



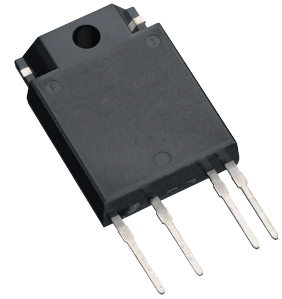
# THE DATASHEET OF S216SE2



# S216SE2 Series

\*Non-zero cross type is also available. (S216SE1 Series)

$I_T(\text{rms}) \leq 16\text{A}$ ,  
Reinforced Insulation Type  
Zero Cross type  
SIP 4pin  
Triac output SSR



## ■ Description

**S216SE2 Series** reinforced insulation type Solid State Relays (SSR) are an integration of an infrared emitting diode (IRED), a Phototriac Detector and a main output Triac. These devices are ideally suited for controlling high voltage AC loads with solid state reliability while providing 3.0kV isolation ( $V_{\text{iso}}(\text{rms})$ ) from input to output.

## ■ Features

1. Output current,  $I_T(\text{rms}) \leq 16.0\text{A}$
2. Zero crossing functionary ( $V_{\text{OX}}$  : MAX. 35V)
3. 4 pin SIP package
4. High repetitive peak off-state voltage ( $V_{\text{DRM}}$  : 600V)
5. Reinforced insulation type (MIN. 0.4mm internal separation)
6. High isolation voltage between input and output ( $V_{\text{iso}}(\text{rms})$  : 3.0kV)
7. Lead-free terminal components are also available (see Model Line-up section in this datasheet)
8. Screw hole for heat sink

## ■ Agency approvals/Compliance

1. Approved by TÜV EN60950 (reinforced insulation), file No. R9051479 (as models No. **S216SE2**)
2. Package resin : UL flammability grade (94V-0)

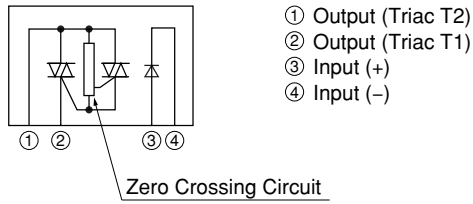
## ■ Applications

1. Isolated interface between high voltage AC devices and lower voltage DC control circuitry.
2. Switching motors, fans, heaters, solenoids, and valves.
3. Power control in applications such as lighting and temperature control equipment.

Notice The content of data sheet is subject to change without prior notice.

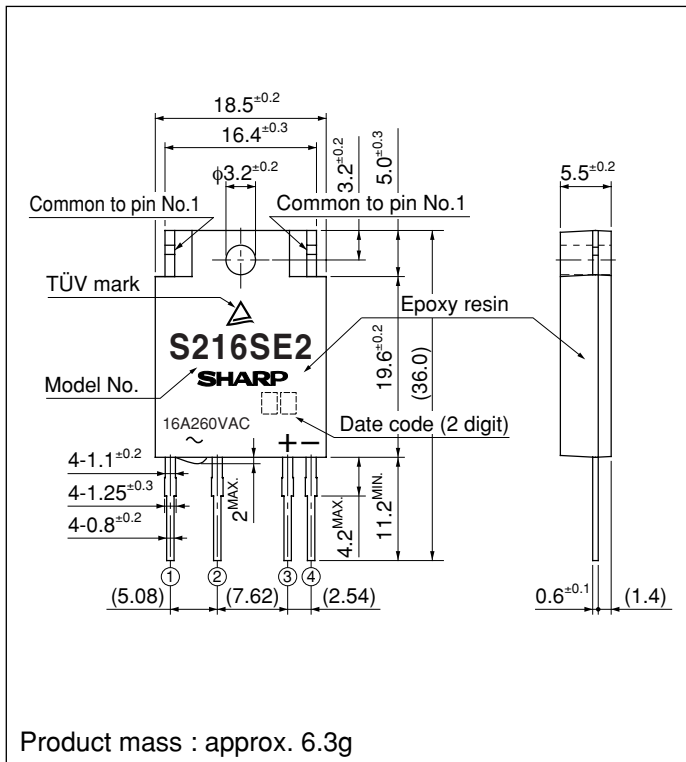
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### Internal Connection Diagram



### Outline Dimensions

(Unit : mm)



( ) : Typical dimensions

Date code (2 digit)

1st digit				2nd digit	
Year of production				Month of production	
A.D.	Mark	A.D	Mark	Month	Mark
1990	A	2002	P	January	1
1991	B	2003	R	February	2
1992	C	2004	S	March	3
1993	D	2005	T	April	4
1994	E	2006	U	May	5
1995	F	2007	V	June	6
1996	H	2008	W	July	7
1997	J	2009	X	August	8
1998	K	2010	A	September	9
1999	L	2011	B	October	O
2000	M	2012	C	November	N
2001	N	∴	∴	December	D

repeats in a 20 year cycle

Country of origin

Japan

Rank mark

There is no rank mark indicator and currently there are no rank offered for this device.

### ■ Absolute Maximum Ratings

(T<sub>a</sub>=25°C)

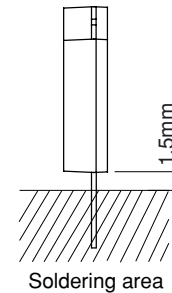
Parameter		Symbol	Rating	Unit
Input	Forward current	I <sub>F</sub>	50 <sup>*3</sup>	mA
	Reverse voltage	V <sub>R</sub>	6	V
Output	RMS ON-state current	I <sub>T(rms)</sub>	16 <sup>*3</sup>	A
	Peak one cycle surge current	I <sub>surge</sub>	160 <sup>*4</sup>	A
	Repetitive peak OFF-state voltage	V <sub>DRM</sub>	600	V
	Non-Repetitive peak OFF-state voltage	V <sub>DSM</sub>	600	V
	Critical rate of rise of ON-state current	dI <sub>T</sub> /dt	50	A/μs
	Operating frequency	f	45 to 65	Hz
*1 Isolation voltage		V <sub>iso(rms)</sub>	3.0	kV
Operating temperature		T <sub>opr</sub>	-25 to +100	°C
Storage temperature		T <sub>stg</sub>	-30 to +125	°C
*2 Soldering temperature		T <sub>sol</sub>	260	°C

\*1 40 to 60%RH, AC for 1minute, f=60Hz

\*2 For 10s

\*3 Refer to Fig.1, Fig.2

\*4 f=60Hz sine wave, T<sub>j</sub>=25°C start



### ■ Electro-optical Characteristics

(T<sub>a</sub>=25°C)

Parameter		Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Input	Forward voltage	V <sub>F</sub>	I <sub>F</sub> =20mA	-	1.2	1.4	V
	Reverse current	I <sub>R</sub>	V <sub>R</sub> =3V	-	-	100	μA
Output	Repetitive peak OFF-stage current	I <sub>DRM</sub>	V <sub>D</sub> =V <sub>DRM</sub>	-	-	100	μA
	ON-state voltage	V <sub>T(rms)</sub>	I <sub>T(rms)</sub> =16A, Resistance load, I <sub>F</sub> =20mA	-	-	1.5	V
	Holding current	I <sub>H</sub>	-	-	-	50	mA
	Critical rate of rise of OFF-state voltage	dV/dt	V <sub>D</sub> =2/3•V <sub>DRM</sub>	30	-	-	V/μs
	Critical rate of rise of OFF-state voltage at commutation	(dV/dt) <sub>c</sub>	T <sub>j</sub> =125°C, V <sub>D</sub> =2/3•V <sub>DRM</sub> , dI <sub>T</sub> /dt=-8.0A/ms	5	-	-	V/μs
Transfer characteristics	Minimum trigger current	I <sub>FT</sub>	V <sub>D</sub> =6V, R <sub>L</sub> =30Ω	-	-	8	mA
	Zero cross voltage	V <sub>OX</sub>	I <sub>F</sub> =8mA	-	-	35	V
	Isolation resistance	R <sub>ISO</sub>	DC500V, 40 to 60%RH	10 <sup>10</sup>	-	-	Ω
	Turn-on time	t <sub>on</sub>	V <sub>D(rms)</sub> =200V, AC60Hz	-	-	9.3	ms
	Turn-off time	t <sub>off</sub>	I <sub>T(rms)</sub> =2A, Resistance load, I <sub>F</sub> =20mA	-	-	9.3	ms
Thermal resistance		R <sub>th(j-c)</sub>	Between junction and case	-	3.3	-	°C/W
		R <sub>th(j-a)</sub>	Between junction and ambient	-	40	-	

### ■ Model Line-up (1) (Lead-free terminal components)

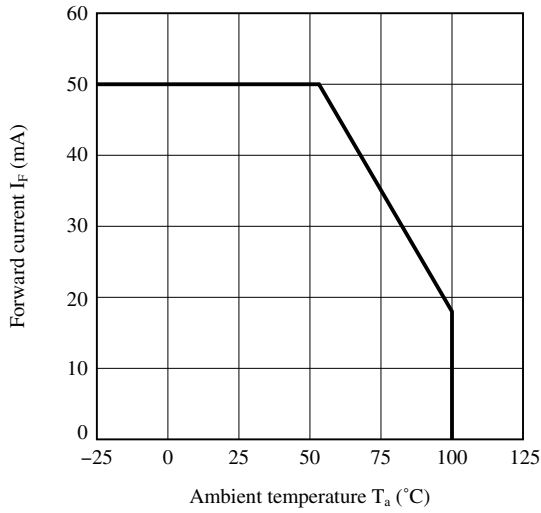
Shipping Package	Case		V <sub>DRM</sub> [V]	I <sub>FT</sub> [mA] (V <sub>D</sub> =6V, R <sub>L</sub> =30Ω)
	200pcs/case			
EN60950 (reinforced insulation)	_____	Approved	600	MAX.8
Model No.	_____	<b>S216SE2F</b>		

### ■ Model Line-up (2) (Lead solder plating components)

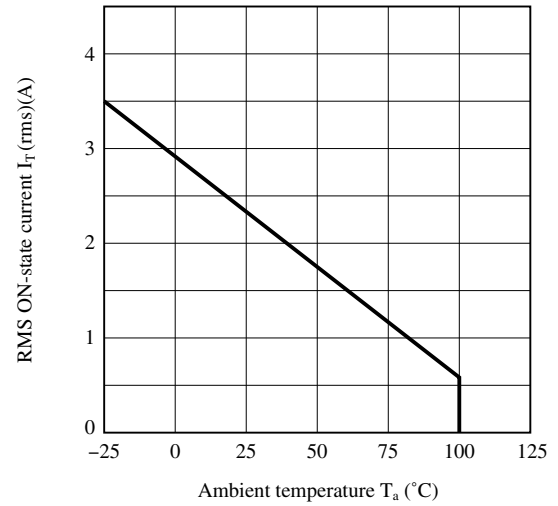
Shipping Package	Case		V <sub>DRM</sub> [V]	I <sub>FT</sub> [mA] (V <sub>D</sub> =6V, R <sub>L</sub> =30Ω)
	200pcs/case			
EN60950 (reinforced insulation)	_____	Approved	600	MAX.8
Model No.	_____	<b>S216SE2</b>		

Please contact a local SHARP sales representative to see the actual status of the production.

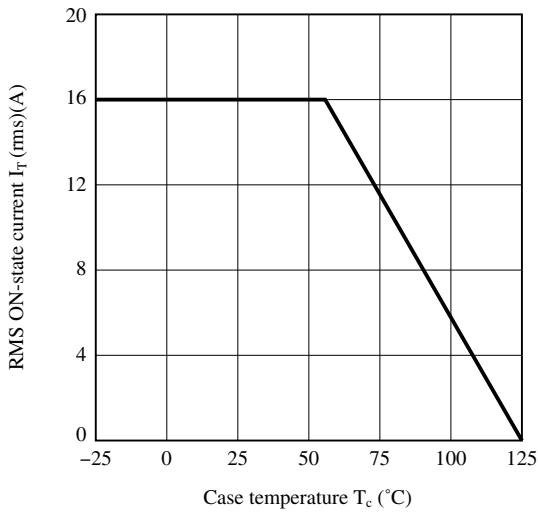
**Fig.1 Forward Current vs. Ambient Temperature**



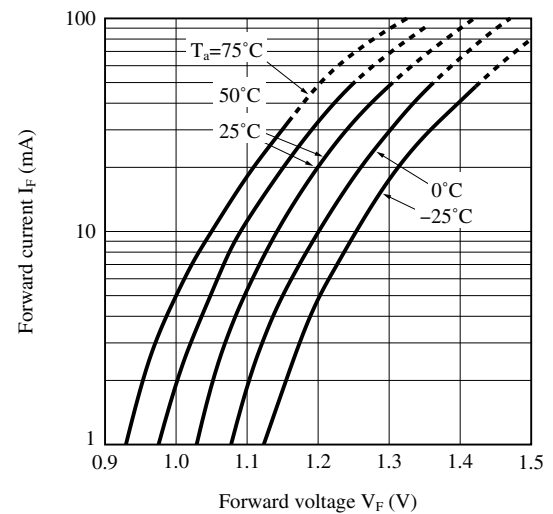
**Fig.2 RMS ON-state Current vs. Ambient Temperature**



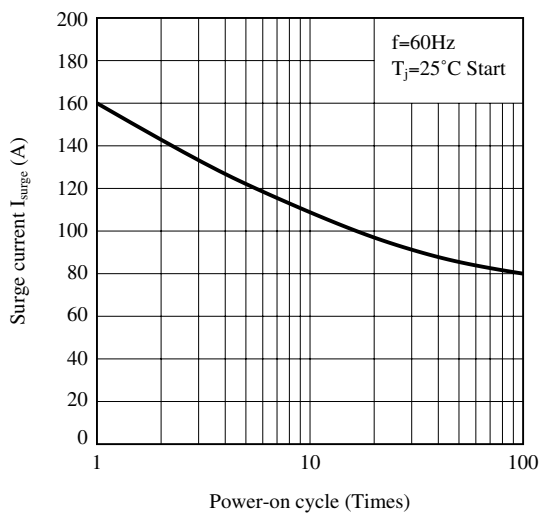
**Fig.3 RMS ON-state Current vs. Case Temperature**



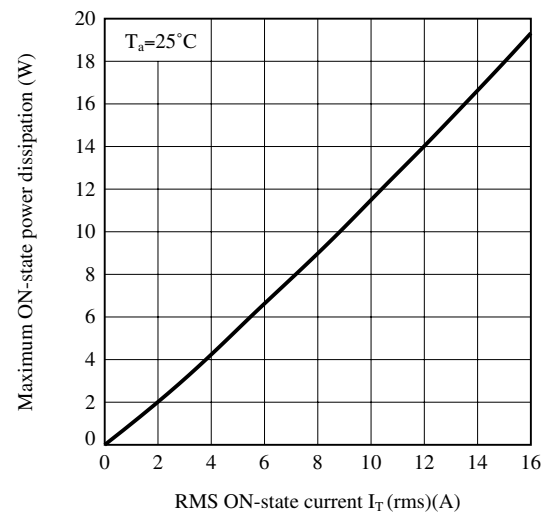
**Fig.4 Forward Current vs. Forward Voltage**



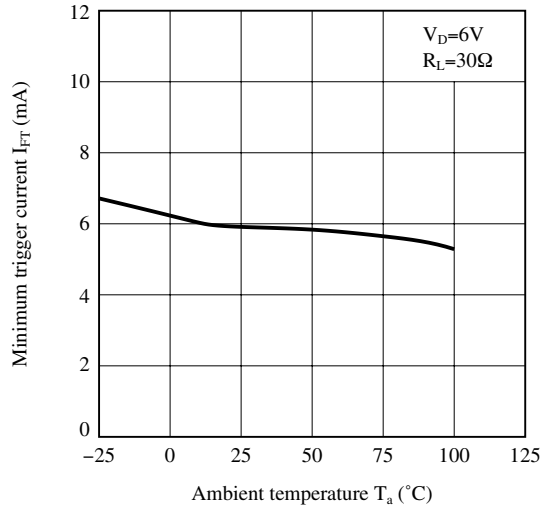
**Fig.5 Surge Current vs. Power-on Cycle**



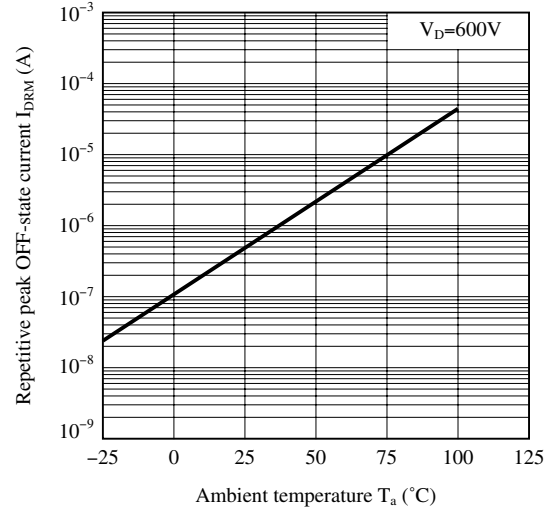
**Fig.6 Maximum ON-state Power Dissipation vs. RMS ON-state Current**



**Fig.7 Minimum Trigger Current vs. Ambient Temperature**



**Fig.8 Repetitive Peak OFF-state Current vs. Ambient Temperature**



Remarks : Please be aware that all data in the graph are just for reference.

## ■ Design Considerations

### ● Recommended Operating Conditions

Parameter		Symbol	Conditions	MIN.	MAX.	Unit
Input	Input signal current at ON state	$I_F(\text{ON})$	–	16	24	mA
	Input signal current at OFF state	$I_F(\text{OFF})$	–	0	0.1	mA
Output	Load supply voltage	$V_{\text{OUT}}(\text{rms})$	–	80	240	V
	Load supply current	$I_{\text{OUT}}(\text{rms})$	Locate snubber circuit between output terminals ( $C_s=0.1\mu\text{F}$ , $R_s=47\Omega$ )	0.1	$I_T(\text{rms})$ $\times 80\%$ (*)	mA
	Frequency	f	–	47	63	Hz
Operating temperature		$T_{\text{opr}}$	–	–20	80	°C

(\*) See Fig.2 about derating curve ( $I_T(\text{rms})$  vs. ambient temperature).

### ● Design guide

In order for the SSR to turn off, the triggering current ( $I_F$ ) must be 0.1mA or less.

When the input current ( $I_F$ ) is below 0.1mA, the output Triac will be in the open circuit mode. However, if the voltage across the Triac,  $V_D$ , increases faster than rated  $dV/dt$ , the Triac may turn on. To avoid this situation, please incorporate a snubber circuit. Due to the many different types of load that can be driven, we can merely recommend some circuit values to start with :  $C_s=0.1\mu\text{F}$  and  $R_s=47\Omega$ . The operation of the SSR and snubber circuit should be tested and if unintentional switching occurs, please adjust the snubber circuit component values accordingly.

When making the transition from On to Off state, a snubber circuit should be used ensure that sudden drops in current are not accompanied by large instantaneous changes in voltage across the Triac. This fast change in voltage is brought about by the phase difference between current and voltage. Primarily, this is experienced in driving loads which are inductive such as motors and solenoids. Following the procedure outlined above should provide sufficient results.

For over voltage protection, a Varistor may be used.

Any snubber or Varistor used for the above mentioned scenarios should be located as close to the main output triac as possible.

Particular attention needs to be paid when utilizing SSRs that incorporate zero crossing circuitry. If the phase difference between the voltage and the current at the output pins is large enough, zero crossing type SSRs cannot be used. The result, if zero crossing SSRs are used under this condition, is that the SSR may not turn on and off irregardless of the input current. In this case, only a non zero cross type SSR should be used in combination with the above mentioned snubber circuit selection process.

The load current should be within the bounds of derating curve. (Refer to Fig.2)  
Also, please use the optional heat sink when necessary.

In case the optional heat sink is used and the isolation voltage between the device and the optional heat sink is needed, please locate the insulation sheet between the device and the heat sink.

When the optional heat sink is equipped, please set up the M3 screw-fastening torque at 0.3 to 0.5N·m.  
In order to dissipate the heat generated from the inside of device effectively, please follow the below suggestions.

- (a) Make sure there are no warps or bumps on the heat sink, insulation sheet and device surface.
- (b) Make sure there are no metal dusts or burrs attached onto the heat sink, insulation sheet and device surface.
- (c) Make sure silicone grease is evenly spread out on the heat sink, insulation sheet and device surface.

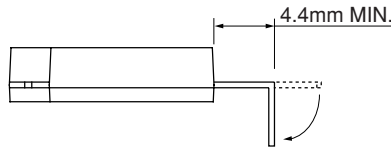
Silicone grease to be used is as follows;

- 1) There is no aged deterioration within the operating temperature ranges.
- 2) Base oil of grease is hardly separated and is hardly permeated in the device.
- 3) Even if base oil is separated and permeated in the device, it should not degrade the function of a device.

Recommended grease : G-746 (Shin-Etsu Chemical Co., Ltd.)  
 : G-747 (Shin-Etsu Chemical Co., Ltd.)  
 : SC102 (Dow Corning Toray Silicone Co., Ltd.)

In case the optional heat sink is screwed up, please solder after screwed.

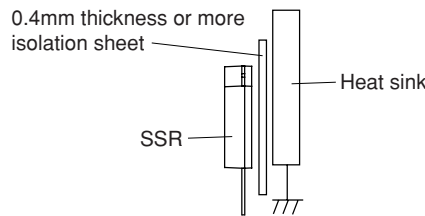
In case of the lead frame bending, please keep the following minimum distance and avoid any mechanical stress between the base of terminals and the molding resin.



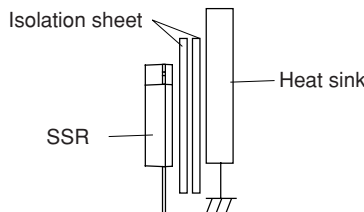
Some of AC electromagnetic counters or solenoids have built-in rectifier such as the diode. In this case, please use the device carefully since the load current waveform becomes similar with rectangular waveform and this results may not make a device turn off.

**Example how to equip optional heat sink for reinforced isolation**

- 1) Case of isolation sheet whose thickness is 0.4mm or more ( $V_{iso}$  : 3kV or more)



- 2) Case of the use of double isolation sheet ( $V_{iso}$  : each 3kV or more)



Please keep 5mm distance as minimum between naked metal portion of SSR and heat sink, and also between naked metal portion of SSR and bis/nut/washer. However, please avoid the natural rubber for isolation sheet.

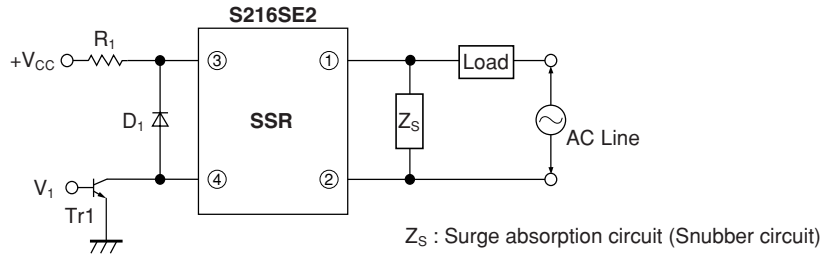
● **Degradation**

In general, the emission of the IRED used in SSR will degrade over time.

In the case where long term operation and / or constant extreme temperature fluctuations will be applied to the devices, please allow for a worst case scenario of 50% degradation over 5years.

Therefore in order to maintain proper operation, a design implementing these SSRs should provide at least twice the minimum required triggering current from initial operation.

● **Standard Circuit**



☆ For additional design assistance, please review our corresponding Optoelectronic Application Notes.

**■ Manufacturing Guidelines****● Soldering Method****Flow Soldering (No solder bathing)**

Flow soldering should be completed below 260°C and within 10s.

Preheating is within the bounds of 100 to 150°C and 30 to 80s.

Please solder within one time.

**Other notices**

Please test the soldering method in actual condition and make sure the soldering works fine, since the impact on the junction between the device and PCB varies depending on the tooling and soldering conditions.

**● Cleaning instructions****Solvent cleaning :**

Solvent temperature should be 45°C or below. Immersion time should be 3minutes or less.

**Ultrasonic cleaning :**

The impact on the device varies depending on the size of the cleaning bath, ultrasonic output, cleaning time, size of PCB and mounting method of the device.

Therefore, please make sure the device withstands the ultrasonic cleaning in actual conditions in advance of mass production.

**Recommended solvent materials :**

Ethyl alcohol, Methyl alcohol and Isopropyl alcohol.

In case the other type of solvent materials are intended to be used, please make sure they work fine in actual using conditions since some materials may erode the packaging resin.

**● Presence of ODC**

This product shall not contain the following materials.

And they are not used in the production process for this device.

Regulation substances : CFCs, Halon, Carbon tetrachloride, 1.1.1-Trichloroethane (Methylchloroform)

Specific brominated flame retardants such as the PBBOs and PBBs are not used in this product at all.

## ■ Package specification

### Package materials

- Packing case : Corrugated cardboard
- Partition : Corrugated cardboard
- Pad : Corrugated cardboard
- Cushioning material : Polyethylene
- Molt plane : Urethane

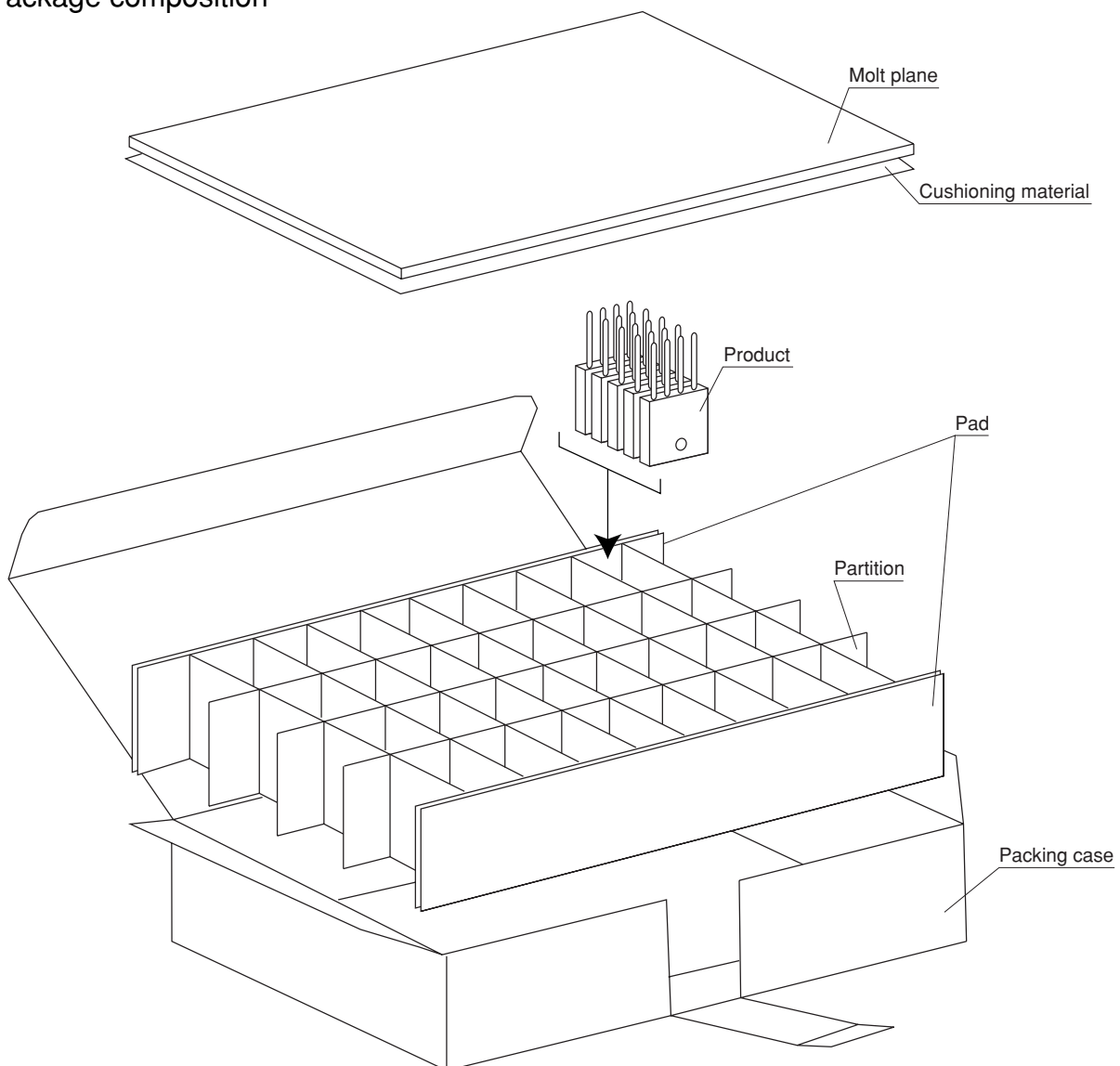
### Package method

The product should be located after the packing case is partitioned and protected inside by 4 pads.

Each partition should have 5 products with the lead upward.

Cushioning material and molt plane should be located after all products are settled (1 packing contains 200 pcs).

### Package composition



## ■ Important Notices

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(i) The devices in this publication are designed for use in general electronic equipment designs such as:

- Personal computers
- Office automation equipment
- Telecommunication equipment [terminal]
- Test and measurement equipment
- Industrial control
- Audio visual equipment
- Consumer electronics

(ii) Measures such as fail-safe function and redundant design should be taken to ensure reliability and safety when SHARP devices are used for or in connection

with equipment that requires higher reliability such as:

- Transportation control and safety equipment (i.e., aircraft, trains, automobiles, etc.)
- Traffic signals
- Gas leakage sensor breakers
- Alarm equipment
- Various safety devices, etc.

(iii) SHARP devices shall not be used for or in connection with equipment that requires an extremely high level of reliability and safety such as:

- Space applications
- Telecommunication equipment [trunk lines]
- Nuclear power control equipment
- Medical and other life support equipment (e.g., scuba).

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