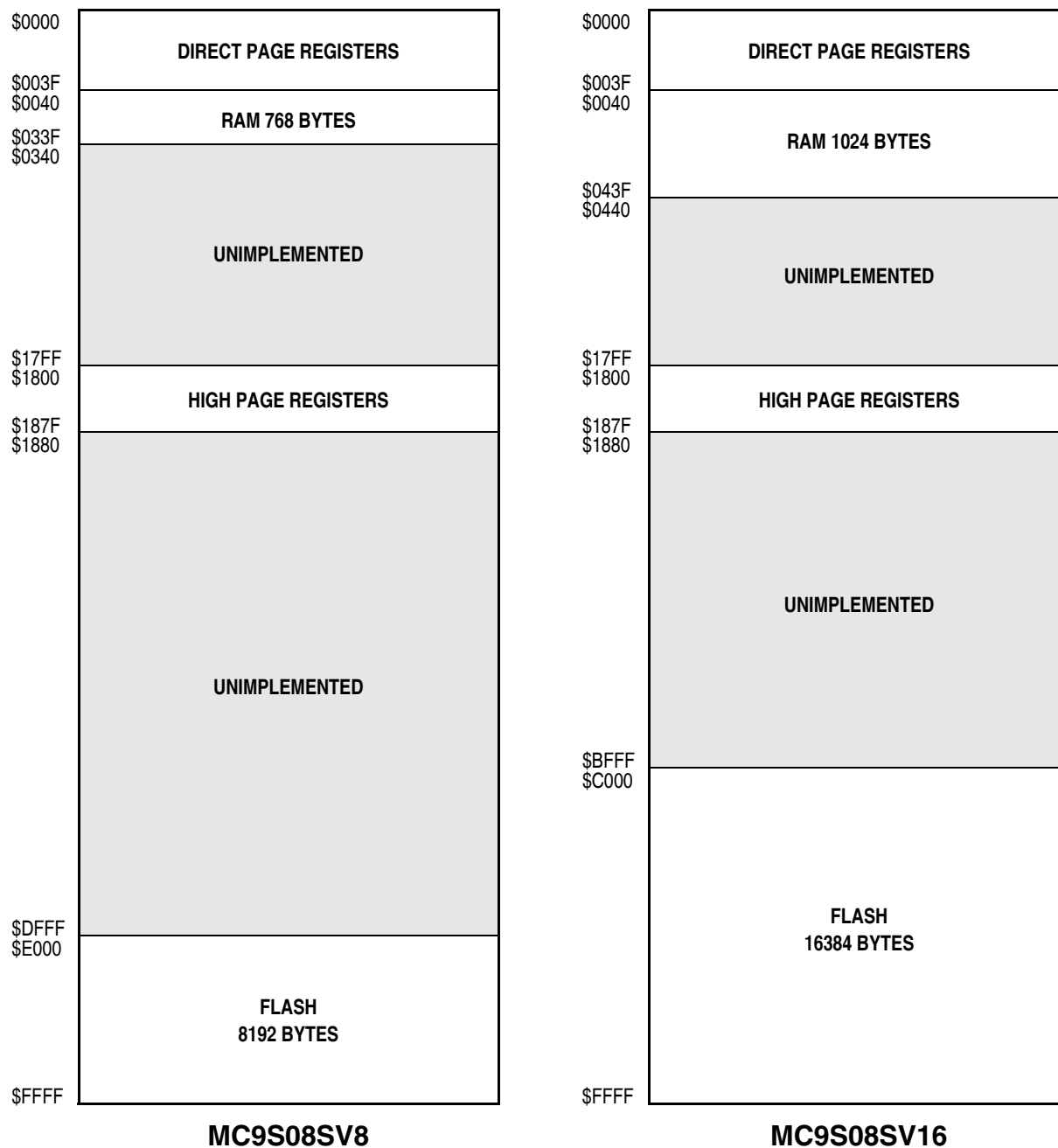


Figure 5. MC9S08SV16 Series Memory Map

5 Electrical Characteristics

5.1 Introduction

This section contains electrical and timing specifications for the MC9S08SV16 series of microcontrollers available at the time of publication.

5.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

Table 2. Parameter Classifications

| | |
|----------|--|
| P | Those parameters are guaranteed during production testing on each individual device. |
| C | Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations. |
| T | Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category. |
| D | Those parameters are derived mainly from simulations. |

NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

5.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in [Table 3](#) may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either V_{SS} or V_{DD}) or the programmable pullup resistor associated with the pin is enabled.

Table 3. Absolute Maximum Ratings

| Rating | Symbol | Value | Unit |
|---|-----------|------------------------|------|
| Supply voltage | V_{DD} | -0.3 to 5.8 | V |
| Maximum current into V_{DD} | I_{DD} | 120 | mA |
| Digital input voltage | V_{In} | -0.3 to $V_{DD} + 0.3$ | V |
| Instantaneous maximum current Single pin limit (applies to all port pins) ^{1, 2, 3} | I_D | ±25 | mA |
| Storage temperature range | T_{stg} | -55 to 150 | °C |

- ¹ Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V_{DD}) and negative (V_{SS}) clamp voltages, then use the larger of the two resistance values.
- ² All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD} .
- ³ Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If positive injection current ($V_{In} > V_{DD}$) is greater than I_{DD} , the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

5.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take $P_{I/O}$ into account in power calculations, determine the difference between actual pin voltage and V_{SS} or V_{DD} and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and V_{SS} or V_{DD} will be very small.

Table 4. Thermal Characteristics

| Rating | Symbol | Value | Unit |
|--|---------------|-----------------------------|------|
| Operating temperature range (packaged) | T_A | T_L to T_H -40 to 85 | °C |
| Thermal resistance Single-layer board | | | |
| 32-pin SDIP | θ_{JA} | 60 | °C/W |
| 32-pin LQFP | | 85 | |
| Thermal resistance Four-layer board | | | |
| 32-pin LQFP | θ_{JA} | 35 | °C/W |
| 32-pin LQFP | | 56 | |

The average chip-junction temperature (T_J) in °C can be obtained from:

$$T_J = T_A + (P_D \times \theta_{JA}) \tag{Eqn. 1}$$

where:

T_A = Ambient temperature, °C

θ_{JA} = Package thermal resistance, junction-to-ambient, °C/W

$P_D = P_{int} + P_{I/O}$

$P_{int} = I_{DD} \times V_{DD}$, Watts — chip internal power

$P_{I/O}$ = Power dissipation on input and output pins — user determined

For most applications, $P_{I/O} \ll P_{int}$ and can be neglected. An approximate relationship between P_D and T_J (if $P_{I/O}$ is neglected) is:

$$P_D = K \div (T_J + 273^\circ\text{C}) \quad \text{Eqn. 2}$$

Solving Equation 1 and Equation 2 for K gives:

$$K = P_D \times (T_A + 273^\circ\text{C}) + \theta_{JA} \times (P_D)^2 \quad \text{Eqn. 3}$$

where K is a constant pertaining to the particular part. K can be determined from Equation 3 by measuring P_D (at equilibrium) for an known T_A . Using this value of K, the values of P_D and T_J can be obtained by solving Equation 1 and Equation 2 iteratively for any value of T_A .

5.5 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions must be taken to avoid exposure to static discharge.

Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

During the device qualification, ESD stresses were performed for the human body model (HBM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless instructed otherwise in the device specification.

Table 5. ESD and Latch-Up Test Conditions

| Model | Description | Symbol | Value | Unit |
|------------|-----------------------------|--------|-------|------|
| Human body | Series resistance | R1 | 1500 | Ω |
| | Storage capacitance | C | 100 | pF |
| | Number of pulses per pin | — | 1 | — |
| Latch-up | Minimum input voltage limit | — | -2.5 | V |
| | Maximum input voltage limit | — | 7.5 | V |

Table 6. ESD and Latch-Up Protection Characteristics

| No. | Rating ¹ | Symbol | Min | Max | Unit |
|-----|--|-----------|------------|-----|------|
| 1 | Human body model (HBM) | V_{HBM} | ± 2000 | — | V |
| 2 | Charge device model (CDM) | V_{CDM} | ± 500 | — | V |
| 3 | Latch-up current at $T_A = 85\text{ }^\circ\text{C}$ | I_{LAT} | ± 100 | — | mA |

¹ Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

5.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 7. DC Characteristics

| Num | C | Characteristic | Symbol | Condition | Min. | Typical ¹ | Max. | Unit |
|-----|---|--|-----------|---|----------------------|----------------------|----------------------|---------------|
| 1 | — | Operating voltage | — | — | 2.7 | — | 5.5 | V |
| 2 | C | Output high voltage All I/O pins, low-drive strength | V_{OH} | $V_{DD} > 2.7\text{ V}$, $I_{Load} = -2\text{ mA}$ | $V_{DD} - 0.5$ | — | — | V |
| | P | | | $V_{DD} > 4.1\text{ V}$, $I_{Load} = -10\text{ mA}$ | $V_{DD} - 0.5$ | — | — | |
| | C | | | $V_{DD} > 2.7\text{ V}$, $I_{Load} = -2\text{ mA}$ | $V_{DD} - 0.5$ | — | — | |
| 3 | D | Output high current Max total I_{OH} for all ports | I_{OHT} | — | — | — | 100 | mA |
| 4 | C | Output low voltage All I/O pins, low-drive strength | V_{OL} | $V_{DD} > 2.7\text{ V}$, $I_{Load} = 0.6\text{ mA}$ | — | — | 0.5 | V |
| | P | | | $V_{DD} > 4.1\text{ V}$, $I_{Load} = 10\text{ mA}$ | — | — | 0.5 | |
| | C | | | $V_{DD} > 2.7\text{ V}$, $I_{Load} = 3\text{ mA}$ | — | — | 0.5 | |
| 5 | D | Output low current Max total I_{OL} for all ports | I_{OLT} | — | — | — | 100 | mA |
| 6 | P | Input high voltage All digital inputs | V_{IH} | $V_{DD} > 4.1\text{ V}$ | $0.70 \times V_{DD}$ | — | — | V |
| | C | | | $V_{DD} > 2.7\text{ V}$ | $0.85 \times V_{DD}$ | — | — | |
| 7 | P | Input low voltage All digital inputs | V_{IL} | $V_{DD} > 4.1\text{ V}$ | — | — | $0.35 \times V_{DD}$ | |
| | C | | | $V_{DD} > 2.7\text{ V}$ | — | — | $0.30 \times V_{DD}$ | |
| 8 | C | Input hysteresis All digital inputs | V_{hys} | — | $0.06 \times V_{DD}$ | — | — | mV |
| 9 | P | Input leakage current All input only pins (per pin) | I_{In} | $V_{In} = V_{DD}$ or V_{SS} | — | 0.1 | 1 | μA |
| 10 | P | Hi-Z (off-state) leakage current All input/output (per pin) | I_{Oz} | $V_{In} = V_{DD}$ or V_{SS} | — | 0.1 | 1 | μA |

Table 7. DC Characteristics (continued)

| Num | C | Characteristic | Symbol | Condition | Min. | Typical ¹ | Max. | Unit |
|-----|---|---|--|---------------------------------------|--------------|----------------------|--------------|------------|
| 11a | P | Pullup, pulldown resistors All digital inputs, when enabled (all I/O pins other than PTA5/IRQ/TCLK/RESET) | R_{PU} , R_{PD} | — | 17.5 | — | 52.5 | k Ω |
| 11b | C | Pullup, pulldown resistors (PTA5/IRQ/TCLK/RESET) | R_{PU} , R_{PD} (Note ²) | — | 17.5 | — | 52.5 | k Ω |
| 12 | C | DC injection current ^{3, 4, 5} Single pin limit Total MCU limit, includes sum of all stressed pins | I_{IC} | $V_{IN} < V_{SS}$, $V_{IN} > V_{DD}$ | -0.2 | — | 0.2 | mA |
| | | | | | -5 | — | 5 | mA |
| 13 | C | Input capacitance, all pins | C_{in} | — | — | — | 8 | pF |
| 14 | C | RAM retention voltage | V_{RAM} | — | — | 0.6 | 1.0 | V |
| 15 | C | POR re-arm voltage ⁶ | V_{POR} | — | 0.9 | 1.4 | 2.0 | V |
| 16 | D | POR re-arm time | t_{POR} | — | 10 | — | — | μ s |
| 17 | P | Low-voltage detection threshold — high range V_{DD} falling V_{DD} rising | V_{LVD1} | — | 3.9 4.0 | 4.0 4.1 | 4.1 4.2 | V |
| | P | Low-voltage detection threshold — low range V_{DD} falling V_{DD} rising | V_{LVD0} | — | 2.48 2.54 | 2.56 2.62 | 2.64 2.70 | V |
| 18 | C | Low-voltage warning threshold — high range 1 V_{DD} falling V_{DD} rising | V_{LVW3} | — | 4.5 4.6 | 4.6 4.7 | 4.7 4.8 | V |
| | P | Low-voltage warning threshold — high range 0 V_{DD} falling V_{DD} rising | V_{LVW2} | — | 4.2 4.3 | 4.3 4.4 | 4.4 4.5 | V |
| 19 | P | Low-voltage warning threshold low range 1 V_{DD} falling V_{DD} rising | V_{LVW1} | — | 2.84 2.90 | 2.92 2.98 | 3.00 3.06 | V |
| | C | Low-voltage warning threshold — low range 0 V_{DD} falling V_{DD} rising | V_{LVW0} | — | 2.66 2.72 | 2.74 2.80 | 2.82 2.88 | V |
| 21 | C | Low-voltage inhibit reset/recover hysteresis | V_{hys} | — | — | 80 | — | mV |
| 22 | C | Bandgap voltage reference ⁷ | V_{BG} | — | — | 1.21 | — | V |

¹ Typical values are measured at 25 °C. Characterized, not tested.

² The specified resistor value is the actual value internal to the device. The pullup or pulldown value may appear higher when measured externally on the pin.

³ All functional non-supply pins, except for PTA5 are internally clamped to V_{SS} and V_{DD} .

Electrical Characteristics

- 4 Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.
- 5 Power supply must maintain regulation within operating V_{DD} range during instantaneous and operating maximum current conditions. If the positive injection current ($V_{in} > V_{DD}$) is greater than I_{DD} , the injection current may flow out of V_{DD} and could result in external power supply going out of regulation. Ensure that external V_{DD} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).
- 6 Maximum is highest voltage that POR is guaranteed.
- 7 Factory trimmed at $V_{DD} = 5.0$ V, Temp = 25 °C

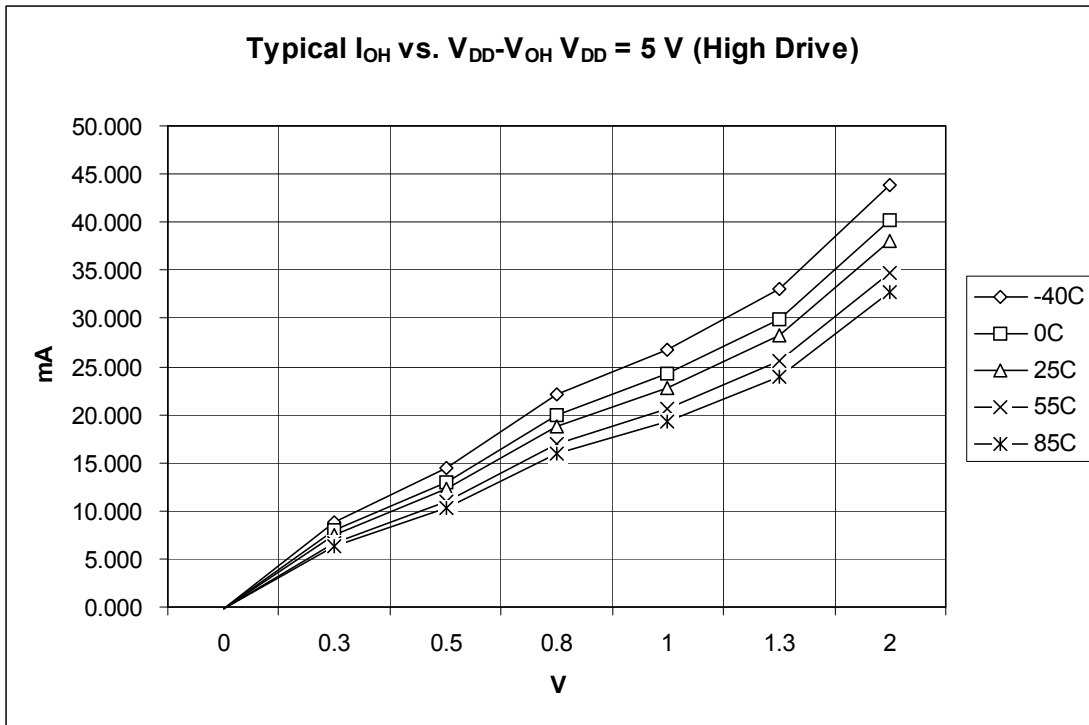


Figure 6. Typical I_{OH} Vs. $V_{DD}-V_{OH}$ ($V_{DD} = 5.0$ V) (High Drive)

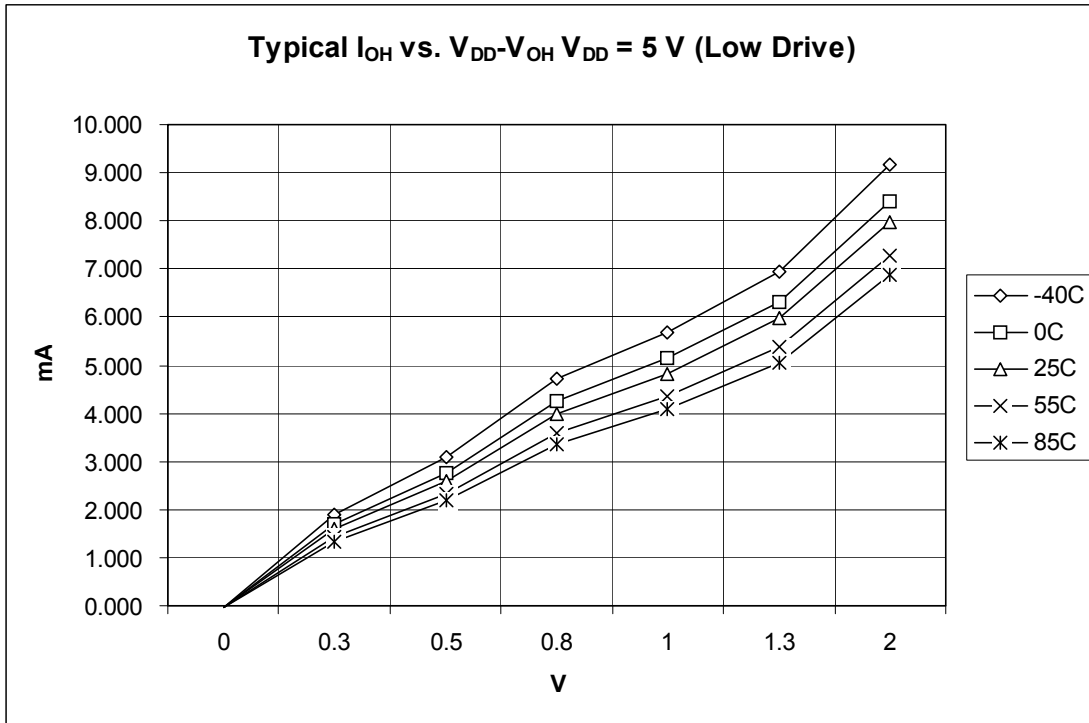


Figure 7. Typical I_{OH} Vs. $V_{DD}-V_{OH}$ ($V_{DD} = 5.0$ V) (Low Drive)

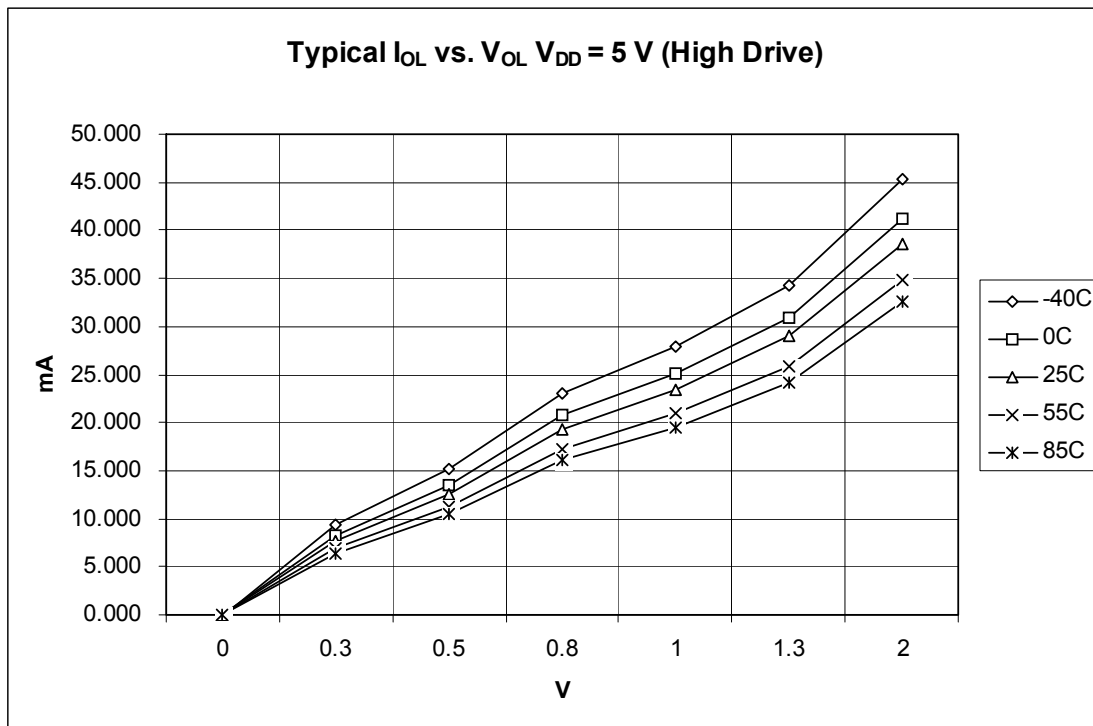


Figure 8. Typical I_{OH} Vs. V_{OL} ($V_{DD} = 5.0$ V) (High Drive)

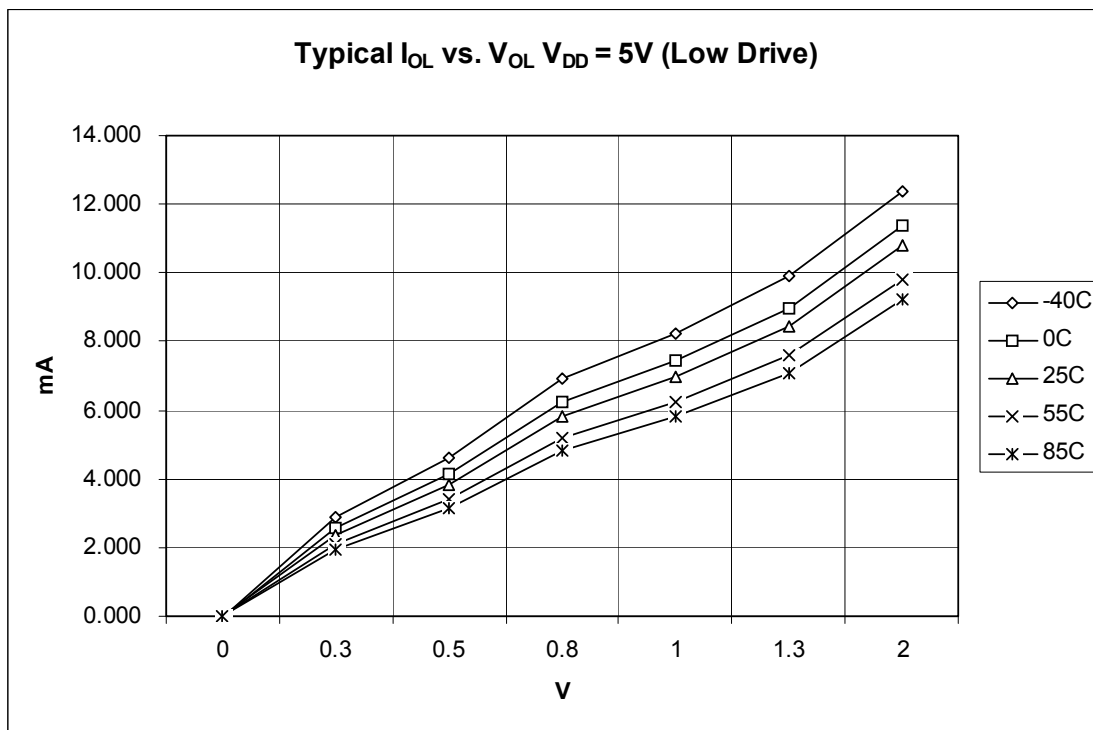


Figure 9. Typical I_{OH} Vs. V_{OL} ($V_{DD} = 5.0 V$) (Low Drive)

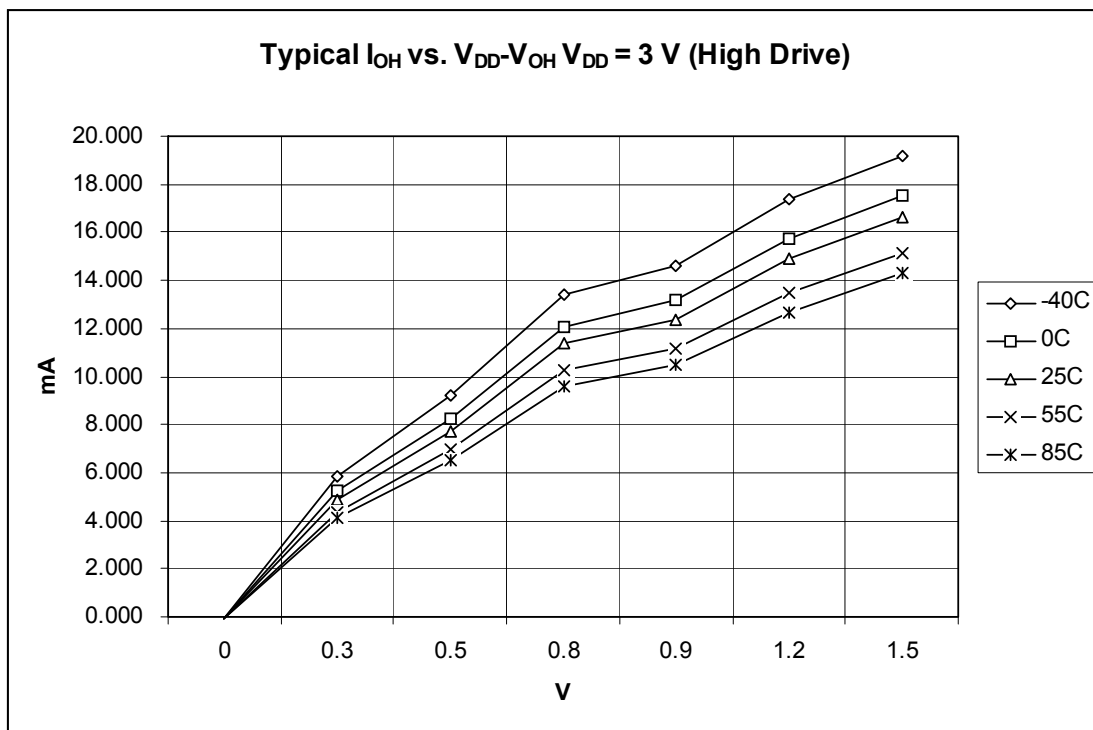


Figure 10. Typical I_{OH} Vs. $V_{DD}-V_{OH}$ ($V_{DD} = 3.0 V$) (High Drive)

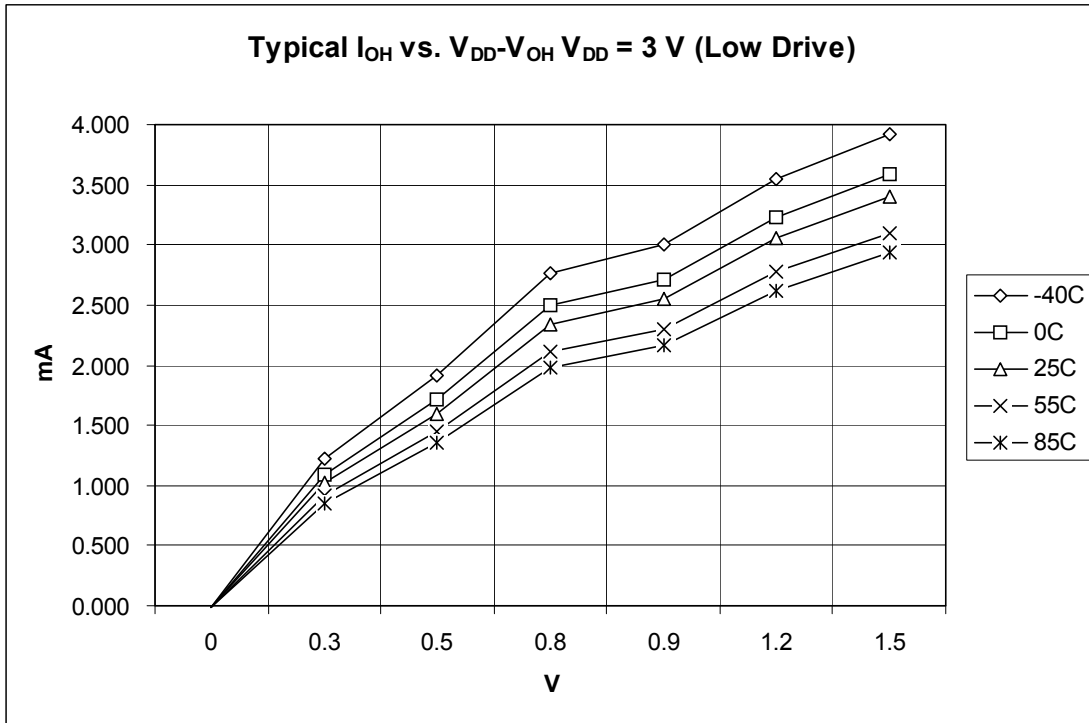


Figure 11. Typical I_{OH} Vs. $V_{DD}-V_{OH}$ ($V_{DD} = 3.0\text{ V}$) (Low Drive)

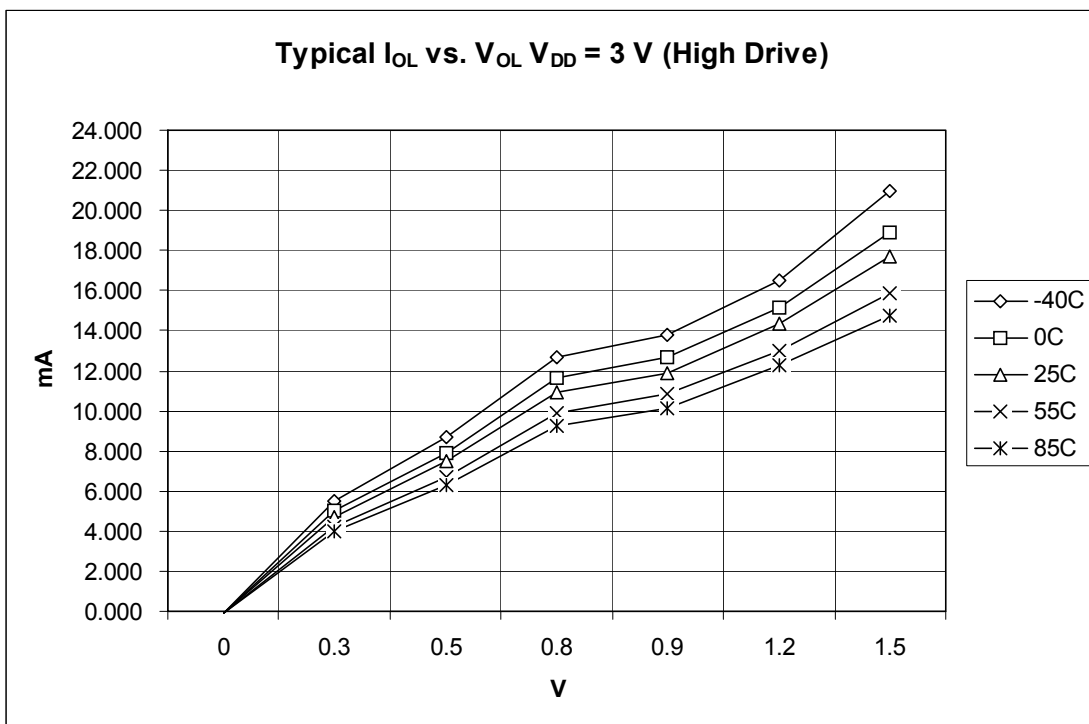


Figure 12. Typical I_{OL} Vs. V_{OL} ($V_{DD} = 3.0\text{ V}$) (High Drive)

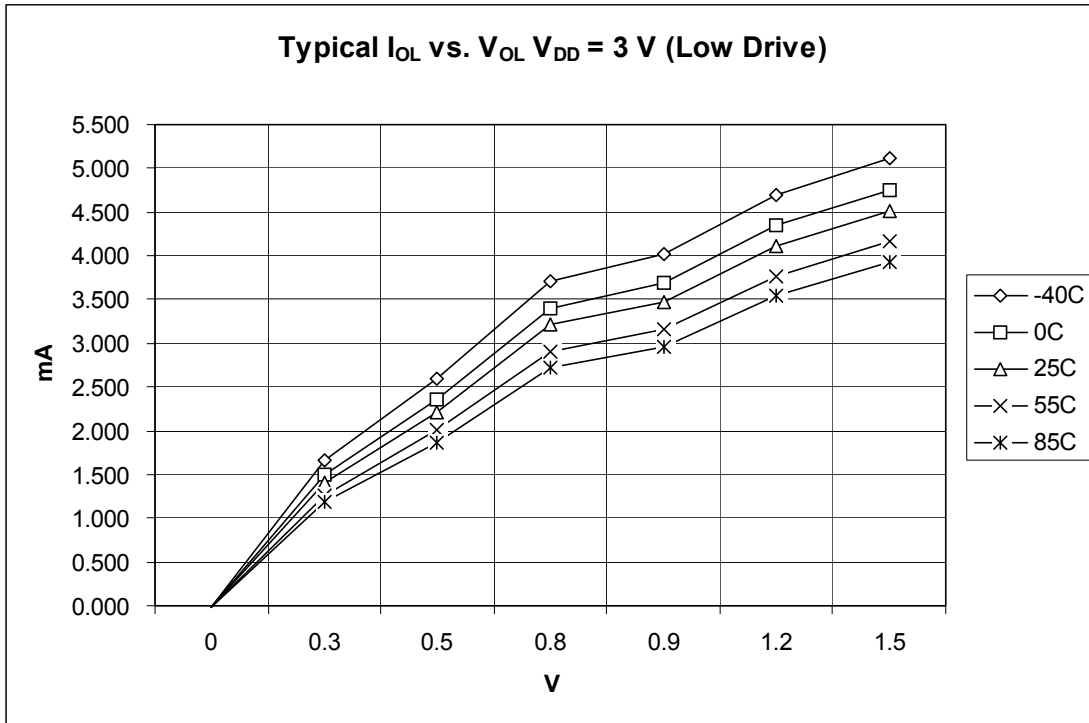


Figure 13. Typical I_{OL} Vs. V_{OL} (V_{DD} = 3.0 V) (Low Drive)

5.7 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

Table 8. Supply Current Characteristics

| Num | C | Parameter | Symbol | Bus Freq | V _{DD} (V) | Typical ¹ | Max | Unit | Temp |
|-----|-------|---|-------------------|----------|---------------------|----------------------|-------|------|--------------|
| 1 | P | Run supply current FBE mode, all modules on | R _I DD | 20 MHz | 5 | 10.57 | 12.96 | mA | -40 to 85 °C |
| | 8 MHz | | | 5.24 | | 6.48 | | | |
| | 1 MHz | | | 2.00 | | 2.60 | | | |
| 2 | P | Run supply current FBE mode, all modules on | R _I DD | 20 MHz | 3 | 8.86 | 10.86 | mA | -40 to 85 °C |
| | 8 MHz | | | 4.53 | | 5.61 | | | |
| | 1 MHz | | | 1.82 | | 2.31 | | | |
| 3 | C | Run supply current FBE mode, all modules off | R _I DD | 20 MHz | 5 | 5.91 | 7.25 | mA | -40 to 85 °C |
| | C | | | 8 MHz | | 2.94 | 3.69 | | |
| | C | | | 1 MHz | | 1.18 | 1.54 | | |
| 4 | C | Run supply current FBE mode, all modules off | R _I DD | 20 MHz | 3 | 5.69 | 6.98 | mA | -40 to 85 °C |
| | C | | | 8 MHz | | 2.90 | 3.60 | | |
| | C | | | 1 MHz | | 1.17 | 1.49 | | |
| 5 | C | Wait mode current FBE mode, all modules off | W _I DD | 20 MHz | 5 | 4.83 | — | mA | -40 to 85 °C |
| | C | | | 1 MHz | | 1.06 | — | | |

Table 8. Supply Current Characteristics (continued)

| Num | C | Parameter | Symbol | Bus Freq | V _{DD} (V) | Typical ¹ | Max | Unit | Temp |
|-----|---|--|-------------------|----------|---------------------|----------------------|----------------------|------|--------------------------|
| 6 | C | Wait mode current FBE mode, all modules off | W _I DD | 20 MHz | 3 | 4.80 | — | mA | -40 to 85 °C |
| | C | | | 1 MHz | | 1.05 | — | | |
| 7 | P | Stop2 mode supply current | S2I _{DD} | — | 5 | 0.85 1.06 2.59 | — — — | μA | -40 °C 25 °C 85 °C |
| | C | | | — | | 3 | 0.76 0.97 2.25 | | — — — |
| 8 | P | Stop3 mode supply current no clocks active | S3I _{DD} | — | 5 | 0.85 1.17 3.56 | — | μA | -40 °C 25 °C 85 °C |
| | C | | | — | | 3 | 0.76 1.07 3.22 | | — |
| 9 | C | ADC adder to stop3 | — | — | 5 | 128.72 | — | μA | -40 to 85 °C |
| | | | | — | 3 | 123.86 | — | | |
| 10 | C | RTC adder to stop3 and stop2 | — | — | 5 | 300 | — | nA | -40 to 85 °C |
| | C | | | — | 3 | 300 | — | | |
| 11 | C | LVD adder to stop3 and stop2 | — | — | 5 | 106.7 | — | μA | -40 to 85 °C |
| | C | | | — | 3 | 95.6 | — | | |

¹ Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.

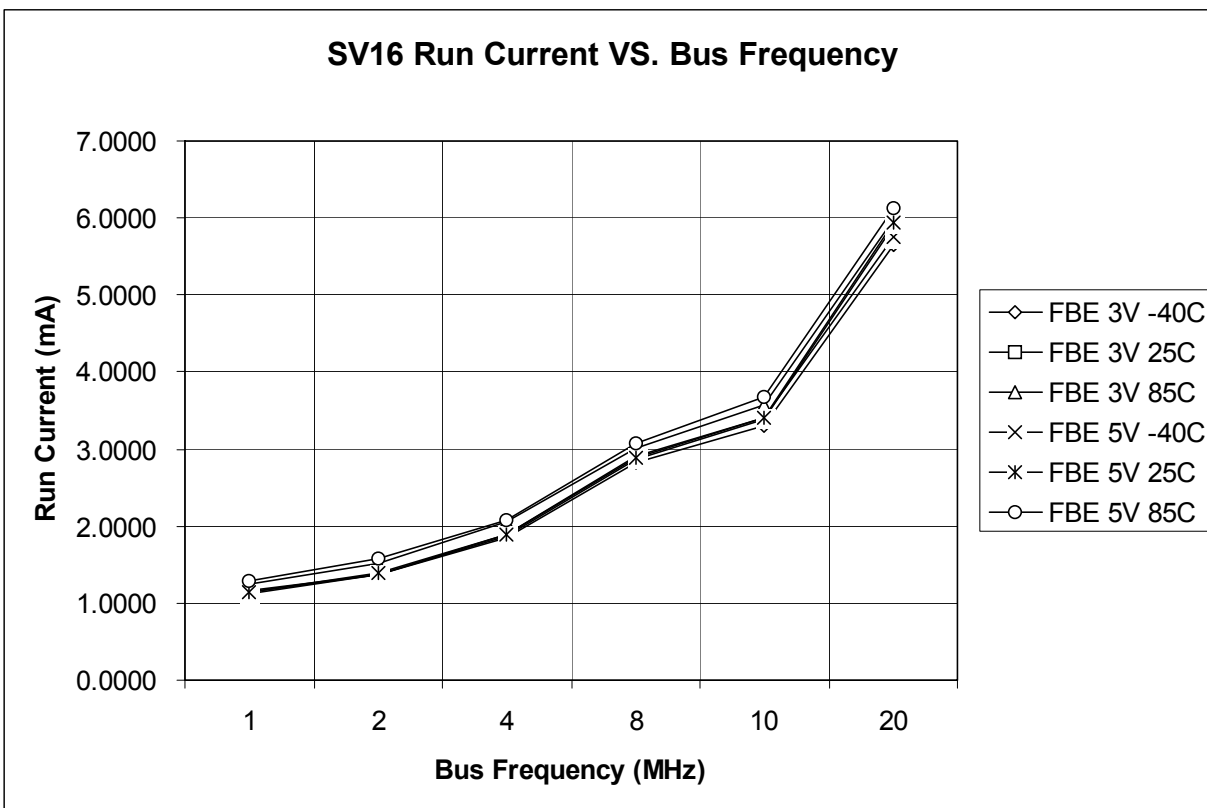


Figure 14. Typical Run I_{DD} for FBE (All Modules Off)

5.8 External Oscillator (XOSC) and ICS Characteristics

Refer to [Figure 16](#) for crystal or resonator circuits.

Table 9. XOSC and ICS Specifications (Temperature Range = –40 to 85 °C Ambient)

| Num | C | Characteristic | Symbol | Min | Typical ¹ | Max | Unit |
|-----|---|---|---------------------|-----------------------|----------------------|------|-------------|
| 1 | C | Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) | | | | | |
| | | Low range (RANGE = 0) | f_{lo} | 32 | — | 38.4 | kHz |
| | | High range (RANGE = 1) FEE or FBE mode ² | f_{hi} | 1 | — | 5 | MHz |
| | | High range (RANGE = 1), high gain (HGO = 1), FBELP mode | f_{hi} | 1 | — | 16 | MHz |
| | | High range (RANGE = 1), low power (HGO = 0), FBELP mode | f_{hi} | 1 | — | 8 | MHz |
| | | Load capacitors | C_1 C_2 | See Note ³ | | | |
| 3 | D | Feedback resistor | R_F | — | 10 | — | MΩ MΩ |
| | | Low range (32 kHz to 38.4 kHz) | | | | | |
| | | High range (1 MHz to 16 MHz) | | | 1 | | |
| 4 | D | Series resistor — Low range | R_S | — | 0 | — | kΩ |
| | | Low gain (HGO = 0) | | | | | |
| | | High gain (HGO = 1) | | | 100 | | |
| 5 | D | Series resistor — High range | R_S | — | 0 | 0 | kΩ |
| | | Low gain (HGO = 0) | | | | | |
| | | High gain (HGO = 1) | | | | | |
| | | ≥ 8 MHz | | | | | |
| | | 4 MHz | | | 0 | 10 | |
| | | 1 MHz | | | 0 | 20 | |
| 6 | C | Crystal start-up time ^{4,5} | t_{CSTL} | — | 200 | — | ms |
| | | Low range, low power | | | | | |
| | | Low range, high power | | | | | |
| | | High range, low power | | | | | |
| | | High range, high power | | | 5 | | |
| | | | t_{CSTH} | | 15 | | |
| 7 | T | Internal reference start-up time | t_{IRST} | — | 60 | 100 | μs |
| 8 | D | Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) | f_{extal} | 0.03125 | — | 5 | MHz MHz |
| | | FEE or FBE mode ² | | | | | |
| | | FBELP mode | | 0 | | 40 | |
| 9 | P | Average internal reference frequency — trimmed | f_{int_t} | — | 31.25 | — | kHz |
| 10 | P | DCO output frequency range — trimmed | f_{dco_t} | 16 | — | 20 | MHz |
| | P | | | | | | |
| 11 | C | Total deviation of DCO output from trimmed frequency ⁴ | Δf_{dco_t} | — | –1.0 to 0.5 | ±2 | % f_{dco} |
| | | Over full voltage and temperature range | | | | | |
| | | Over fixed voltage and temperature range of 0 to 70 °C | | | ±0.5 | ±1 | |
| 12 | C | FLL acquisition time ^{4,6} | $t_{Acquire}$ | — | — | 1 | ms |
| 13 | C | Long term jitter of DCO output clock (averaged over 2 ms interval) ⁷ | C_{Jitter} | — | 0.02 | 0.2 | % f_{dco} |

¹ Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.

Electrical Characteristics

- 2 When ICS is configured for FEE or FBE mode, input clock source must be divisible using RDIV to within the range of 31.25 kHz to 39.0625 kHz.
- 3 See crystal or resonator manufacturer's recommendation.
- 4 This parameter is characterized and not tested on each device.
- 5 Proper PC board layout procedures must be followed to achieve specifications.
- 6 This specification applies to any time the FLL reference source or reference divider is changed, trim value changed, DMX32 bit is changed, DRS bit is changed, or changing from FLL disabled (FBELP, FBILP) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
- 7 Jitter is the average deviation from the programmed frequency measured over the specified interval at maximum f_{BUS} . Measurements are made with the device powered by filtered supplies and clocked by a stable external clock signal. Noise injected into the FLL circuitry via V_{DD} and V_{SS} and variation in crystal oscillator frequency increase the C_{Jitter} percentage for a given interval.

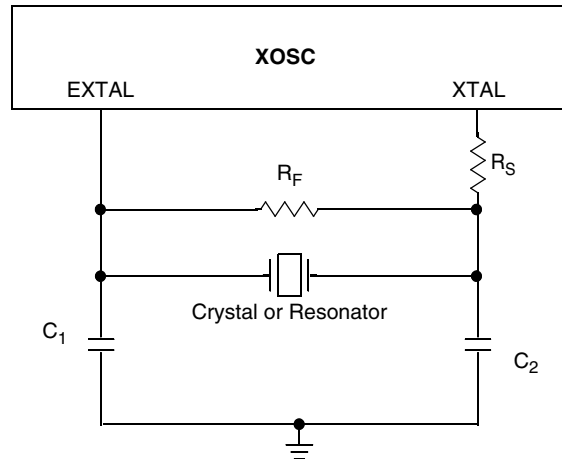


Figure 15. Typical Crystal or Resonator Circuit

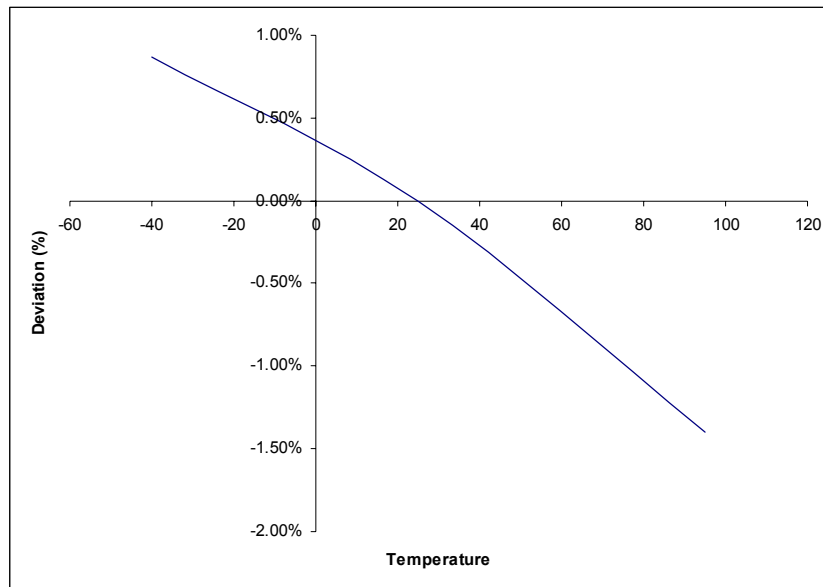


Figure 16. Deviation of DCO Output from Trimmed Frequency (20 MHz, 5.0 V)

5.9 AC Characteristics

This section describes timing characteristics for each peripheral system.

5.9.1 Control Timing

Table 10. Control Timing

| Num | C | Rating | Symbol | Min | Typical ¹ | Max | Unit |
|-----|---|---|----------------------|-----------------------------|----------------------|--------|---------|
| 1 | D | Bus frequency ($t_{cyc} = 1/f_{Bus}$) | f_{Bus} | dc | — | 20 | MHz |
| 2 | D | Internal low power oscillator period | t_{LPO} | 700 | — | 1300 | μ s |
| 3 | D | External reset pulse width ² | t_{extrst} | 100 | — | — | ns |
| 4 | D | Reset low drive | t_{rstdrv} | $34 \times t_{cyc}$ | — | — | ns |
| 5 | D | BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes | t_{MSSU} | 500 | — | — | ns |
| 6 | D | BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes ³ | t_{MSH} | 100 | — | — | μ s |
| 7 | D | IRQ pulse width Asynchronous path ² Synchronous path ⁴ | t_{LILH}, t_{IHIL} | 100 $1.5 \times t_{cyc}$ | — — | — — | ns |
| 8 | D | Keyboard interrupt pulse width Asynchronous path ² Synchronous path ⁴ | t_{LILH}, t_{IHIL} | 100 $1.5 \times t_{cyc}$ | — — | — — | ns |
| 9 | C | Port rise and fall time — Low output drive (PTxDS = 0) (load = 50 pF) ⁵ Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1) | t_{Rise}, t_{Fall} | — — | 16 23 | — — | ns |
| | | Port rise and fall time — High output drive (PTxDS = 1) (load = 50 pF) ⁵ Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1) | t_{Rise}, t_{Fall} | — — | 5 9 | — — | ns |

¹ Typical values are based on characterization data at $V_{DD} = 5.0$ V, 25 °C unless otherwise stated.

² This is the shortest pulse that is guaranteed to be recognized as a reset pin request.

³ To enter BDM mode following a POR, BKGD/MS should be held low during the power-up and for a hold time of t_{MSH} after V_{DD} rises above V_{LVD} .

⁴ This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized.

⁵ Timing is shown with respect to 20% V_{DD} and 80% V_{DD} levels. Temperature range -40 °C to 85 °C.

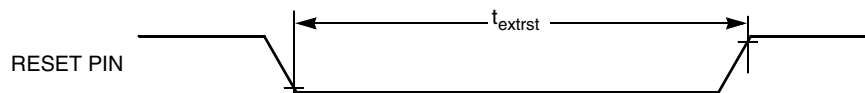


Figure 17. Reset Timing

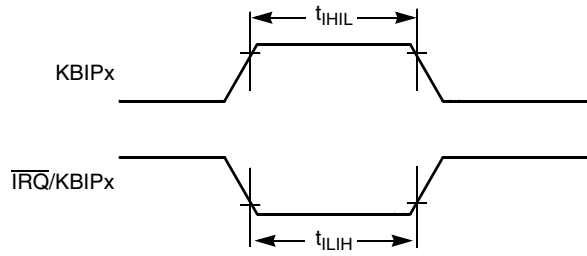


Figure 18. $\overline{\text{IRQ}}/\text{KBIPx}$ Timing

5.9.2 TPM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 11. TPM Input Timing

| No. | C | Function | Symbol | Min | Max | Unit |
|-----|---|---------------------------|-------------------|-----|--------------------|------------------|
| 1 | D | External clock frequency | f_{TCLK} | 0 | $f_{\text{Bus}}/4$ | Hz |
| 2 | D | External clock period | t_{TCLK} | 4 | — | t_{cyc} |
| 3 | D | External clock high time | t_{clkh} | 1.5 | — | t_{cyc} |
| 4 | D | External clock low time | t_{clkl} | 1.5 | — | t_{cyc} |
| 5 | D | Input capture pulse width | t_{ICPW} | 1.5 | — | t_{cyc} |

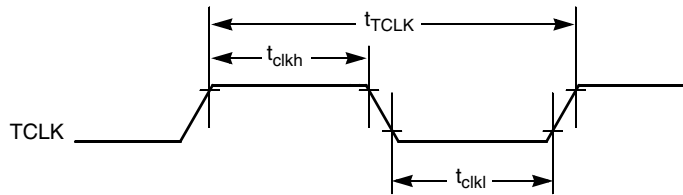


Figure 19. Timer External Clock

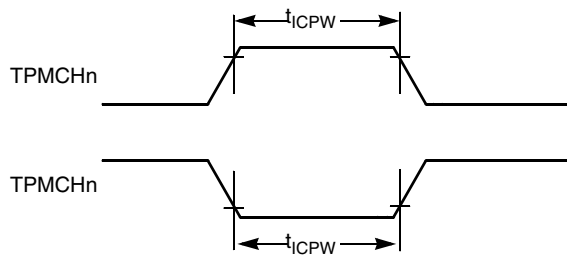


Figure 20. Timer Input Capture Pulse

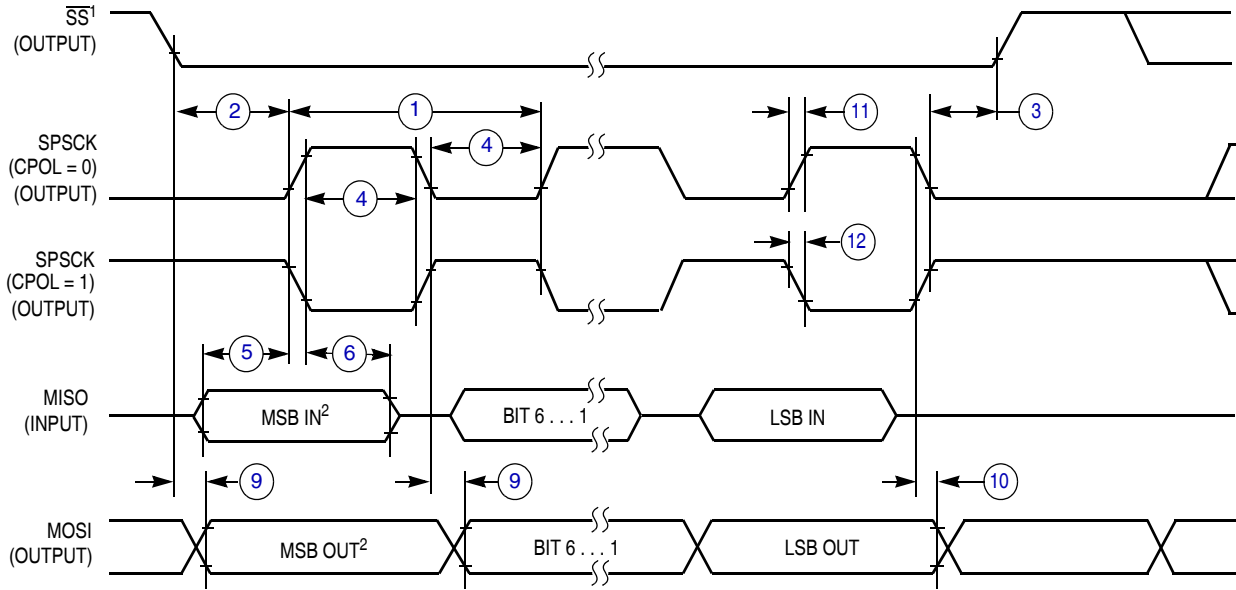
5.9.3 SPI Timing

Table 12 and Figure 21 through Figure 24 describe the timing requirements for the SPI system.

Table 12. SPI Timing

| No. | C | Function | Symbol | Min | Max | Unit |
|-----|---|---|----------------------|----------------------------------|----------------------------|--------------------------|
| — | D | Operating frequency Master Slave | f_{op} | $f_{Bus}/2048$ 0 | $f_{Bus}/2$ $f_{Bus}/4$ | Hz |
| 1 | D | SPSCK period Master Slave | t_{SPSCK} | 2 4 | 2048 — | t_{cyc} t_{cyc} |
| 2 | D | Enable lead time Master Slave | t_{Lead} | 1/2 1 | — — | t_{SPSCK} t_{cyc} |
| 3 | D | Enable lag time Master Slave | t_{Lag} | 1/2 1 | — — | t_{SPSCK} t_{cyc} |
| 4 | D | Clock (SPSCK) high or low time Master Slave | t_{WSPSCK} | $t_{cyc} - 30$ $t_{cyc} - 30$ | $1024 t_{cyc}$ — | ns ns |
| 5 | D | Data setup time (inputs) Master Slave | t_{SU} | 15 15 | — — | ns ns |
| 6 | D | Data hold time (inputs) Master Slave | t_{HI} | 0 25 | — — | ns ns |
| 7 | D | Slave access time | t_a | — | 1 | t_{cyc} |
| 8 | D | Slave MISO disable time | t_{dis} | — | 1 | t_{cyc} |
| 9 | D | Data valid (after SPSCK edge) Master Slave | t_v | — — | 25 25 | ns ns |
| 10 | D | Data hold time (outputs) Master Slave | t_{HO} | 0 0 | — — | ns ns |
| 11 | D | Rise time Input Output | t_{RI} t_{RO} | — — | $t_{cyc} - 25$ 25 | ns ns |
| 12 | D | Fall time Input Output | t_{FI} t_{FO} | — — | $t_{cyc} - 25$ 25 | ns ns |

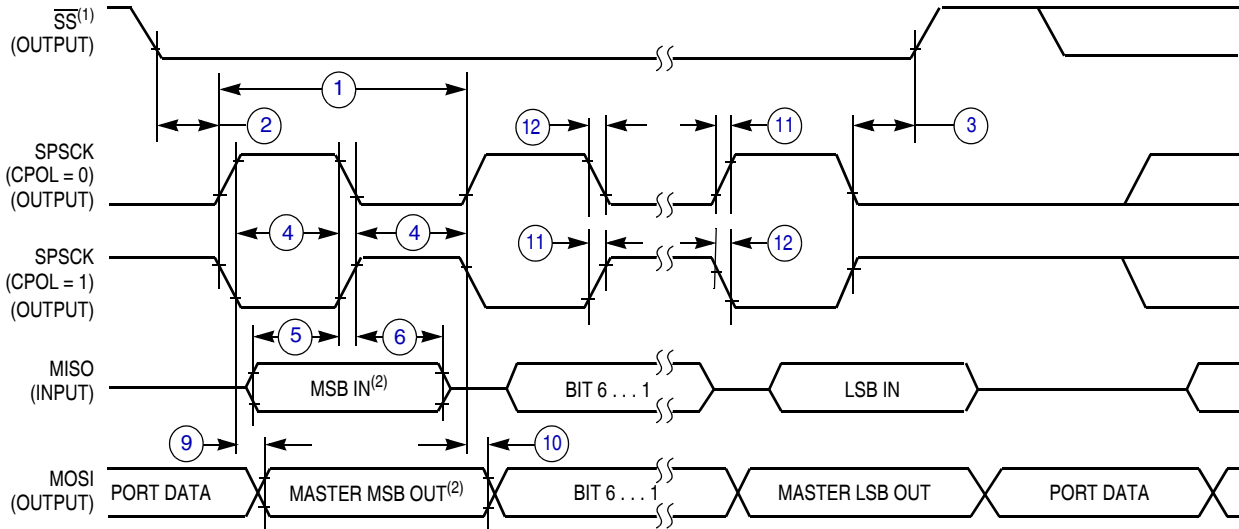
Electrical Characteristics



NOTES:

1. \overline{SS} output mode (DDS7 = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

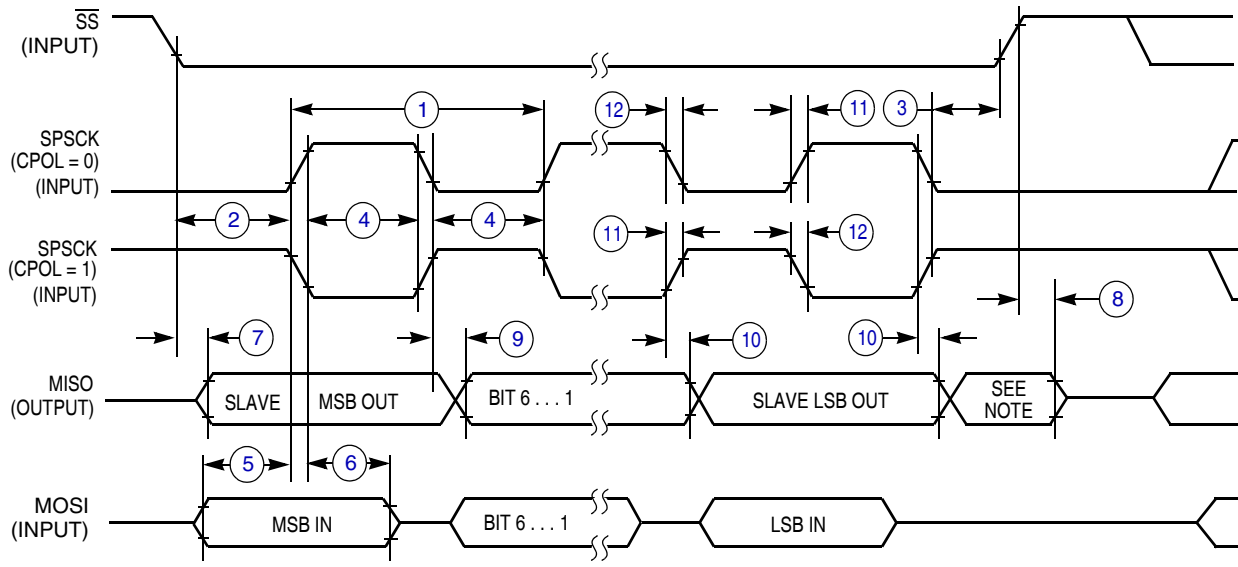
Figure 21. SPI Master Timing (CPHA = 0)



NOTES:

1. \overline{SS} output mode (DDS7 = 1, SSOE = 1).
2. LSBF = 0. For LSBF = 1, bit order is LSB, bit 1, ..., bit 6, MSB.

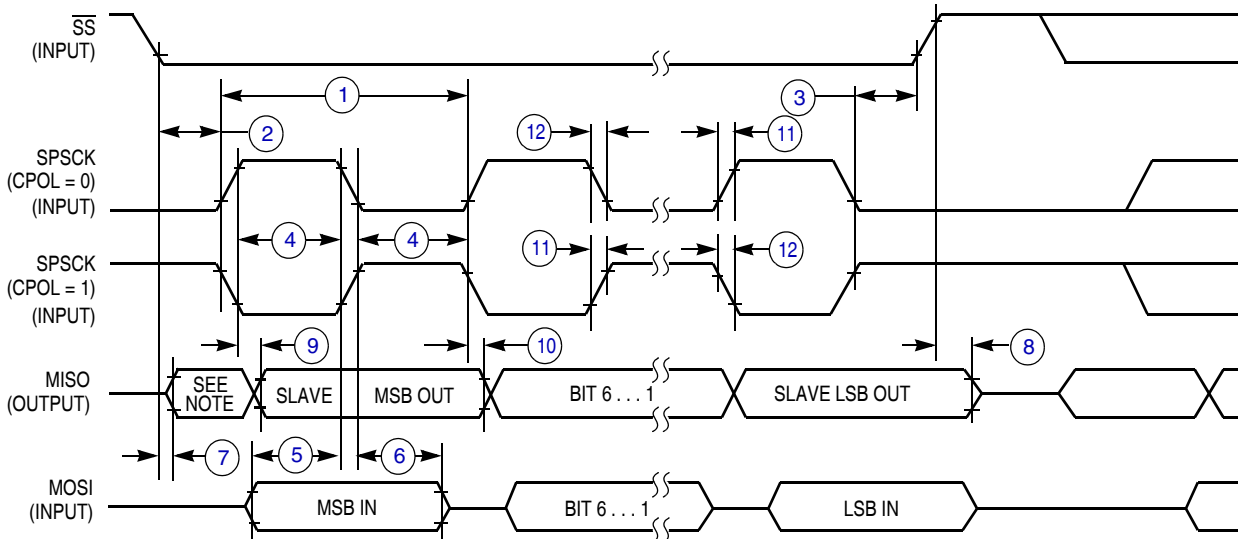
Figure 22. SPI Master Timing (CPHA = 1)



NOTE:

1. Not defined but normally MSB of character just received

Figure 23. SPI Slave Timing (CPHA = 0)



NOTE:

1. Not defined but normally LSB of character just received

Figure 24. SPI Slave Timing (CPHA = 1)

5.10 Analog Comparator (ACMP) Electricals

Table 13. Analog Comparator Electrical Specifications

| C | Characteristic | Symbol | Min | Typical | Max | Unit |
|---|-------------------------|------------|-----|---------|-----|---------|
| D | Supply voltage | V_{DD} | 2.7 | — | 5.5 | V |
| P | Supply current (active) | I_{DDAC} | — | 20 | 35 | μA |

Table 13. Analog Comparator Electrical Specifications (continued)

| C | Characteristic | Symbol | Min | Typical | Max | Unit |
|---|--|-------------|----------------|---------|----------|---------|
| D | Analog input voltage | V_{AIN} | $V_{SS} - 0.3$ | — | V_{DD} | V |
| P | Analog input offset voltage | V_{AIO} | — | 20 | 40 | mV |
| C | Analog comparator hysteresis | V_H | 3.0 | 9.0 | 15.0 | mV |
| P | Analog input leakage current | I_{ALKG} | — | — | 1.0 | μA |
| C | Analog comparator initialization delay | t_{AINIT} | — | — | 1.0 | μs |

5.11 ADC Characteristics

Table 14. 10-Bit ADC Operating Conditions

| Characteristic | Conditions | Symb | Min | Typ ¹ | Max | Unit | Comment |
|--------------------------------|---|------------|------------|------------------|------------|------------|-----------------|
| Supply voltage | Absolute | V_{DDA} | 2.7 | — | 5.5 | V | |
| Input voltage | | V_{ADIN} | V_{REFL} | — | V_{REFH} | V | |
| Input capacitance | | C_{ADIN} | — | 4.5 | 5.5 | pF | |
| Input resistance | | R_{ADIN} | — | 3 | 5 | k Ω | |
| Analog source resistance | 10-bit mode $f_{ADCK} > 4\text{MHz}$ $f_{ADCK} < 4\text{MHz}$ | R_{AS} | — | — | 5 | k Ω | External to MCU |
| | 8-bit mode (all valid f_{ADCK}) | | — | — | 10 | | |
| ADC conversion clock frequency | High speed (ADLPC = 0) | f_{ADCK} | 0.4 | — | 8.0 | MHz | |
| | Low power (ADLPC = 1) | | 0.4 | — | 4.0 | | |

¹ Typical values assume $V_{DDA} = 5.0\text{ V}$, Temp = 25 °C, $f_{ADCK} = 1.0\text{ MHz}$ unless otherwise stated. Typical values are for reference only and are not tested in production.

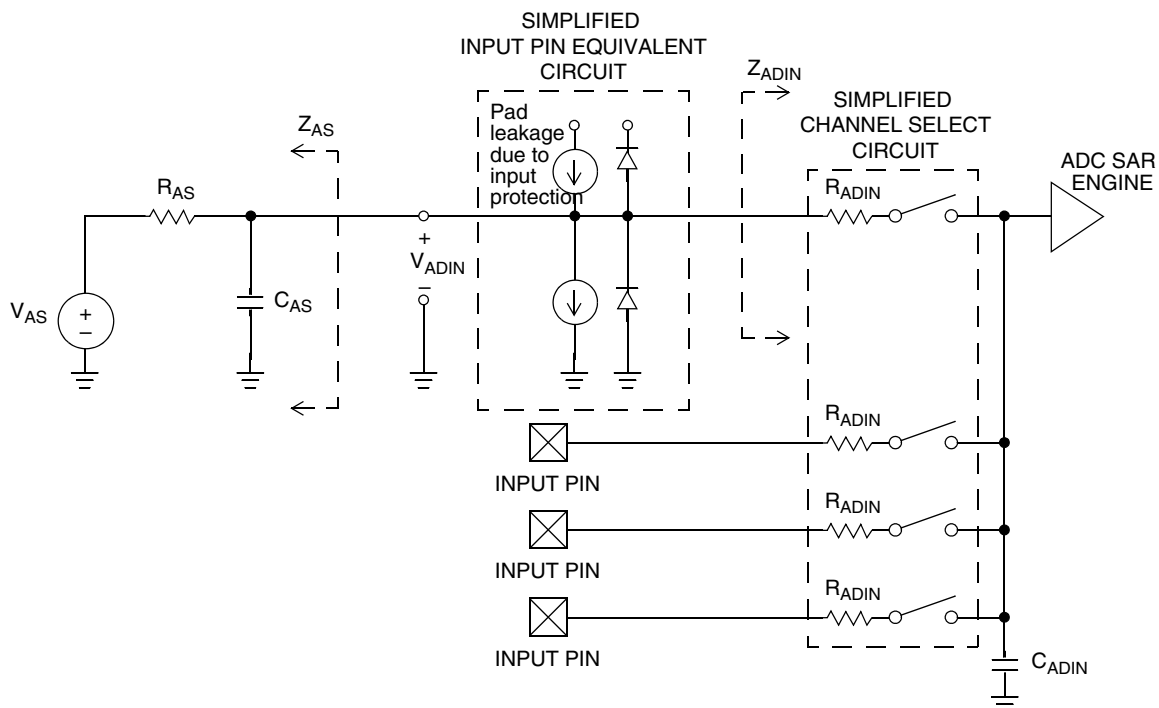


Figure 25. ADC Input Impedance Equivalency Diagram

 Table 15. 10-Bit ADC Characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$)

| C | Characteristic | Conditions | Symb | Min | Typ ¹ | Max | Unit | Comment |
|---|---|------------------------|-------------|------|------------------|-----|---------------|---------------------------|
| T | Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1 | | I_{DDA} | — | 133 | — | μA | |
| T | Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1 | | I_{DDA} | — | 218 | — | μA | |
| T | Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1 | | I_{DDA} | — | 327 | — | μA | |
| P | Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1 | | I_{DDA} | — | 0.582 | 1 | mA | |
| P | ADC asynchronous clock source | High speed (ADLPC = 0) | f_{ADACK} | 2 | 3.3 | 5 | MHz | $t_{ADACK} = 1/f_{ADACK}$ |
| | | Low power (ADLPC = 1) | | 1.25 | 2 | 3.3 | | |

Table 15. 10-Bit ADC Characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

| C | Characteristic | Conditions | Symb | Min | Typ ¹ | Max | Unit | Comment |
|---|---|---------------------------|--------------|-----|------------------|------|------------------|--|
| P | Conversion time (including sample time) | Short sample (ADLSMP = 0) | t_{ADC} | — | 20 | — | ADCK cycles | See reference manual for conversion time variances |
| | | Long sample (ADLSMP = 1) | | — | 40 | — | | |
| P | Sample time | Short sample (ADLSMP = 0) | t_{ADS} | — | 3.5 | — | ADCK cycles | |
| | | Long sample (ADLSMP = 1) | | — | 23.5 | — | | |
| D | Temp sensor slope | –40 °C– 25 °C | m | — | 3.266 | — | mV/°C | |
| | | 25 °C– 85 °C | | — | 3.638 | — | | |
| D | Temp sensor voltage | 25 °C | V_{TEMP25} | — | 1.396 | — | mV | |
| P | Total unadjusted error | 10-bit mode | E_{TUE} | — | ±1.5 | ±3.5 | LSB ² | Includes quantization |
| P | | 8-bit mode | | — | ±0.7 | ±1.5 | | |
| P | Differential non-linearity | 10-bit mode ³ | DNL | — | ±0.5 | ±1.0 | LSB ² | |
| P | | 8-bit mode ³ | | — | ±0.3 | ±0.5 | | |
| T | Integral non-linearity | 10-bit mode | INL | — | ±0.5 | ±1.0 | LSB ² | |
| T | | 8-bit mode | | — | ±0.3 | ±0.5 | | |
| P | Zero-scale error | 10-bit mode | E_{ZS} | — | ±1.5 | ±2.1 | LSB ² | $V_{ADIN} = V_{SSA}$ |
| P | | 8-bit mode | | — | ±0.5 | ±0.7 | | |
| T | Full-scale error | 10-bit mode | E_{FS} | — | ±1 | ±1.5 | LSB ² | $V_{ADIN} = V_{DDA}$ |
| T | | 8-bit mode | | — | ±0.5 | ±0.5 | | |
| D | Quantization error | 10-bit mode | E_Q | — | — | ±0.5 | LSB ² | |
| | | 8-bit mode | | — | — | ±0.5 | | |
| D | Input leakage error | 10-bit mode | E_{IL} | — | ±0.2 | ±2.5 | LSB ² | Pad leakage ^{4*} R_{AS} |
| | | 8-bit mode | | — | ±0.1 | ±1 | | |

¹ Typical values assume $V_{DDA} = 5.0$ V, Temp = 25 °C, $f_{ADCK} = 1.0$ MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

² 1 LSB = $(V_{REFH} - V_{REFL})/2^N$

³ Monotonicity and No-Missing-Codes guaranteed in 10-bit and 8-bit modes

⁴ Based on input pad leakage current. Refer to pad electricals.

5.12 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the flash memory.

Program and erase operations do not require any special power sources other than the normal V_{DD} supply. For more detailed information about program/erase operations, see the Memory section.

Table 16. Flash Characteristics

| C | Characteristic | Symbol | Min | Typical | Max | Unit |
|---|---|-------------------------|--------|--------------|--------|-------------------|
| D | Supply voltage for program/erase –40 °C to 85 °C | $V_{\text{prog/erase}}$ | 2.7 | — | 5.5 | V |
| D | Supply voltage for read operation | V_{Read} | 2.7 | — | 5.5 | V |
| D | Internal FCLK frequency ¹ | f_{FCLK} | 150 | — | 200 | kHz |
| D | Internal FCLK period (1/FCLK) | t_{FcyC} | 5 | — | 6.67 | μs |
| P | Byte program time (random location) ² | t_{prog} | 9 | | | t_{FcyC} |
| P | Byte program time (burst mode) ² | t_{Burst} | 4 | | | t_{FcyC} |
| P | Page erase time ² | t_{Page} | 4000 | | | t_{FcyC} |
| P | Mass erase time ² | t_{Mass} | 20,000 | | | t_{FcyC} |
| C | Byte program current ³ | RI_{DDBP} | — | 4 | — | mA |
| C | Page erase current ³ | RI_{DDPE} | — | 6 | — | mA |
| C | Program/erase endurance ⁴ T_L to T_H = –40 °C to 85 °C $T = 25$ °C | | 10,000 | — 100,000 | — — | cycles |
| C | Data retention ⁵ | $t_{\text{D_ret}}$ | 15 | 100 | — | years |

¹ The frequency of this clock is controlled by a software setting.

² These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.

³ The program and erase currents are additional to the standard run I_{DD} . These values are measured at room temperatures with $V_{\text{DD}} = 5.0$ V, bus frequency = 4.0 MHz.

⁴ **Typical endurance for flash** was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, *Typical Endurance for Nonvolatile Memory*.

⁵ **Typical data retention** values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25 °C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618, *Typical Data Retention for Nonvolatile Memory*.

5.13 EMC Performance

Electromagnetic compatibility (EMC) performance is highly dependant on the environment in which the MCU resides. Board design and layout, circuit topology choices, location and characteristics of external components as well as MCU software operation all play a significant role in EMC performance. The system designer should consult Freescale applications notes such as AN2321, AN1050, AN1263, AN2764, and AN1259 for advice and guidance specifically targeted at optimizing EMC performance.

5.13.1 Radiated Emissions

Microcontroller radiated RF emissions are measured from 150 kHz to 1 GHz using the TEM/GTEM Cell method in accordance with the IEC 61967-2 and SAE J1752/3 standards. The measurement is performed with the microcontroller installed on a custom EMC evaluation board while running specialized EMC test software. The radiated emissions from the microcontroller are measured in a TEM cell in two package orientations (the North and East).

Ordering Information

The maximum radiated RF emissions of the tested configuration in all orientations are less than or equal to the reported emissions levels.

Table 17. Radiated Emissions, Electric Field

| Parameter | Symbol | Conditions | Frequency | f_{osc}/f_{BUS} | Level ¹ (Max) | Unit | |
|------------------------------------|---------------|--|----------------|-----------------------------|--------------------------|------------|---|
| Radiated emissions, electric field | V_{RE_TEM} | $V_{DD} = 5.0\text{ V}$ $T_A = 25\text{ °C}$ package type 32-pin LQFP | 0.15 – 50 MHz | 4 MHz crystal 19 MHz bus | 9 | dB μ V | |
| | | | 50 – 150 MHz | | 5 | | |
| | | | 150 – 500 MHz | | 2 | | |
| | | | 500 – 1000 MHz | | 1 | | |
| | | | IEC Level | | N | | — |
| | | | SAE Level | | 1 | | — |

¹ Data based on qualification test results.

6 Ordering Information

This section contains ordering information for MC9S08SV16 series devices. See below for an example of the device numbering system.

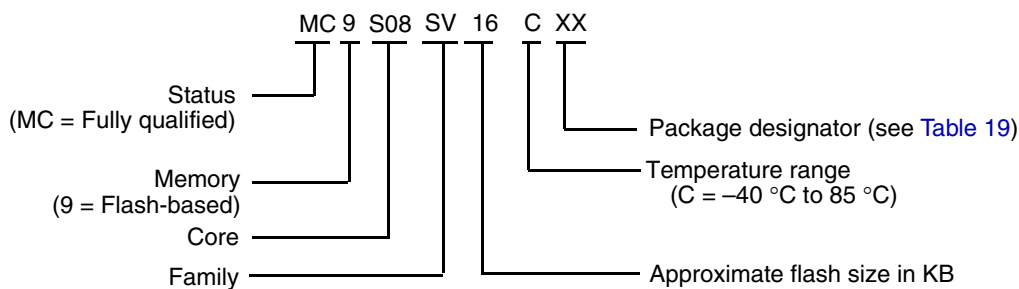
Table 18. Device Numbering System

| Device Number ¹ | Memory | | Available Packages ² |
|----------------------------|--------|-----------|---------------------------------|
| | FLASH | RAM | |
| MC9S08SV16 | 16 KB | 1024 Byte | 32-pin SDIP |
| MC9S08SV8 | 8 KB | 768 Byte | 32-pin LQFP |

¹ See the reference manual, *MC9S08SV16 Series Reference Manual*, for a complete description of modules included on each device.

² See [Table 19](#) for package information.

Example of the device numbering system:



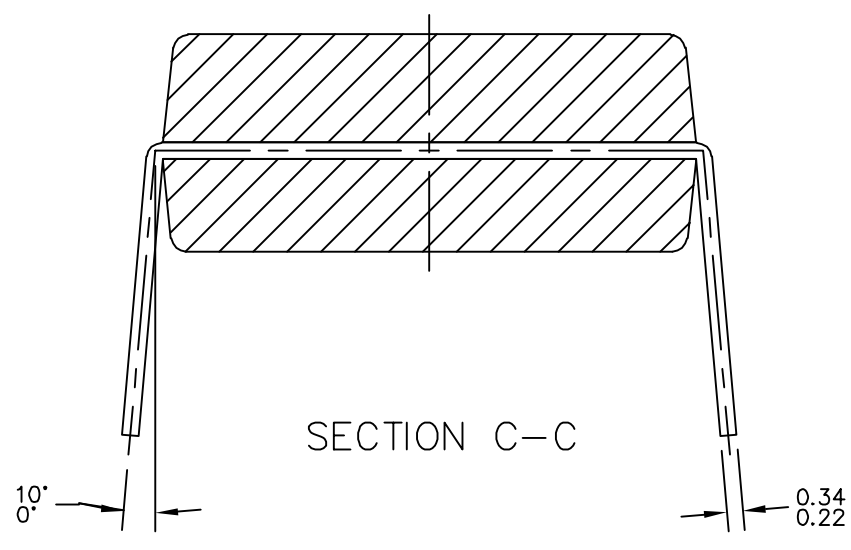
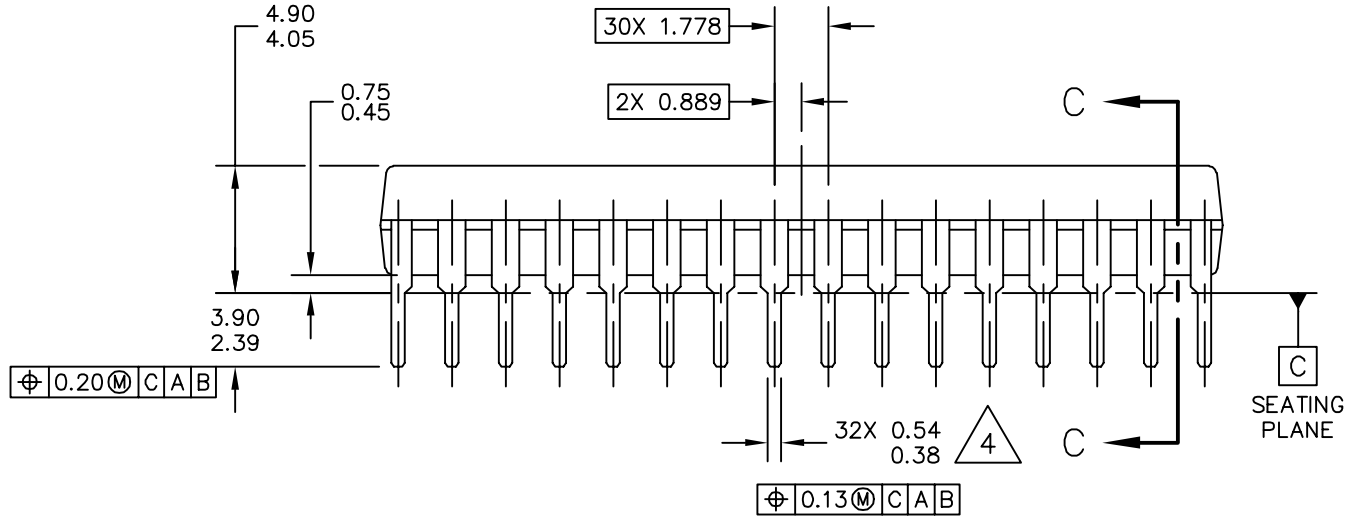
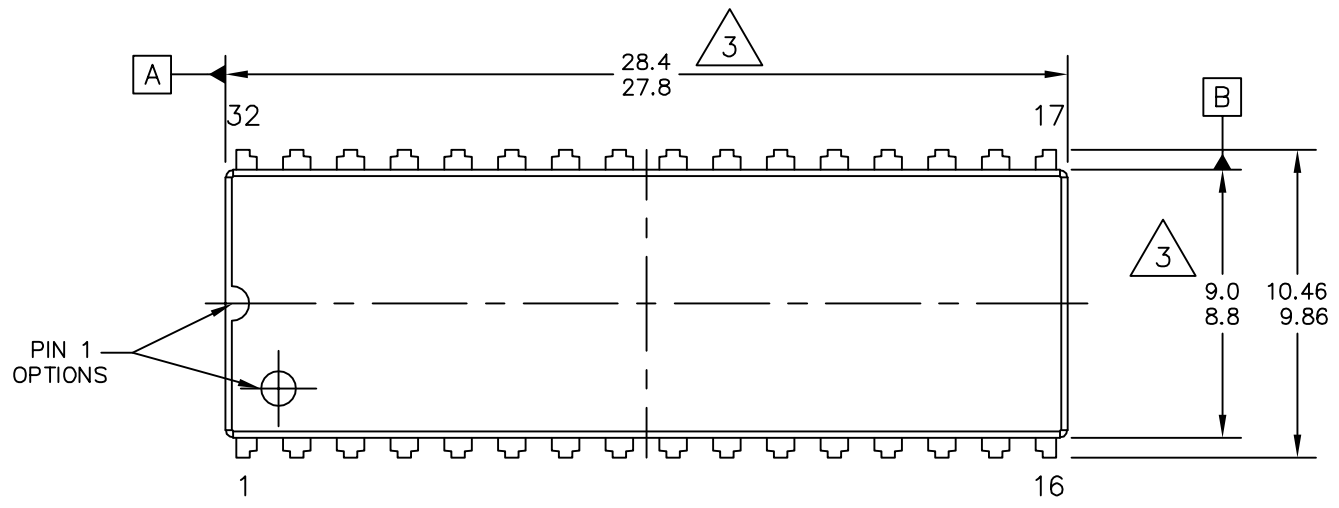
7 Package Information

Table 19. Package Descriptions

| Pin Count | Package Type | Abbreviation | Designator | Case No. | Document No. |
|-----------|-----------------------------|--------------|------------|----------|--------------|
| 32 | Low Quad Flat Package | LQFP | LC | 873A-03 | 98ASH70029A |
| 32 | Shrink Dual In-line Package | SDIP | BM | 1376-02 | 98ASA99330D |

7.1 Mechanical Drawings

The following pages are mechanical drawings for the packages described in [Table 19](#).



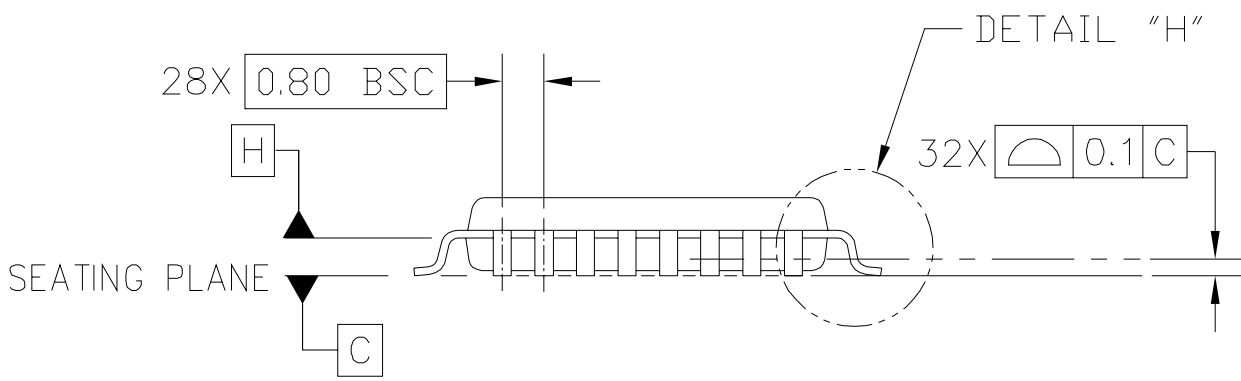
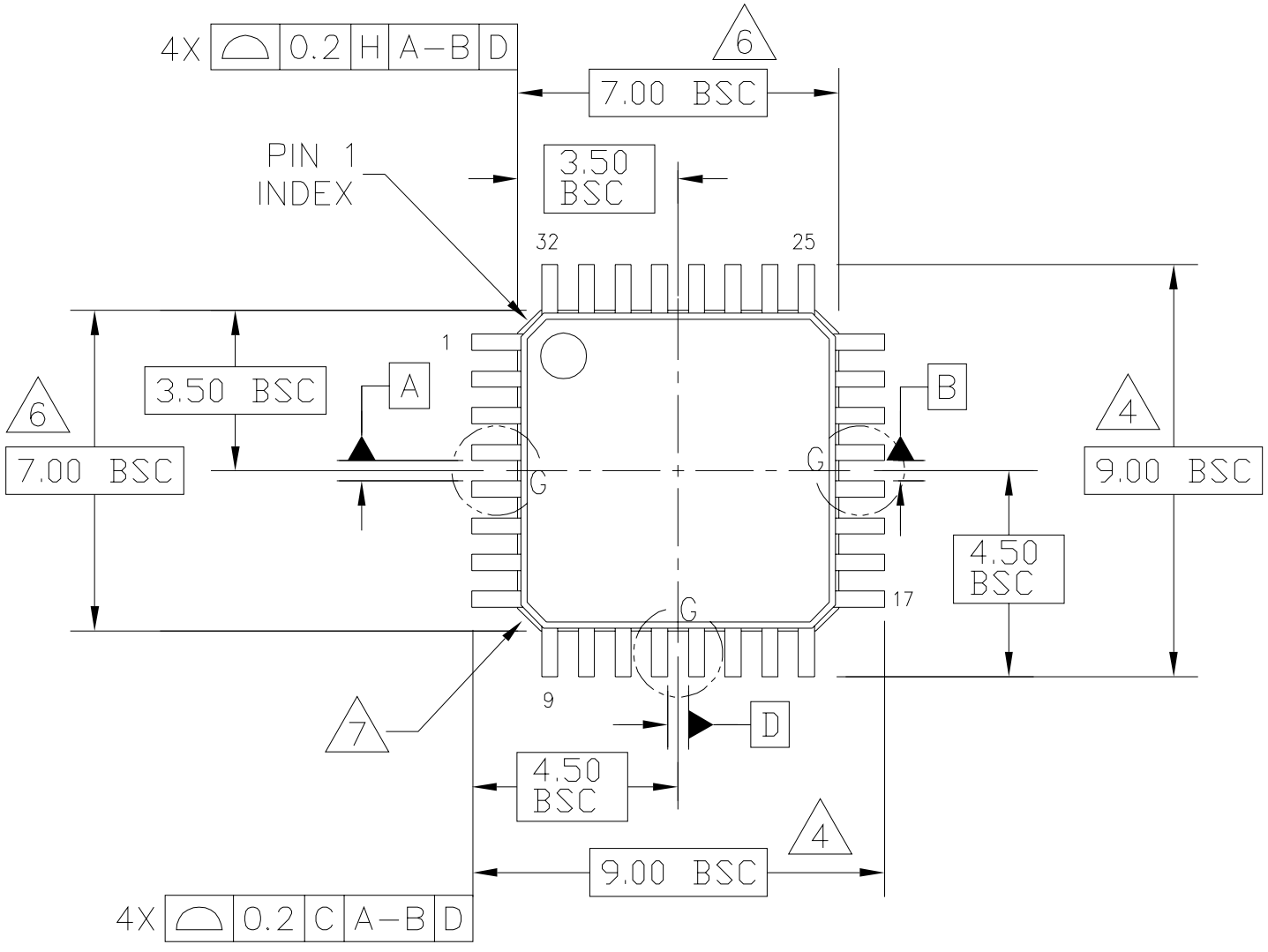
| | | | |
|---|---------------------------|----------------------------|-------------|
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| TITLE: 32 LEAD PDIP | DOCUMENT NO: 98ASA99330D | | REV: A |
| | CASE NUMBER: 1376-02 | | 25 APR 2005 |
| | STANDARD: NON-JEDEC | | |



NOTES:

1. ALL DIMENSION ARE IN MILLIMETERS.
2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5-1994.
3. DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS.
4. DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION.

| | | | |
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| | | | |
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| © FREESCALE SEMICONDUCTOR, INC. ALL RIGHTS RESERVED. | MECHANICAL OUTLINE | PRINT VERSION NOT TO SCALE | |
| TITLE: LOW PROFILE QUAD FLAT PACK (LQFP) 32 LEAD, 0.8 PITCH (7 X 7 X 1.4) | DOCUMENT NO: 98ASH70029A | REV: D | |
| | CASE NUMBER: 873A-03 | 19 MAY 2005 | |
| | STANDARD: JEDEC MS-026 BBA | | |



NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.

2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5-1994.

3. DATUMS A, B, AND D TO BE DETERMINED AT DATUM PLANE H.

4. DIMENSIONS TO BE DETERMINED AT SEATING PLANE DATUM C.

5. DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL NOT CAUSE THE LEAD WIDTH TO EXCEED THE MAXIMUM DIMENSION BY MORE THAN 0.08 MM. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSION AND ADJACENT LEAD OR PROTRUSION: 0.07 MM.

6. DIMENSIONS DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE PROTRUSION IS 0.25 MM PER SIDE. DIMENSIONS ARE MAXIMUM PLASTIC BODY SIZE DIMENSIONS INCLUDING MOLD MISMATCH.

7. EXACT SHAPE OF EACH CORNER IS OPTIONAL.

8. THESE DIMENSIONS APPLY TO THE FLAT SECTION OF THE LEAD BETWEEN 0.1 MM AND 0.25 MM FROM THE LEAD TIP.

| | | | |
|---|----------------------------|----------------------------|--|
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| TITLE: LOW PROFILE QUAD FLAT PACK (LQFP) 32 LEAD, 0.8 PITCH (7 X 7 X 1.4) | DOCUMENT NO: 98ASH70029A | REV: D | |
| | CASE NUMBER: 873A-03 | 19 MAY 2005 | |
| | STANDARD: JEDEC MS-026 BBA | | |

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